

Impact of SLR tracking on GPS

Position Paper presented at the
ILRS Workshop on SLR tracking of
GNSS constellations

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Overview ■■■

- Current status
 - Satellite constellation
 - Retro-reflector, CoM offset
 - SLR network
- SLR data reduction
 - Bias corrections
- Analysis to date
 - Orbit validation results
 - SLR range residuals
- Summary of current status
- Potential benefits
- Future prospects
- Recommendations

Current SLR installation on GPS II constellation

- Retro-reflector arrays installed on two GPS satellites
 - GPS SVN 35 (PRN 05), Block IIA
 - launched August 1993
 - deactivated April 2009
 - GPS SVN 36 (PRN 06), Block IIA
 - launched March 1994
 - still in service

GPS retro-reflector planar array

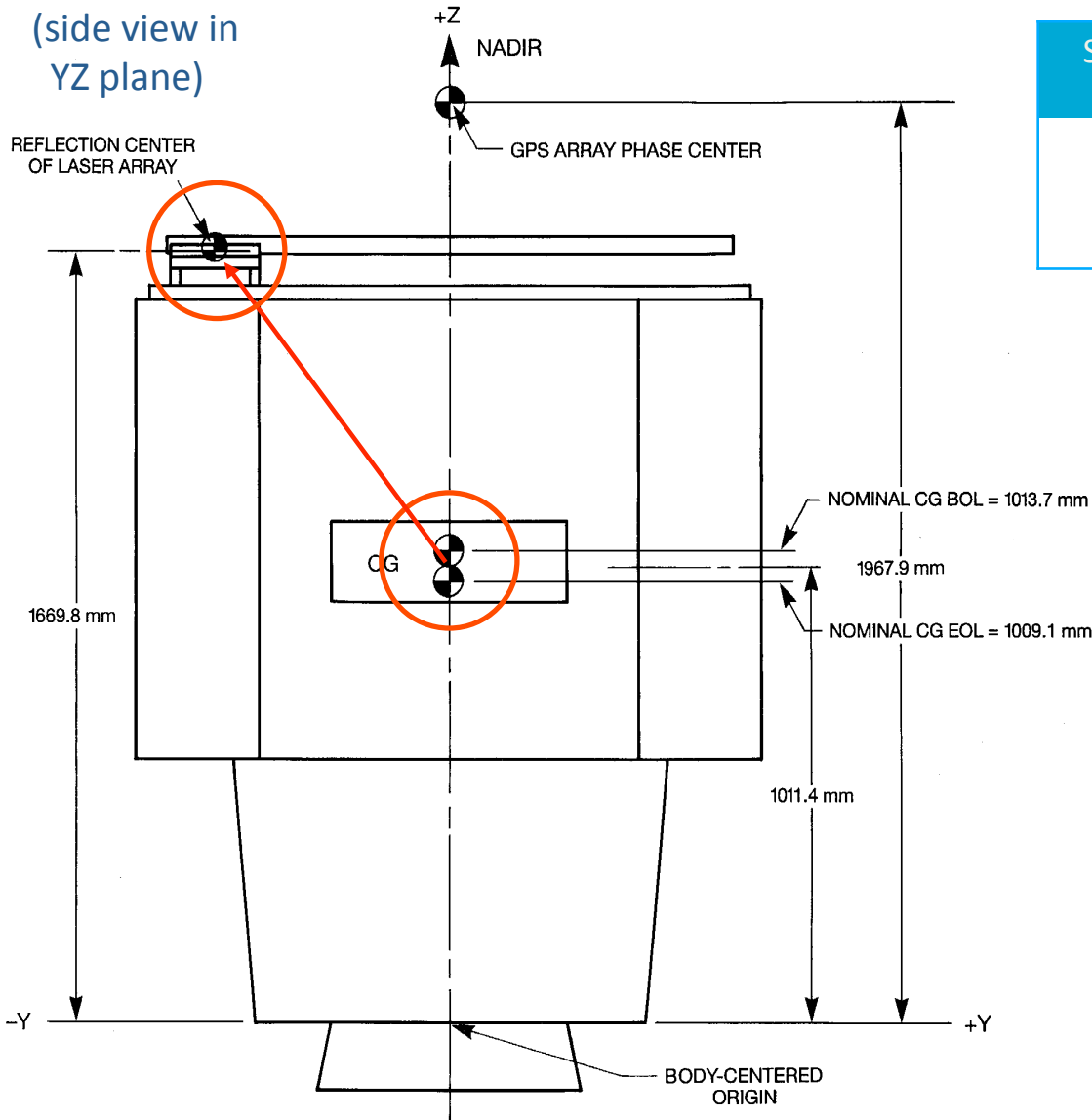
- Purpose: Test of POD
- Dimensions: 239 mm × 194 mm × 37 mm, mass 1.27 kg
- 32 fused-quartz corner cubes in alternating rows of four and five
- Built by the Russian Institute for Space Device Engineering
- Design similar to GLONASS satellites retro-reflectors, but total reflecting area smaller
- See *Degnan, J.J. and E.C. Pavlis [1994]*



http://ilrs.gsfc.nasa.gov/satellite_missions/list_of_satellites/gp35_reflector.html

Current status ■■■

GPS array CoM offsets



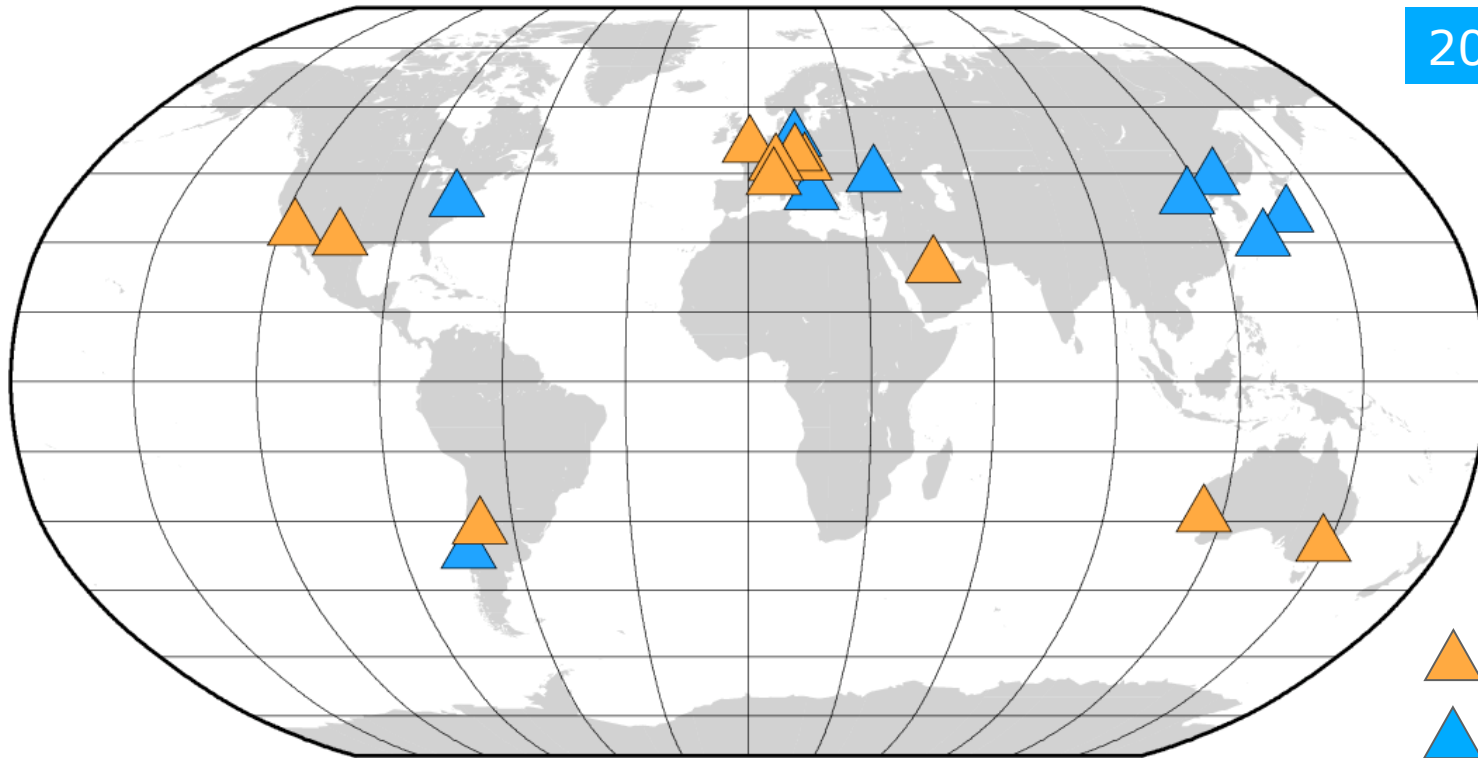
SVN	X offset (mm)	Y offset (mm)	Z offset (mm)
35	862.58	-524.51	669.5
36	862.58	-524.51	671.7

Davis and Trask [2007]

- CoM moves as fuel is expended
- CoM expected to move by **-4.6 mm** in Z direction over life of satellite
- Z difference of 2 mm reflects sat.-specific CoM of the SV (due to fuel)
- CoM accuracy is about **3 mm**
- Offsets last updated in 2006 (add'l adapter plate now accounted for)

Current status ■■■ SLR network for GPS tracking

2008.0 - 2009.5



▲ > 1000 obs.
▲ < 1000 obs.

- Only limited set of SLR stations (~20/56) capable of tracking high GPS satellites
- ILRS Tracking Schedule (Night tracking only)

SLR data reduction ■■■ Bias corrections (1/2)

- SLR observation bias corrections generally not applied by GPS analysts using SLR for validation or combination
- For “non-ILRS” analysts it is difficult to find out which biases should be applied in SLR data analysis

Information provided on the ILRS web page

- **Data correction Sinex file**, in principle very nice solution, easy to apply, **BUT**
 - last update 2003!
 - should include **R**ange, **T**ime, **P**ressure, and **S**tanford counter biases, but does not include **S**
 - in many cases for the biases **only the validity periods** are given, but no actual values
- **Stanford counter corrections** (separate table)
- **Range corrections for Herstmonceux** (separate table)

SLR observations were used so far for

- **Independent validation of GPS orbits** providing important information about
 - radial orbit accuracy
 - inter-system biases
 - orbit modeling problems
- **Combination studies:** GPS orbit estimation based on GPS and SLR observations (*Zhu et al. [2007]*, *Urschl et al. [2007]*)
 - until now no orbit improvement, due to limited amount and poor distribution of SLR data (temporal and geographical)
 - potential exists for GPS orbit improvement

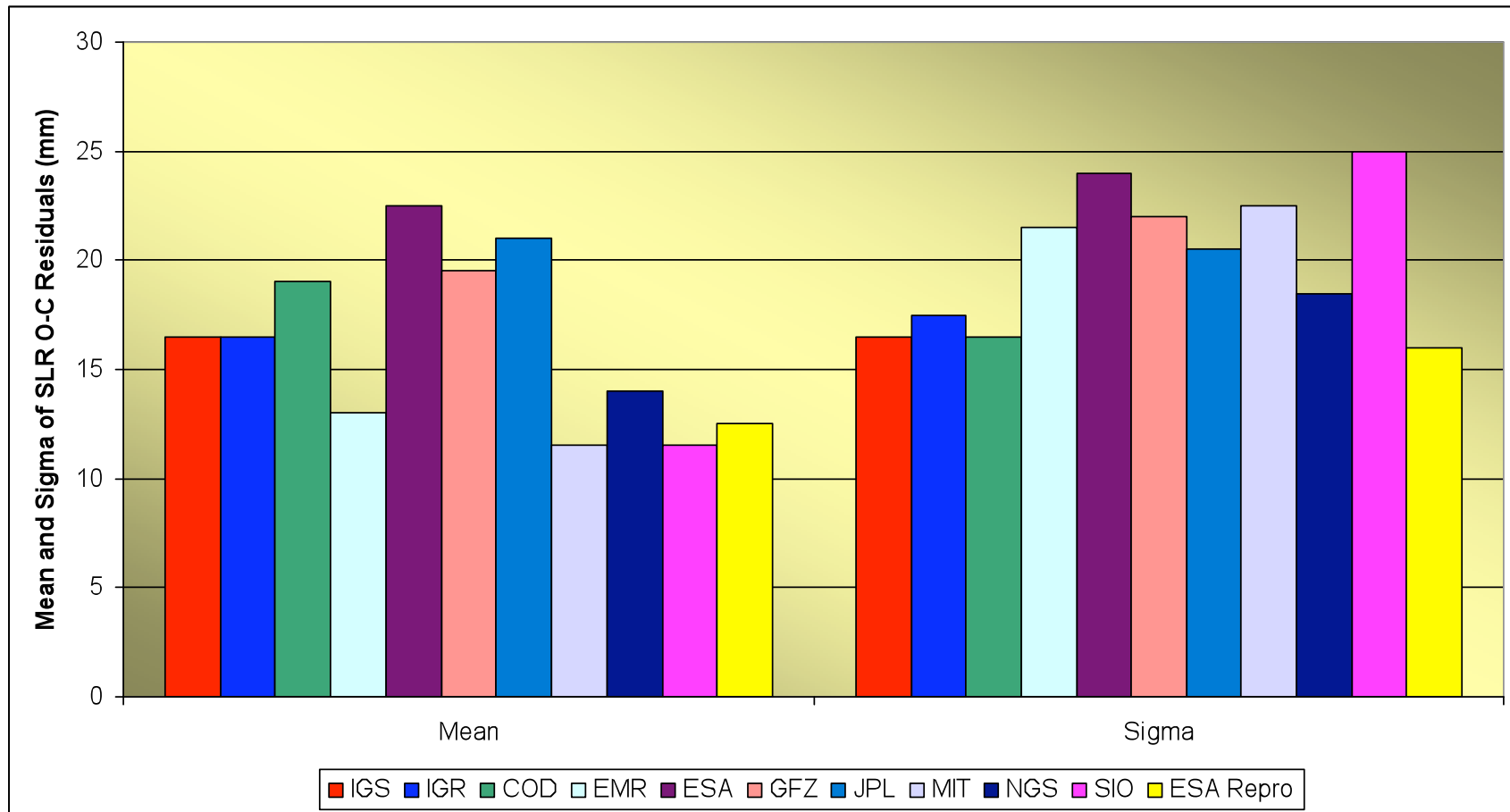
Typical SLR range residuals for IGS final orbits

based on data of 2007, *Springer* [2007]

- 1-2 cm RMS
 - compares with ~1 cm RMS for SLR long-arc tracking of Lageos
 - residuals have improved due to orbit improvement
- 1.5-2.5 cm range bias reflecting
 - AC orbital scale analysis difference (range of +/-1.3 cm)
 - possible albedo mismodeling
 - possible CoM offset mismodeling

Analysis to date ■ ■ ■ GPS orbit validation (2/3)

for AC final GPS orbits



Detection of GPS orbit modeling problems

- Deficiencies in a priori solar radiation pressure model found by *Urschl et al.* [2007]
 - ROCK model [*Fliegel et al.*, 1992] causes large residuals close to eclipse seasons
 - CODE model [*Springer et al.*, 1999] reduces systematic behavior

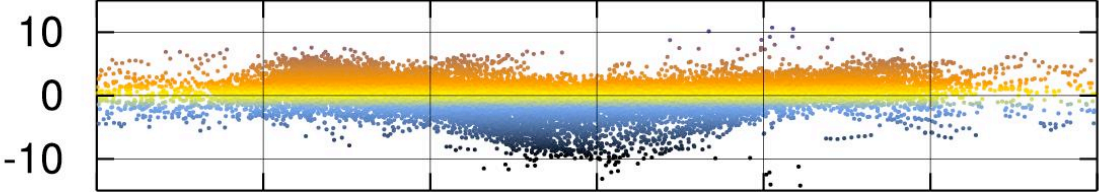
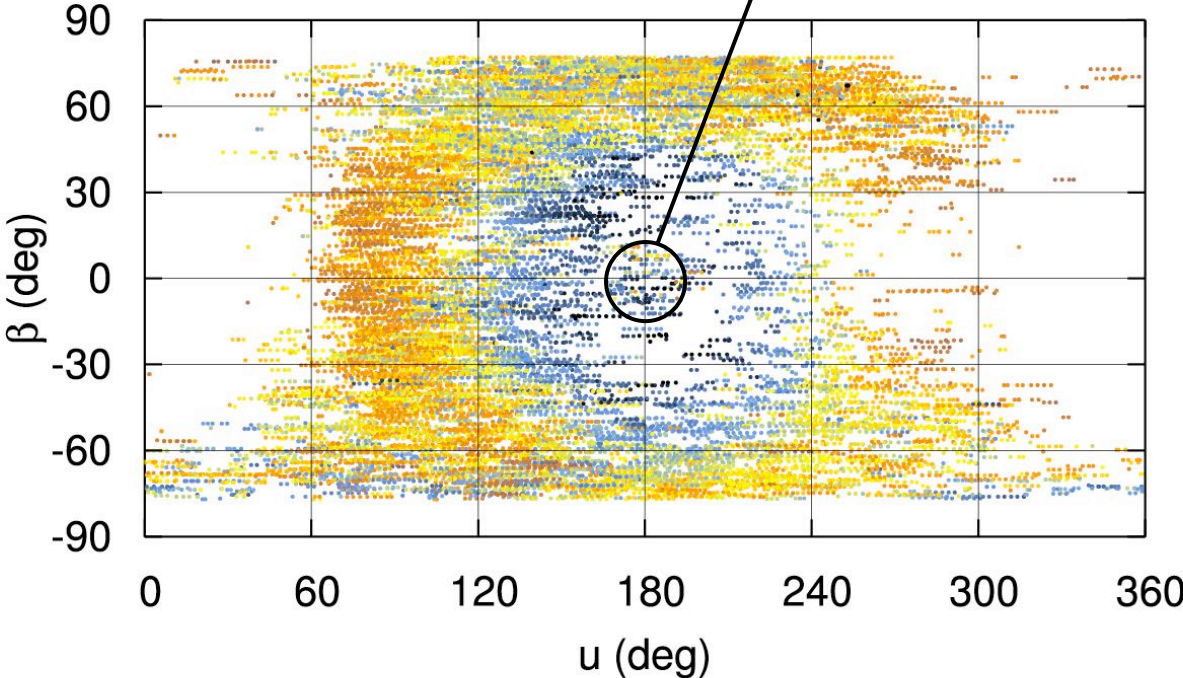
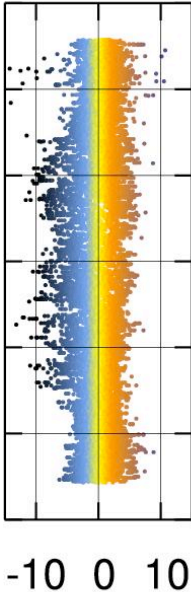
Analysis to date

SLR range residuals (1/3)

as function of satellites' position wrt Sun

ROCK a priori SRP model

Elevation of sun above orbital plane



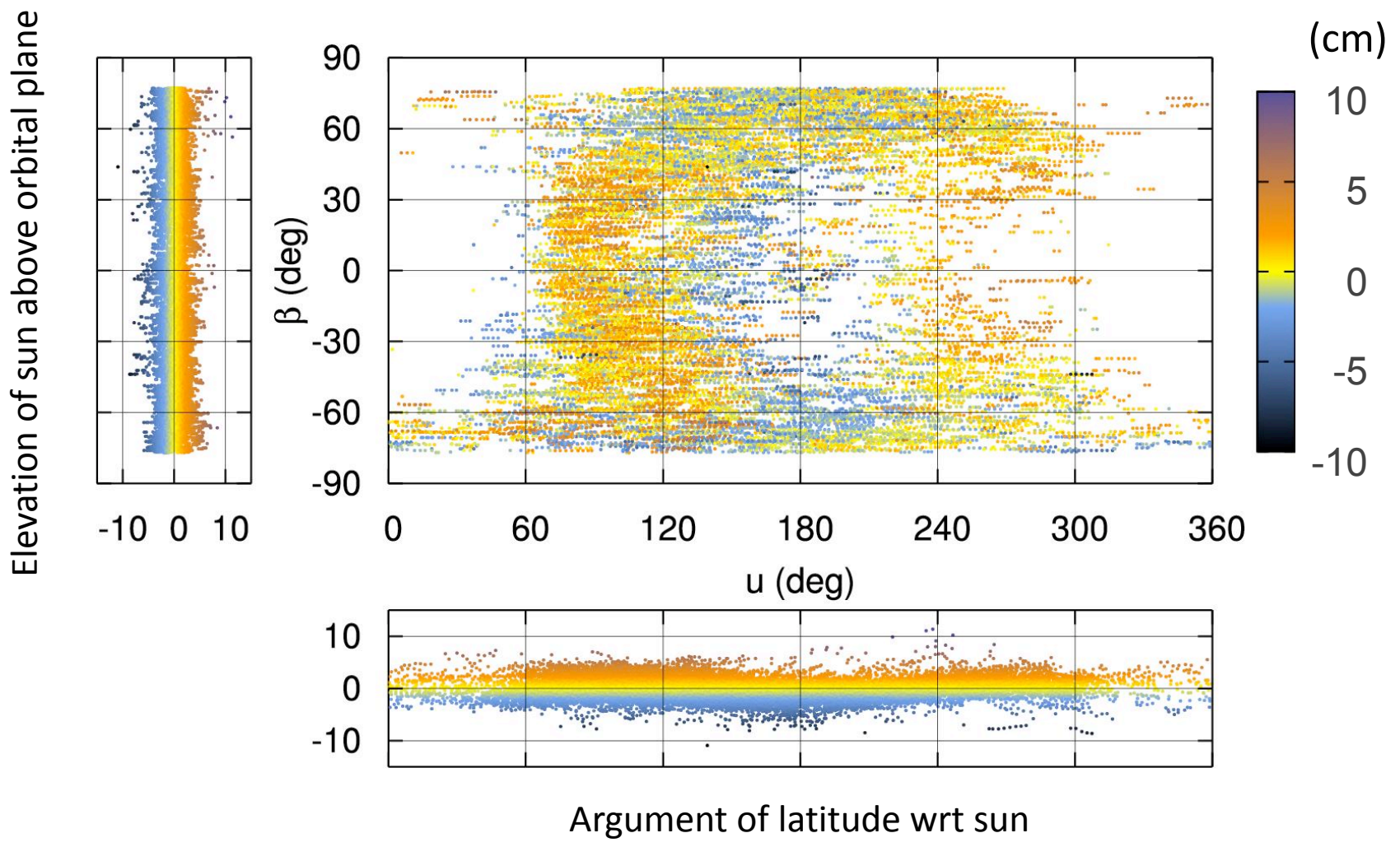
Argument of latitude wrt sun

Analysis to date

SLR range residuals (2/3)

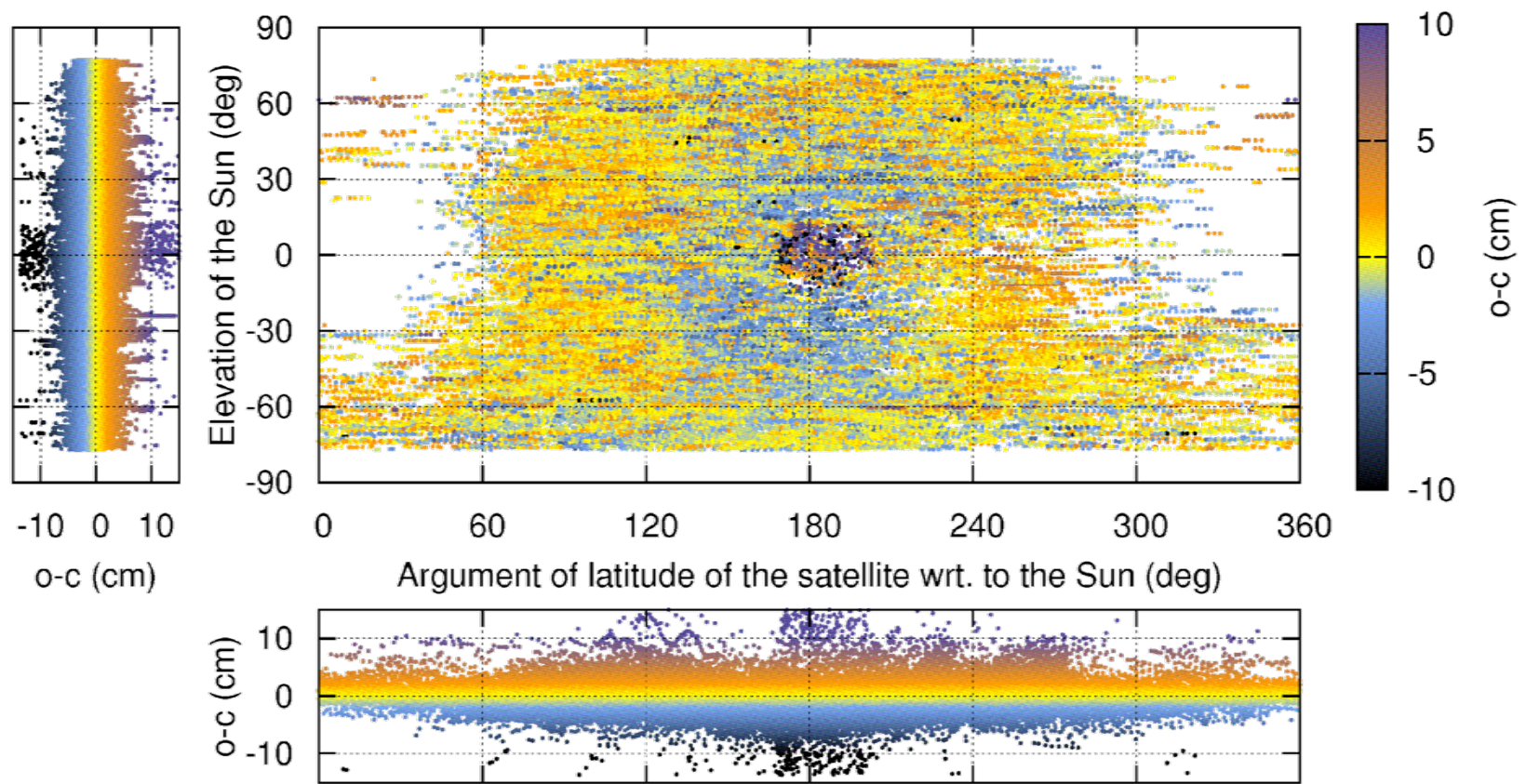
CODE a priori SRP model

as function of satellites' position wrt Sun



Analysis to date ■■■ SLR range residuals (3/3)

based on reprocessed ESOC orbit series 1995.0 – 2009.0



- SLR and GPS agree very well!
- Only a **small bias (~1.8 cm)** and **eclipse season (attitude) effects** remain.

Summary of current status ■■■

- SLR has been demonstrated to be viable, valuable and unique technique for independent analysis of GPS orbits through
 - evaluation of GPS error budget
 - provides radial orbit accuracy
 - detection of systematic errors (inter-system biases)
 - verification of orbit models (e.g. solar radiation pressure, albedo, attitude, ...)
- SLR has had very limited impact on GPS orbit improvement in combined data analyses due to sparseness of data
 - only 1-2 satellites with retro-reflectors, insufficient SLR stations, fragmentary data
- Unresolved data processing issues regarding bias corrections
- Included in routine ILRS SLR satellite tracking schedule

Combination of GPS + SLR for GPS orbit determination

- Potential for GPS orbit improvement, but
 - inter-system biases have to be understood and modeled
 - orbit model deficiencies have to be resolved
 - SLR tracking data has to cover most of the orbital arc (today there are considerably more SLR sites on the northern hemisphere)
- SLR tracking data for GPS satellites are not used in routine GPS processing by IGS Analysis Centers
 - subject to change?

Because laser retro-reflectors can be put on nearly *any* satellite, they provide basis for common observing systems of nearly *all* satellites

- **Common reference frame** (large amount of “space ties” would enable connections between the reference frames of the different techniques (IDS, IGS, ILRS))
 - tie GPS to ITRF
 - tie GPS to other GNSS
- **Interchangeability and consistency of results**
- **Quality assurance**
- Improved **long-term stability** of GPS data products

Goals for GPS III set by the multi-agency (U.S.) working group in 2007

- Achieve **stable geodetic reference frame** with accuracy >10 times better than user requirements for positioning, navigation, and timing
- Maintain a **close alignment of the WGS 84 and ITRF**
- Provide **quality assessment capability** independent of current “microwave” orbits and clocks
- Ensure **interoperability of GPS with other GNSS constellations** through **a common, independent measurement technique**

*Reference: GPS III Geodetic Requirements, submitted to IFOR, 13 April 2007
(for Official Use only)*

Conclusion of the WG

- SLR most practical, cost-beneficial and effective means of meeting these requirements

Proposal of the WG (in consultation with the ILRS)

- Concept of operations for the ILRS to control and schedule laser ranging to GPS
- Protocol would essentially apply to all GNSS

To take advantage of the potential benefits of SLR there is a need for

- Studies to demonstrate and quantify the potential benefits
- Studies to develop optimal observing strategy
- Improved ILRS tracking network
 - more sites with better geometry
 - better tracking and enhanced data acquisition
- Maintenance of accurate CoM offsets for GPS s/c
- GPS-SLR ties
 - Combining SLR/GPS normal equations may enable accurate space ties.
 - Are ground ties then needed?

To take advantage of the potential benefits of SLR there is a need for

- Greater number of GPS s/c with retro-reflectors
 - For science application: number not yet determined
 - Consensus of U.S. inter-agency working group: every GPS III s/c to carry a retro-reflector

Contributors ■■■

Position Paper on Impact of SLR Tracking on GPS

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