

# A new Australian conjunction assessment and threat warning service

**James C. S. Bennett**

*Astrodynamics Group Leader, EOS Space Systems Pty Ltd*

*Space Asset Management Program Leader, Space Environment Research Centre*

**INTERNATIONAL WORKSHOP ON SPACE DEBRIS MANAGEMENT, 9<sup>th</sup> November 2018**



**Australian Government**  
Department of Industry,  
Innovation and Science

**Business**  
Cooperative Research  
Centres Program

# Overview

- Brief introduction to SERC
  - RP3: Space Asset Management program
- Progress in operational conjunction and threat warning service.
- Timeline to initial operational capability and full operational capability.



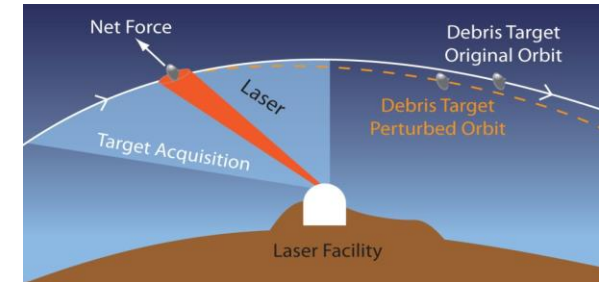
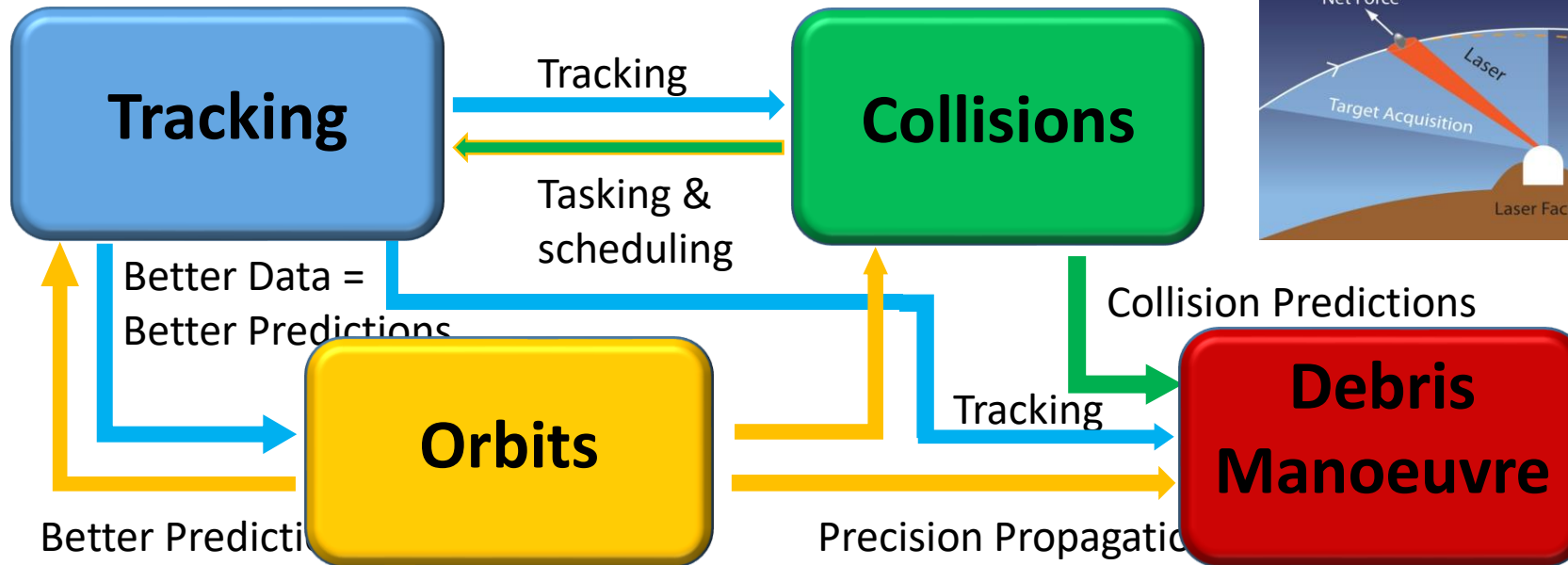
# SERC Founding Participants



**Business**  
Cooperative Research  
Centres Programme



**SERC  
Research  
Programs**



# The current team

## Research staff:

- Dr James Bennett
- Dr Daniel Kucharski
- Dr Marek Möckel
- Dr Michael Lachut
- Dr Sven Flegel
- Mr Jeffrey Wardman
- Mr David Kooymans
- EOS Space Systems Team
- Industrial Sciences Group

## PhD Candidates:

- Mr Joseph O’Leary
- Mr Richard Samuel
- Mr James Allworth
- Ms Hansani Kaushalya Perera  
THANIPPULI KANKANAMALAGE

## Student Interns:

- Thomas La
- Nathaniel McGrath

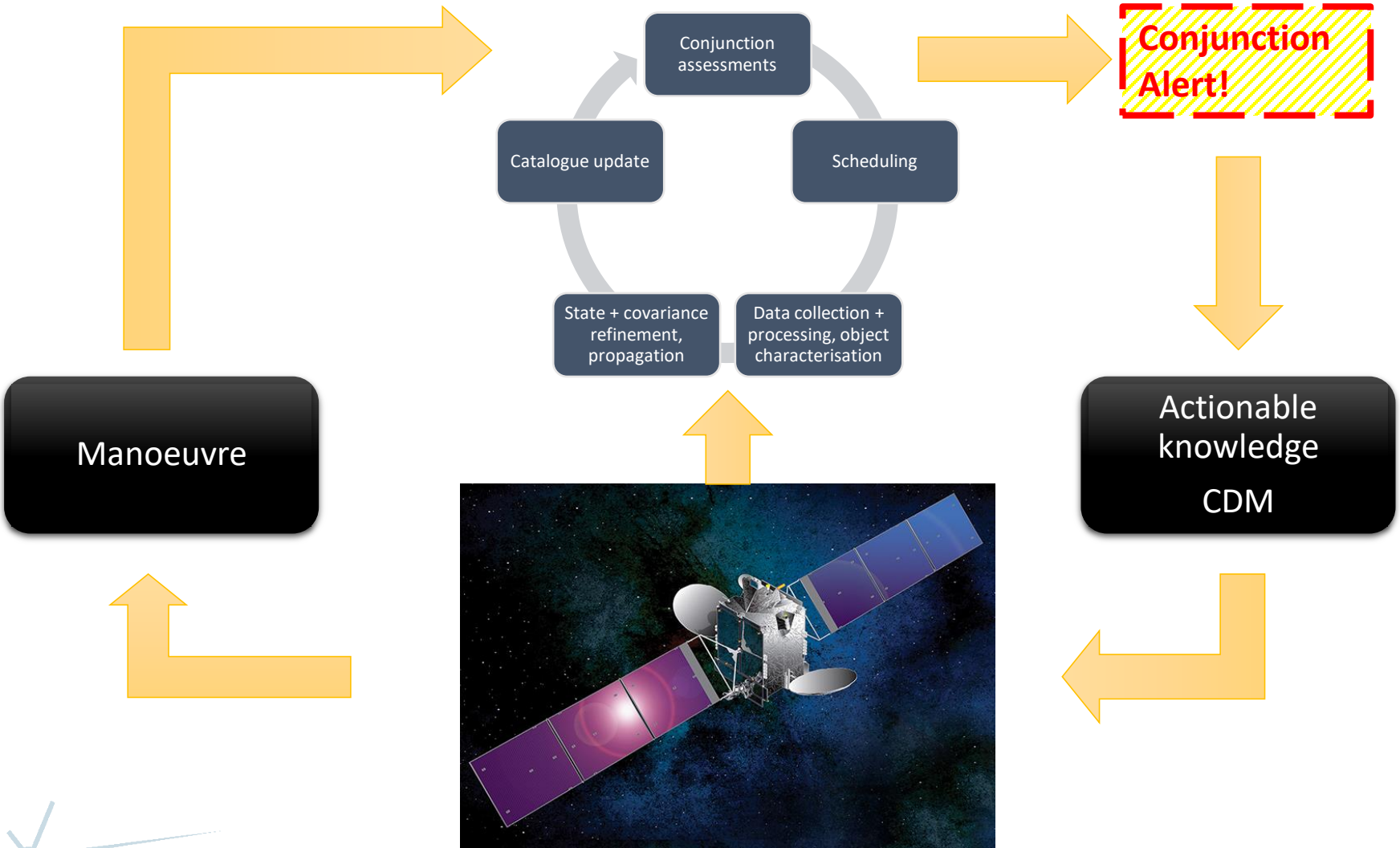


# Other RP3 presentations

Tue 6th	11:45	12:00	Gravity field determination using post-Newtonian energy integral	Joseph O'Leary	University of South Australia / Space Environment Research Centre, Australia
	12:00	12:15	Orbit determination and prediction accuracy of TOPEX with a priori solar radiation force derived from photometrics and laser ranging data	Michael Lachut	EOS Space Systems, Queanbeyan / Space Environment Research Centre, Mt Stromlo, Australia
Fri 9th	14:15	14:30	Assessing GEO close encounter warnings for spacecraft operations	Sven Flegel	Space Environment Research Centre, Canberra / Visiting Researcher to the Royal Melbourne Institute of Technology, Australia
	16:15	16:30	High-definition Photometry - New tool for space debris characterization	Daniel Kucharski	Space Environment Research Centre, Canberra, Australia / The University of Texas, Austin, USA,
Fri 9th	SD11		Design of a high-performance conjunction assessment service	Marek Moeckel	Space Environment Research Centre, Mt Stromlo, Australia
	SD12		Increasing the determinacy and uniqueness of solutions to the physical characteristics and non-natural behaviours of near-earth orbiting space objects	Richard Samuel	Space Environment Research Centre / Australian National University, Weston Creek, Australia
	SD13		Design & development of an optimized sensor scheduling & tasking programme for tracking space objects	David Shteinman	Industrial Sciences Group, Sydney, Australia

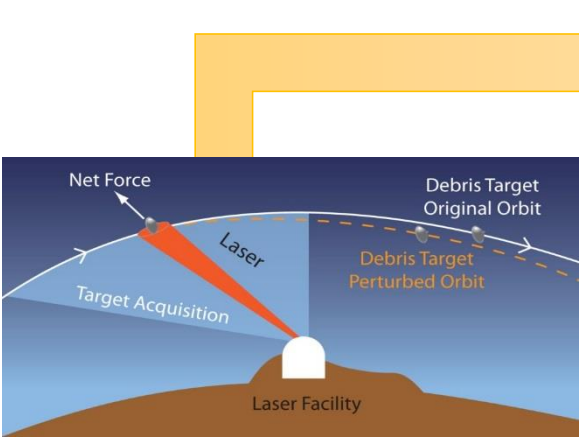


# Research Program 3: Space Asset Management

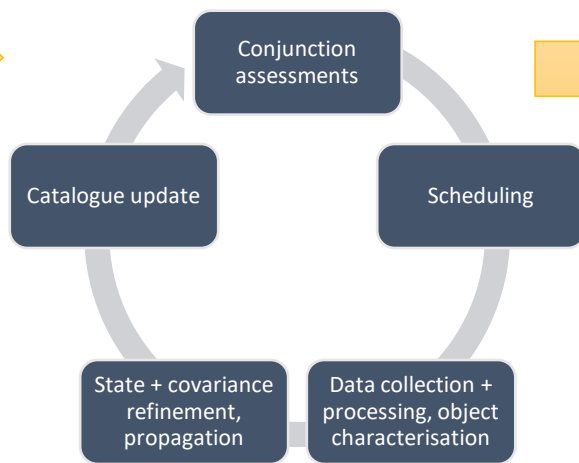


Source: <https://www.optus.com.au/about/network/satellite/fleet/optus-10>





Manoeuvre



**Conjunction Alert!**

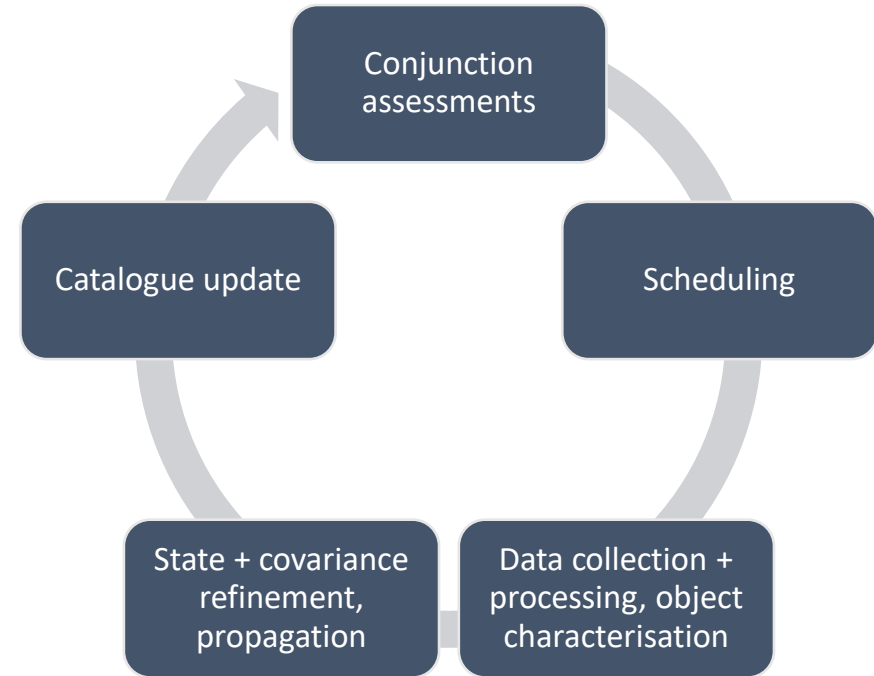
Actionable knowledge  
CDM

Manoeuvre simulations



# Presentation Overview

- Sensors
- Scheduling
- Database/catalogue
- Object characterisation
- Orbit determination
- Error propagation
- Conjunction assessments





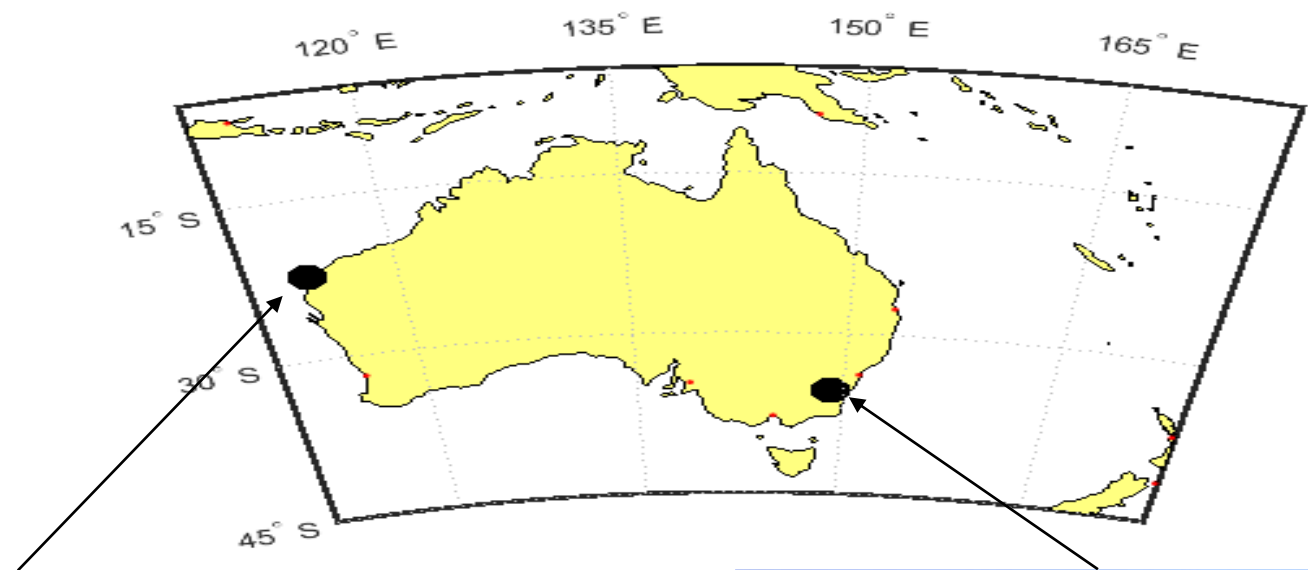
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# Sensor network

- EOS Space Systems' Space Debris Tracking Station at Mount Stromlo
- New operational site at Learmonth
  - Collaboration between EOS Space Systems & Lockheed Martin with support from AUS DoD



Learmonth, WA (22° S, 114° E)

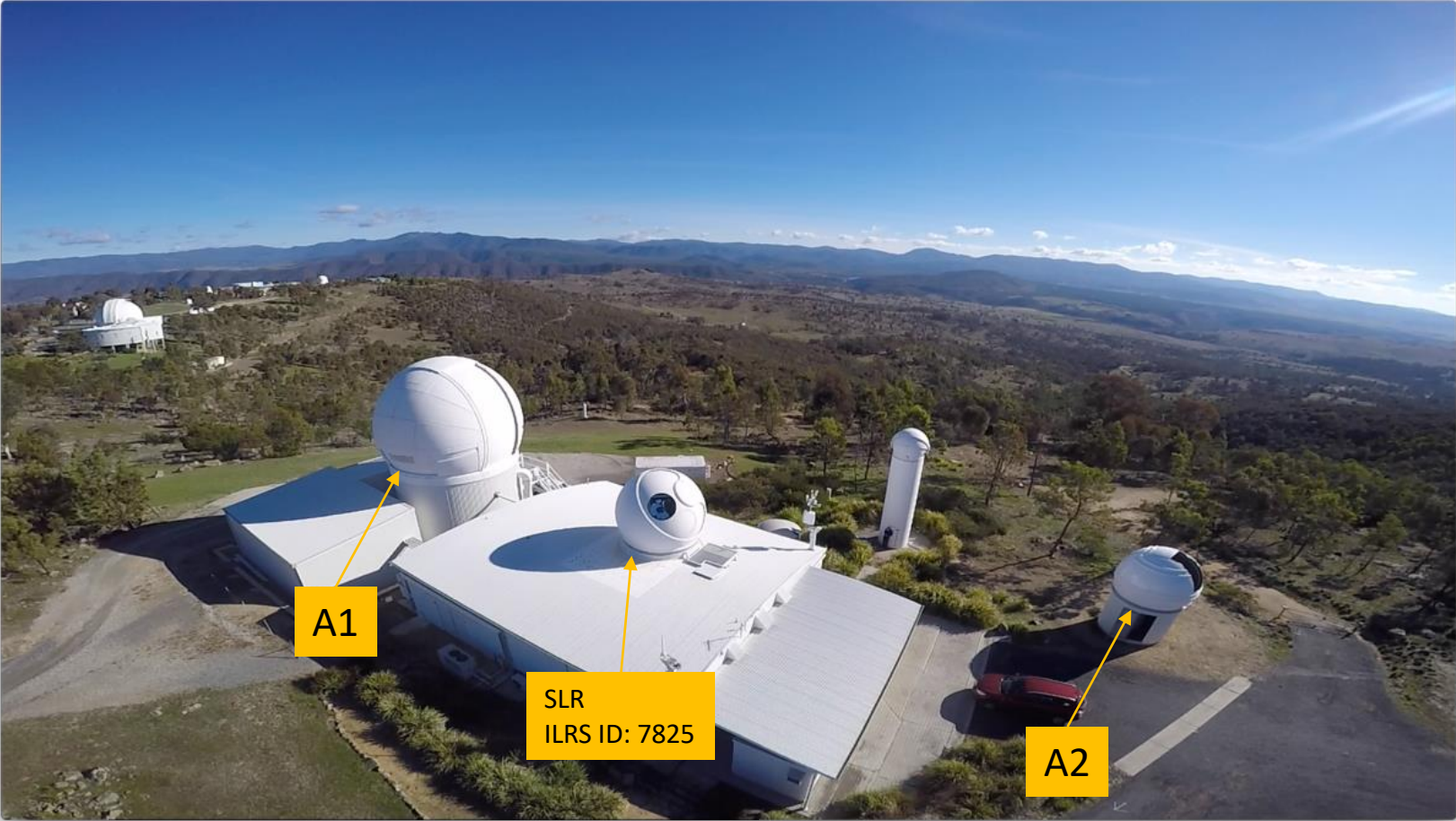


Mt Stromlo, ACT (35° S, 149° E)

System ID	Site	Aperture	Configuration
A1	Mt Stromlo	1.8 m	Active + Passive
A2	Mt Stromlo	0.7 m	Passive
B1	Learmonth	1.0 m	Active + Passive
B2	Learmonth	1.0 m	Active + Passive
B3	Learmonth	0.7 m	Passive
B4	Learmonth	0.7 m	Passive



# Sensor network – Mt Stromlo

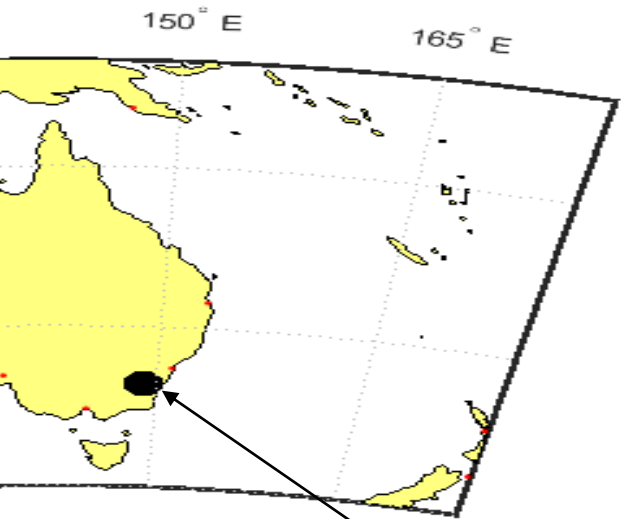


Mt Stromlo, ACT (35° S, 149° E)

# Sensor network



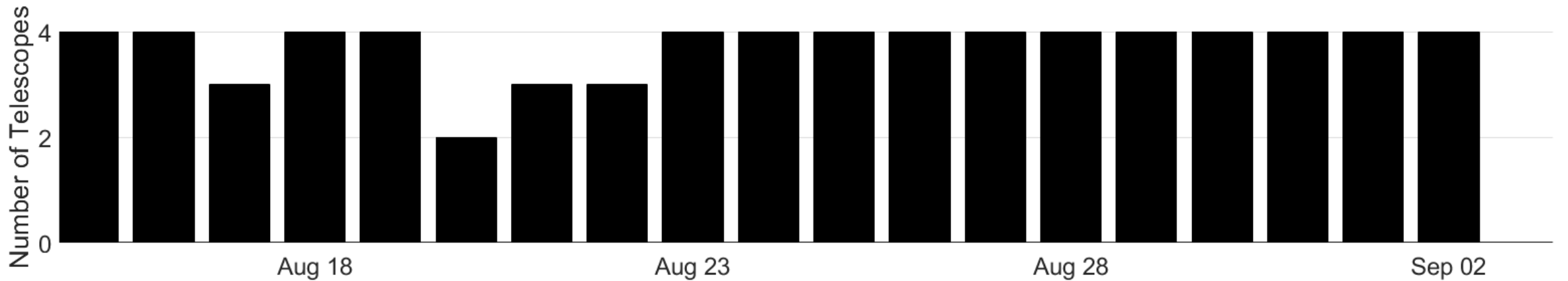
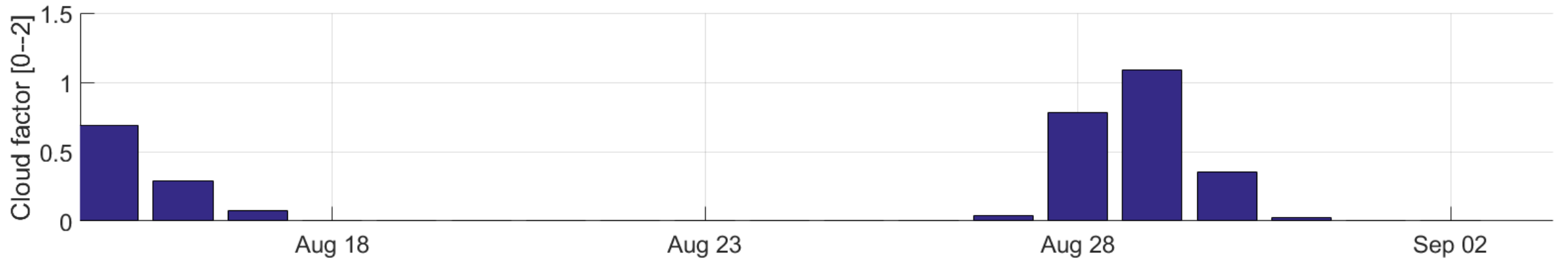
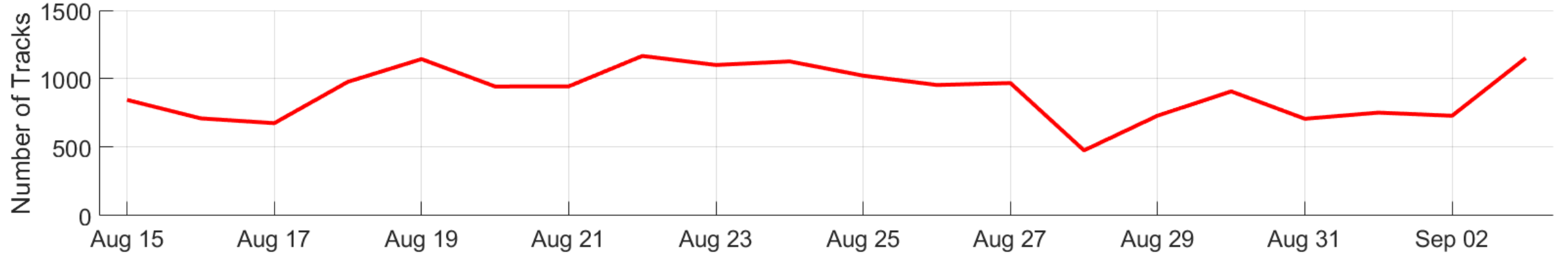
Learmonth, WA ( $22^{\circ}$  S,  $114^{\circ}$  E)



Mt Stromlo, ACT ( $35^{\circ}$  S,  $149^{\circ}$  E)



# Recent tracking – Learmonth only



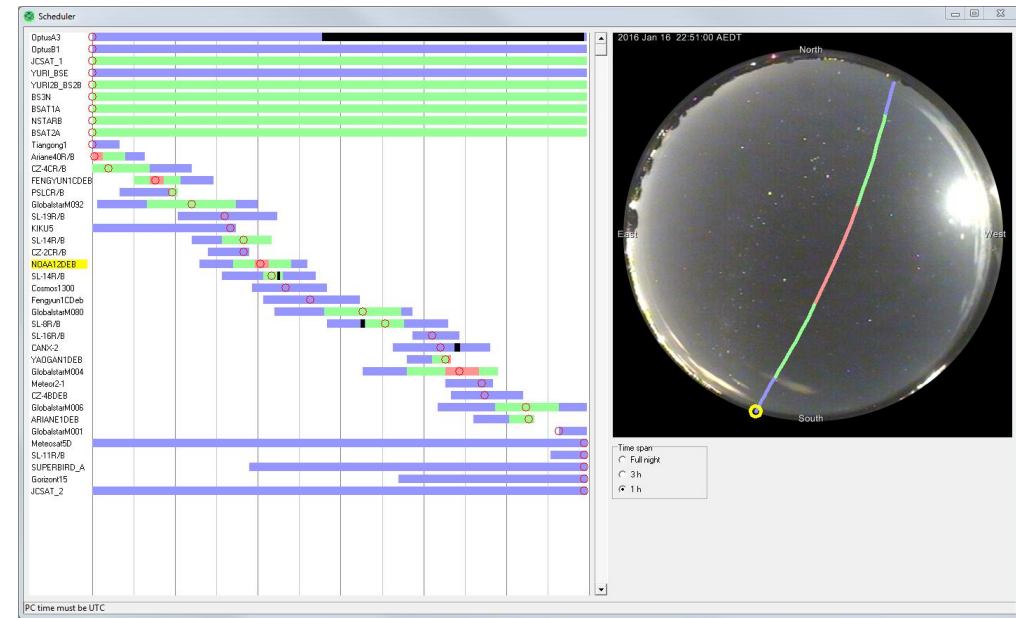
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# Network scheduling

- EOS have several methods of tasking the network
- SERC have developed an information gain based scheduler that
  - Started by Dr. Steve Gehly\*
    - Recoded for use in operations (James Allworth)
  - Interface with EOS sensor network completed and single-sensor testing has been achieved.
  - Contracted to The Industrial Sciences Group:  
<http://www.industrialsciences.com.au/>
    - Phase 1 completed, multi-sensor functionality across 6 active and passive sensor network, under testing.
    - Phase 2 started
- Phase 2 of the scheduler will see it optimised in C++ to handle a larger network of sensors and a catalogue of 100,000+ objects (late 2018)

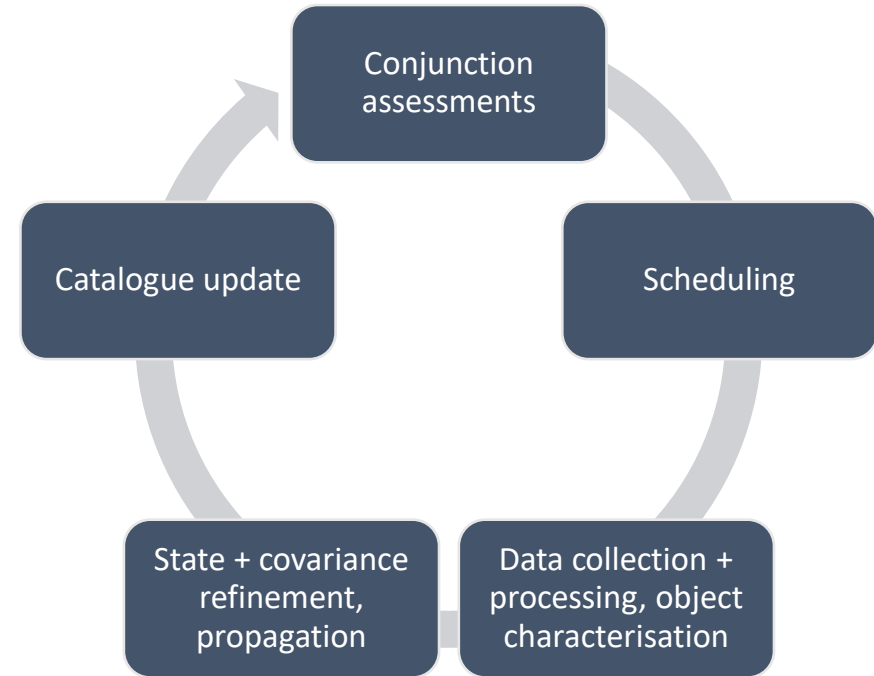


\* Gehly, S. and J. Bennett, *Incorporating Target Priorities in the Sensor Tasking Reward Function*, in *Advanced Maui Optical and Space Surveillance Technologies Conference*. 2015: Maui, Hawaii.  
Gehly, S. and J. Bennett, *Distributed Fusion Sensor Networks for Space Situational Awareness*, in *68th International Astronautical Congress*. 2017: Adelaide, Australia.



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- Central database-backed application
  - Storage, association, processing tracking data, light curves, object characteristics, calibrations
  - HTTP interface with small html frontend
- Relational database
  - Traceability – e.g. Orbit determination: what tracks, what sensors, what force models, EOP, solar flux, observation weighting etc.
- Automation of track correlations & orbit determinations
- System monitoring

## OD Summary

ID	6464
Satellite ID	13688
Satellite Norad ID	40747
Satellite Cospar ID	15036B
Satellite Name	DELTA 4 R/B
OD Start Date	20180819000000
OD Span	8
OP Span	7
Record Status	SUCCESS
Reason	
Processing Started	20180828063013
Processing Completed	20180828141355
Scope version	3.1.1

Orbital Period	1307.5
Inclination	26.1
Apogee	66017
Perigee	445
RCS	18.0698
Orbital Regime	LGTO
Satcat Status	DEBRIS

## OD Actions

Update Status

Check Generated CPF

Check Residuals

Check State

Check Error against Obs

Check Bias and RMS

Check Covariance

Check Satellite Data

Check OD Assess

Check Initial State

Check Scope Output

Download Results

Rerun OD

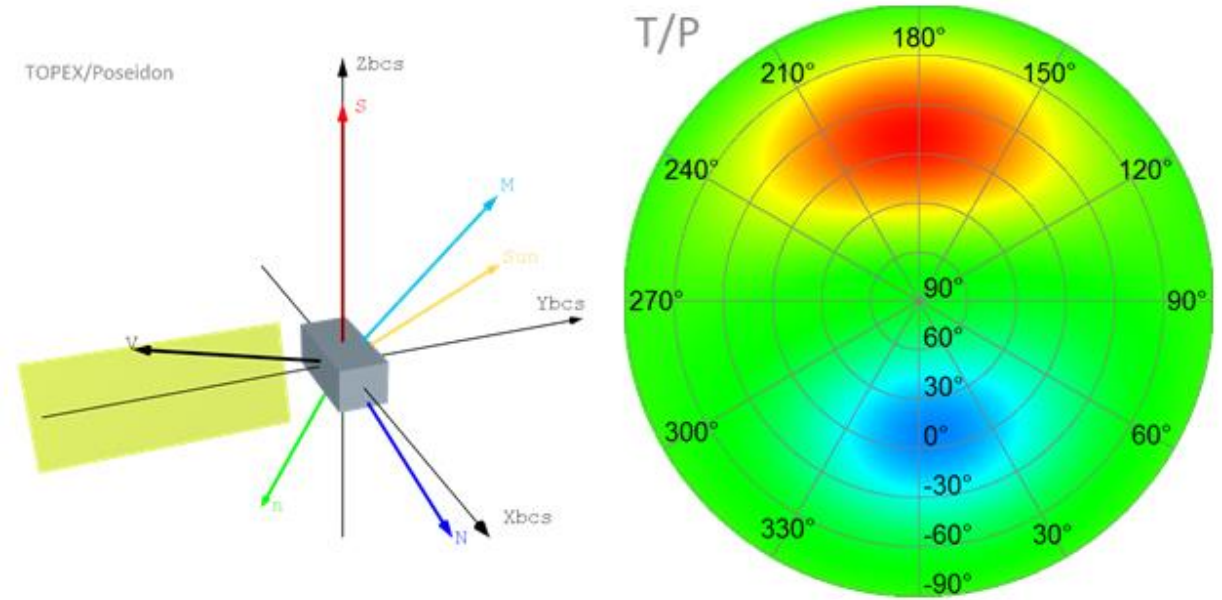
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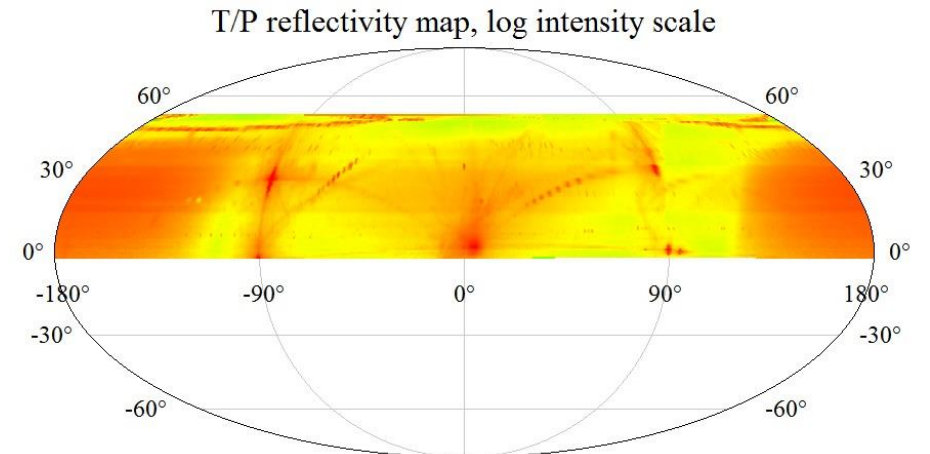


# Object Characterisations

- Characterisation for the laser manoeuvre experiment, spin analyses
- High rate detector capable of 100 kHz sampling of photons
  - Mounted on the A2 telescope at Mt Stromlo
- Collaboration between SERC, EOS, Graz, NICT, Borowiec, University of Texas at Austin
- Andor Zyla 5.5 Front Illuminated sCMOS camera has been mounted to A2.



Left: TOPEX/Poseidon: satellite body and force vectors. Right: body surface response to the incoming photon flux indicates a larger area where the positive torque can be generated: red) spin-up, blue) de-spin.



Reflectivity map of TOPEX/Poseidon measured by Graz photon counting system on July 10, 2015

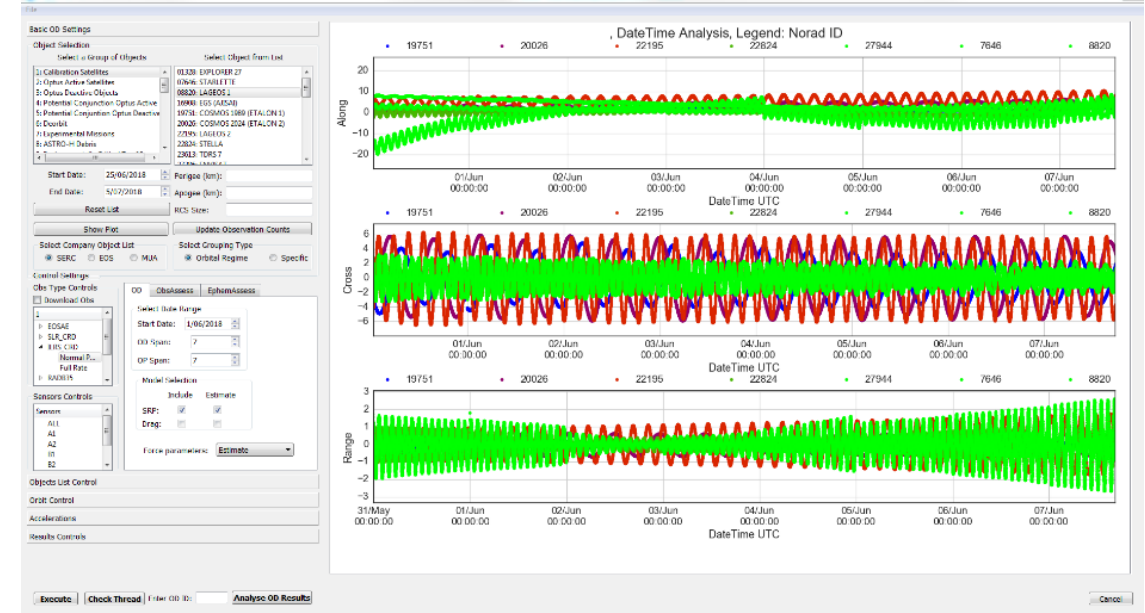
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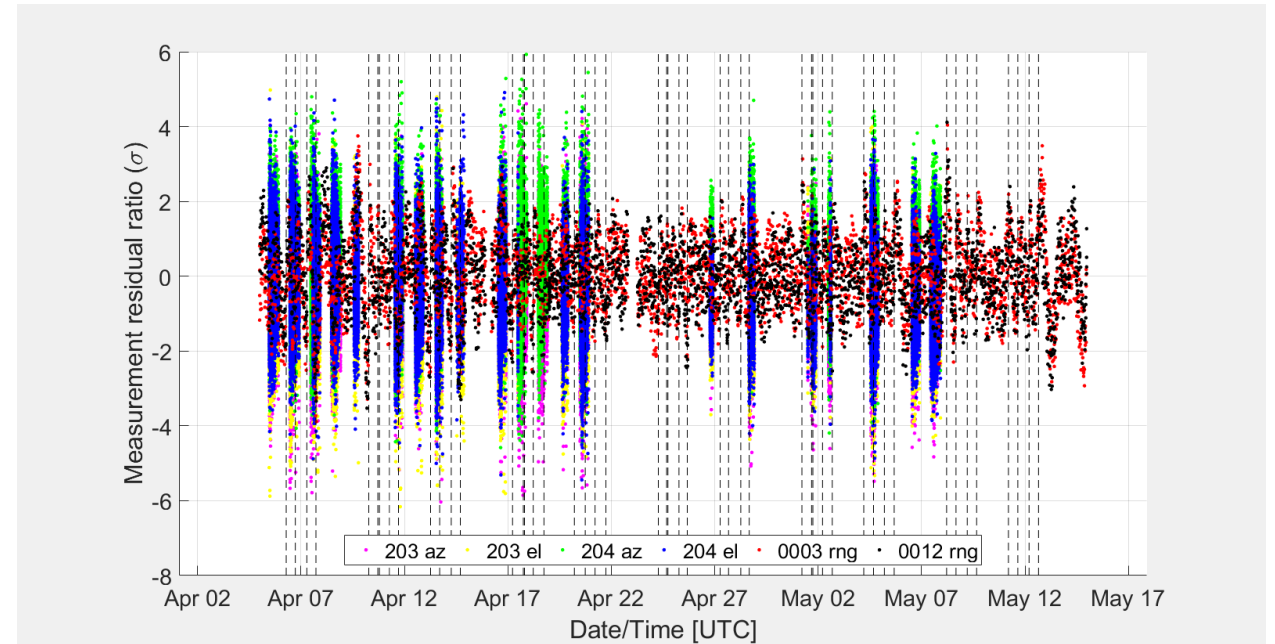
# Orbit determinations

- In-house orbit determination software in C++;
- Automated ephemeris generation and sensor cueing
- Batch process, will also include filters and run side-by-side comparisons
- Störmer-Cowell predictor-corrector numerical integrator
- New observation sources can be integrated quickly
- Spherical/aspherical satellite geometry



# Manoeuvre fitting

- Can successfully fit multiple manoeuvre types
- Example:
  - GEO object: Optus 10
  - 40 day OD, 49 SPT (N-S), 5 bi-prop (E-W)
  - Two station RF range, optical from B3 & B4.
- Needs to be automated
  - Automate delivery of manoeuvre plans
  - Automate manoeuvre detection algorithms
    - Collaboration with UT Austin & UNSW



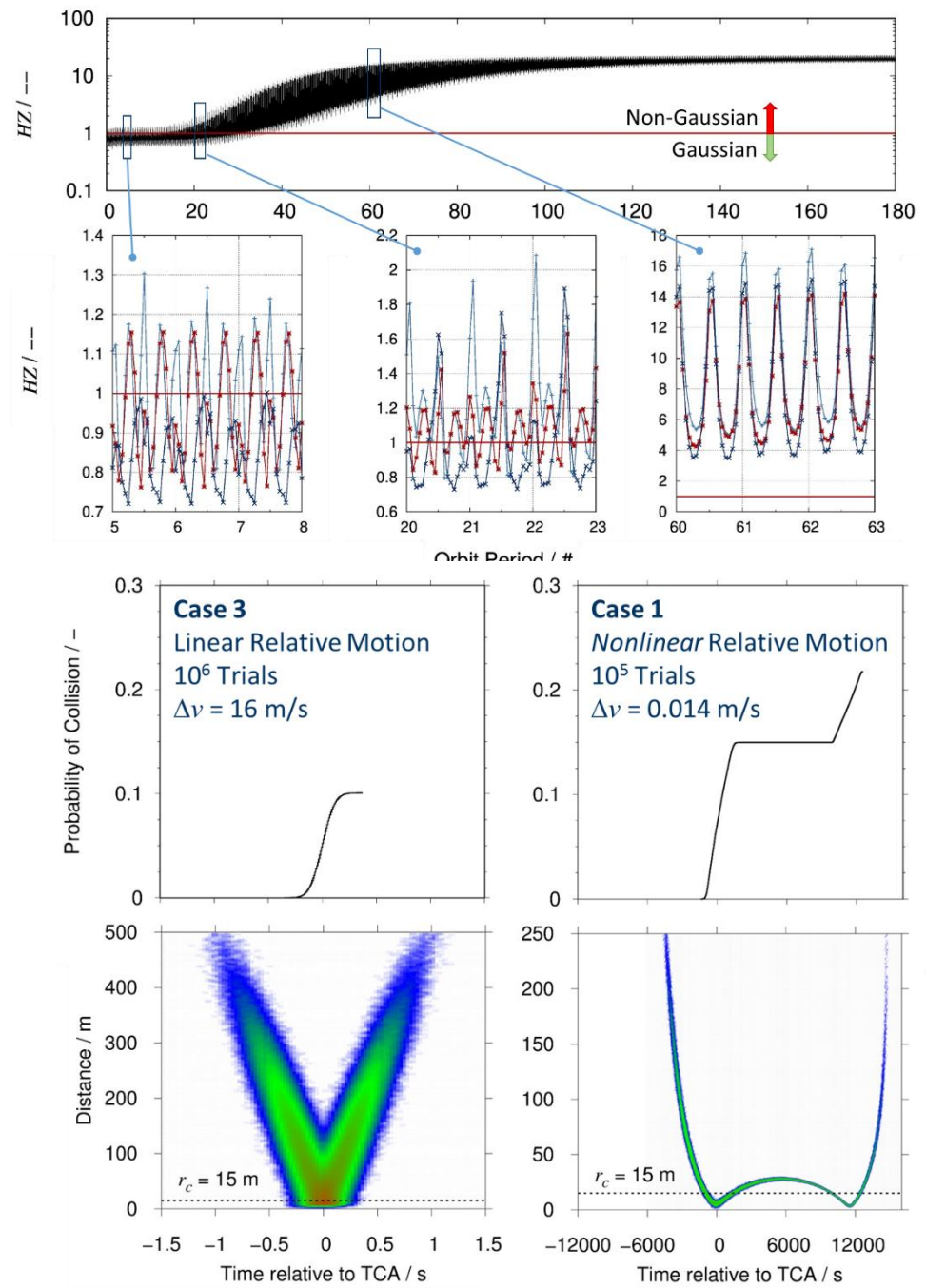
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# State uncertainty prediction


- Rigorous assessment of the breakdown in Gaussianity of the state uncertainty
  - Henze-Zirkler test for multivariate normality
  - Store in object catalogue, use for scheduling, conjunction assessments, track associations, OD assessments
- Probability of collision in conjunction assessments
- Actionable conjunction assessments





# CDM visualisation

Analyze CDM About



Load CDM

**Orbit Frame**  
ECI

**Camera Focus**  
Earth

**Draw Elements**

- Coordinates
- Orbits
- Error Volume
- Error Axes
- Satellite Marker
- To Other

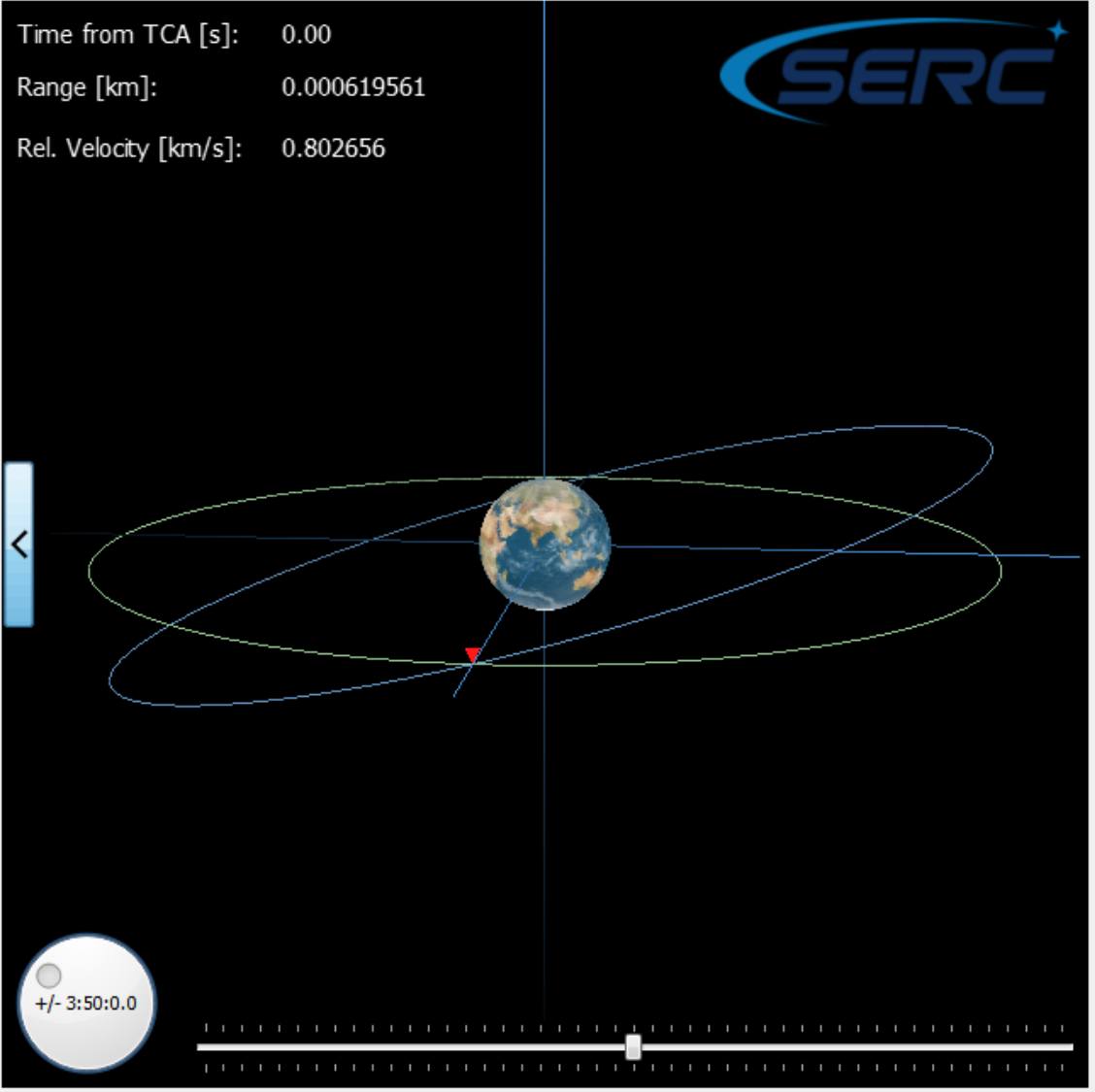

**Satellite Properties**

GEO\_EQUATORIAL  
Diameter [m]: 10.000

GEO\_INCLINED  
Diameter [m]: 10.000

**Position Uncertainty**  
Confidence [%]: 95.000

Time from TCA [s]: 0.00  
Range [km]: 0.000619561  
Rel. Velocity [km/s]: 0.802656



<

+/- 3:50:0.0

SERC



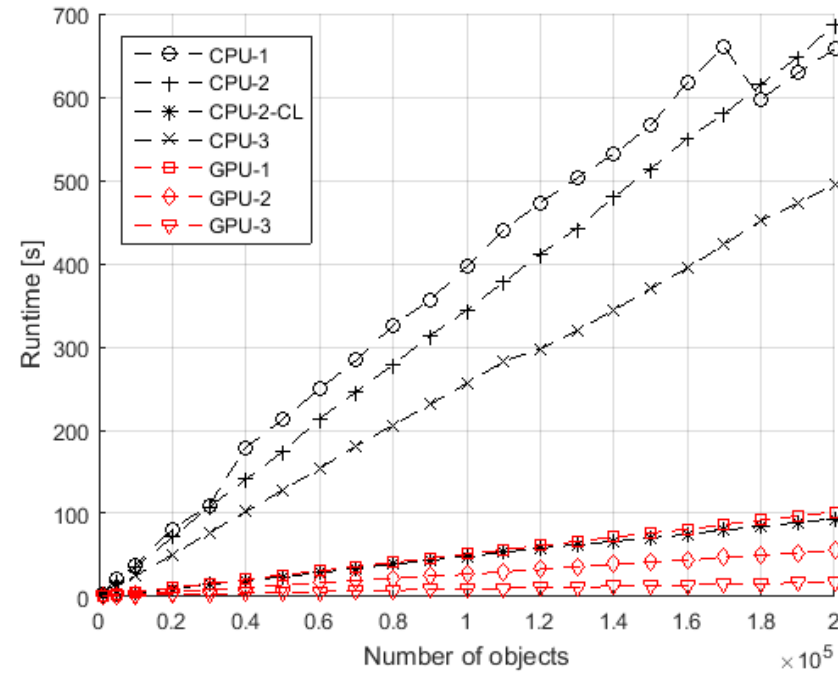
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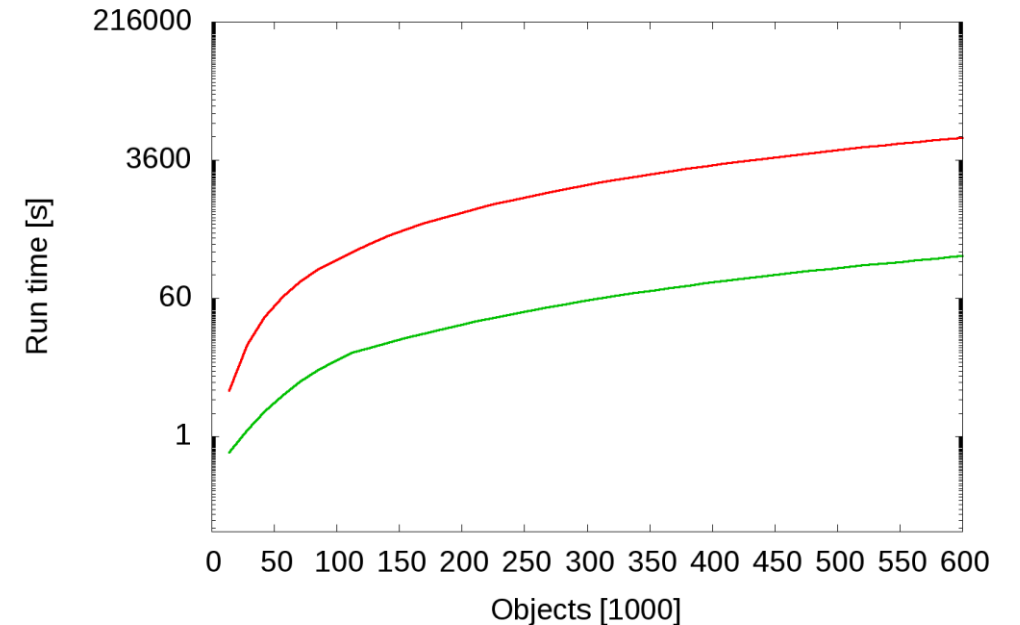


# Conjunction assessments

- Parallelised conjunction assessments can run on multi-core CPU and GPU
  - Large speed-ups achieved with SGP4;
  - All-on-all 7-day conjunction assessment in 48 minutes, down from 8 hours
  - Generic propagator interface
- Implemented full force model numerical integration
  - Currently being parallelised
  - Early indication is scales linearly with number of objects
- Ability to integrate other ephemeris information such as operator ephemerides (e.g. Optus)



CPU-1	Intel i7-4710HQ 3.5GHz (1 core)
CPU-2	Intel Xeon E5-1620 3.6GHz (1 core)
CPU-2-CL	Intel Xeon E5-1620 3.6GHz (OpenCL, 8 cores)
CPU-3	Intel i7-7700 3.6GHz (1 core)
GPU-1	Nvidia GeForce 860m (OpenCL)
GPU-2	Nvidia GeForce GTX960 (OpenCL)
GPU-3	Nvidia GeForce GTX1070 (OpenCL)



CPU (i7-4790) — OpenCL GPU (GTX 960) —

# Simple interface

The screenshot displays the SCRAP GUI interface. On the left, there is a control panel with the following elements:

- Server:** SCRAP
- Sources:** Scenario 0, Coming Soon
- Scenario:** Start: 2.45832e+06, End: 2.45833e+06, TimeStep: 200, MaxDistance: 5, File: tle\_nightly\_2018-07-24.txt
- Table:** A table with columns: Object1, Object2, Distance, rel. Velocity, Date, Name1, Name2. It lists 15 conjunction events.
- Conjunction Counter:** 2/26
- Progress:** 2% complete, 132 M/s
- Buttons:** Enqueue, Cancel, Download Results
- Status:** Securely connected to gravity.sevc

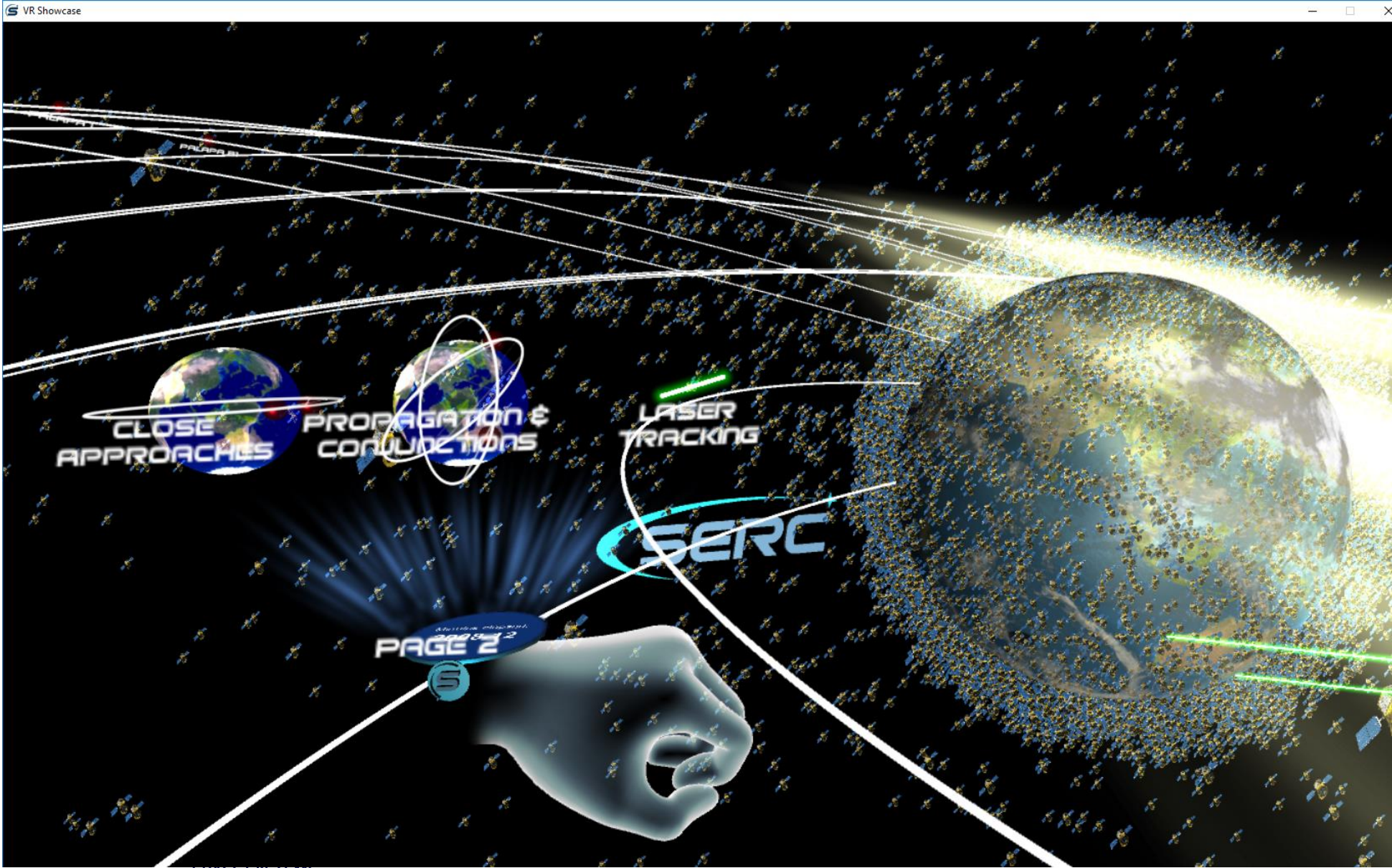
On the right, a 3D model of Earth shows two orbital paths: a yellow orbit and a white orbit, with a red line indicating the conjunction point.

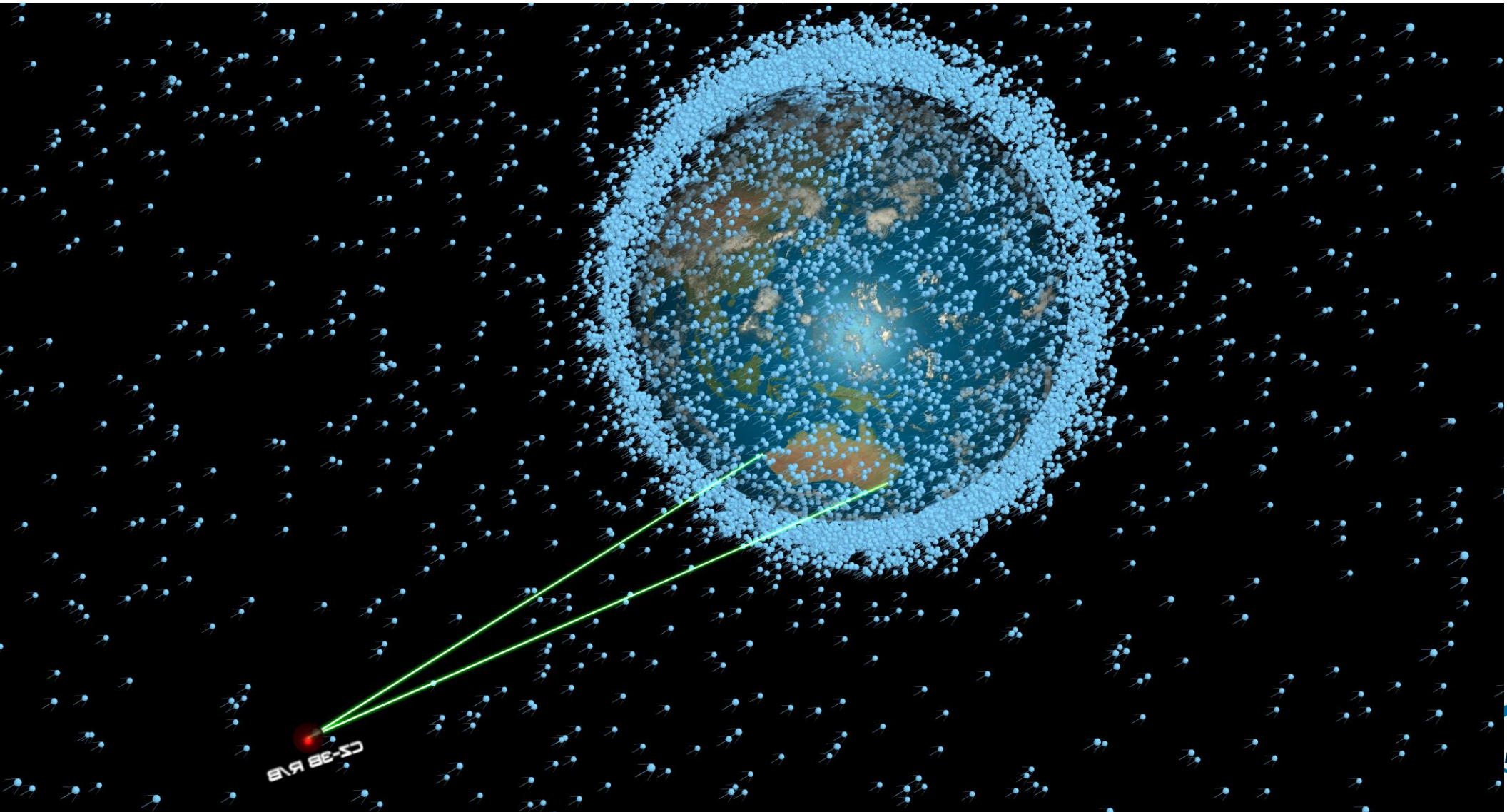
Conjunctions: 87451, Start Date: 2018-09-04T12:00:00, End Date: 2018-09-11T12:00:00 [Compare](#)

ID 1	ID 2	Distance	Relative Velocity	Time	Name 1	Name 2
31547	36658	0.0210061	10.5082	2018-09-09T06:02:38	FENGYUN 1C DEB	FENGYUN 1C DEB
25490	38329	0.0287375	15.0094	2018-09-07T08:29:43	TAURUS R/B	DMSP 5D-2 F11 DEB
31901	40500	0.0332068	11.3349	2018-09-10T18:02:05	FENGYUN 1C DEB	DMSP 5D-2 F13 DEB
27126	37307	0.0424915	7.92719	2018-09-10T23:42:08	PSLV DEB	COSMOS 2251 DEB
19922	29965	0.0454632	14.711	2018-09-06T01:29:52	SL-8 R/B	FENGYUN 1C DEB
26930	33901	0.0476115	12.2392	2018-09-05T10:55:51	PICOSAT 9	COSMOS 2251 DEB
134	31012	0.0480762	14.6184	2018-09-06T03:13:43	THOR ABLESTAR DEB	FENGYUN 1C DEB
733	38510	0.0498728	14.4551	2018-09-11T01:03:51	THOR AGENA D R/B	FENGYUN 1C DEB
31336	34570	0.05016	13.7216	2018-09-05T13:08:54	FENGYUN 1C DEB	COSMOS 2251 DEB
31167	34270	0.0512025	14.7952	2018-09-05T01:13:41	FENGYUN 1C DEB	COSMOS 2251 DEB
18681	38840	0.056241	13.7476	2018-09-08T07:18:06	SL-8 DEB	NOAA 8 DEB
12373	42550	0.0579649	14.1192	2018-09-09T02:40:46	DELTA 1 DEB	THORAD AGENA D DEB
420	34011	0.0595775	4.76017	2018-09-08T06:57:05	THOR ABLESTAR DEB	COSMOS 2251 DEB
42247	42425	0.0604704	13.8144	2018-09-11T07:59:41	SL-16 DEB	NOAA 16 DEB
14223	31068	0.062459	14.9889	2018-09-09T00:59:07	SCOUT G-1 DEB	FENGYUN 1C DEB
43547	43549	0.0629221	0.000460819	2018-09-09T01:05:09	TEMPEST-D	HALOSAT
31491	37686	0.0653341	14.0745	2018-09-06T14:24:39	FENGYUN 1C DEB	FENGYUN 1C DEB
32200	34192	0.0679	12.638	2018-09-05T23:53:11	FENGYUN 1C DEB	ARIANE 42P+ DEB
35225	36309	0.071062	14.7817	2018-09-07T02:25:46	FENGYUN 1C DEB	METEOR 2-6 DEB
31119	37988	0.0711577	14.1161	2018-09-10T15:40:36	SAUDICOMSAT 7	COSMOS 2251 DEB
30053	35129	0.0753762	0.721383	2018-09-10T08:09:40	FENGYUN 1C DEB	FENGYUN 1C DEB
41771	42051	0.0757076	0.648598	2018-09-10T03:00:17	SKYSAT C4	FLOCK 3P 72
21797	37637	0.0758537	14.7205	2018-09-04T12:49:49	SL-8 R/B	DELTA 1 DEB
6080	20891	0.0783068	14.4483	2018-09-10T01:14:52	SL-3 R/B	CZ-4 DEB
31404	38310	0.0831987	2.70006	2018-09-09T01:42:24	METEOR 2-5 DEB	CZ-4B DEB
36305	41858	0.0833316	14.969	2018-09-05T11:44:05	METEOR 1-11 DEB	CZ-2D R/B
32101	36100	0.0840153	13.5813	2018-09-09T06:09:35	FENGYUN 1C DEB	DMSP 5D-3 F18 DEB
41399	42245	0.0853848	14.689	2018-09-07T22:44:56	NOAA 16 DEB	SL-16 DEB
33826	42416	0.0854106	11.7038	2018-09-05T21:47:37	COSMOS 2251 DEB	NOAA 16 DEB
21796	30564	0.0865438	14.6248	2018-09-10T00:20:11	COSMOS 2173	FENGYUN 1C DEB
10658	11134	0.0883476	14.2104	2018-09-07T20:53:03	DELTA 1 DEB	COSMOS 1057
30660	40995	0.0885832	14.969	2018-09-06T15:03:25	FENGYUN 1C DEB	IRIDIUM 33 DEB
29911	34472	0.0894965	14.8852	2018-09-10T03:29:41	FENGYUN 1C DEB	COSMOS 2251 DEB
29899	30856	0.0904635	14.4428	2018-09-07T22:13:31	FENGYUN 1C DEB	FENGYUN 1C DEB
17716	25114	0.0915027	13.5355	2018-09-11T08:14:36	THORAD AGENA D DEB	ORBCOMM FM 11
26069	41353	0.092915	14.7861	2018-09-06T00:35:40	COSMOS 2369	NOAA 16 DEB
12343	30684	0.0943078	13.867	2018-09-11T05:16:12	COSMOS 1174 DEB	FENGYUN 1C DEB
13468	18161	0.0964023	12.1694	2018-09-07T03:10:33	COSMOS 1275 DEB	SL-8 R/B



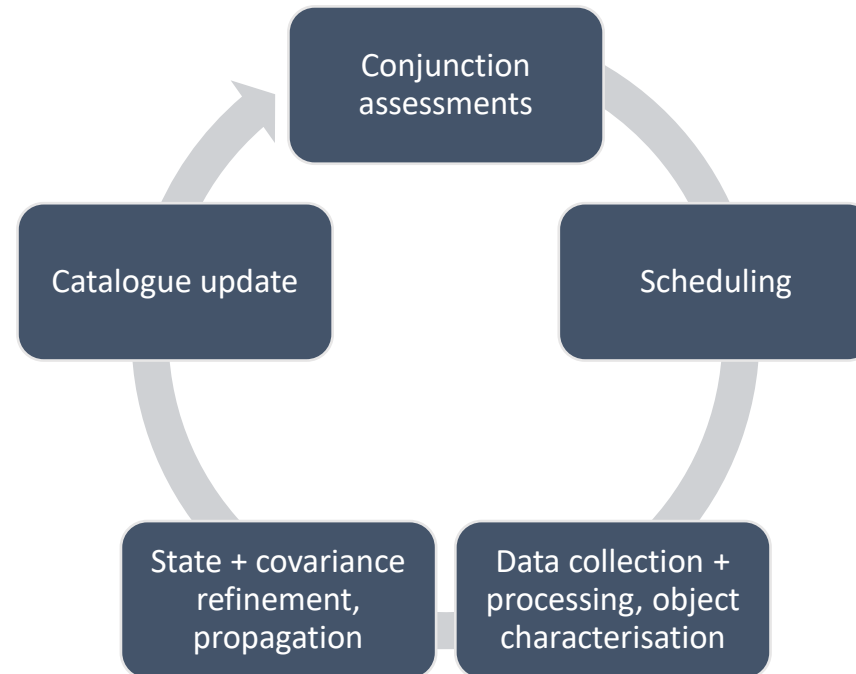
# VR visualisation





# Status

- Initial operational capability – December 2018
  - Test runs with Optus
  - Conjunction data messages produced, assessed
- Full operational capability – Feb-Apr 2019





# Questions?

## James Bennett

EOS Space Systems

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[serc.org.au](http://serc.org.au)

[info@serc.org.au](mailto:info@serc.org.au)

 [facebook.com/serc.aus](https://facebook.com/serc.aus)

 [@serc\\_au](https://twitter.com/serc_au)



Australian Government  
Department of Industry,  
Innovation and Science

**Business**  
Cooperative Research  
Centres Program

## Other RP3 research – PhD candidates

- Conservation of First Post-Newtonian Energy Integral (University of South Australia)
- Collision probability estimation for short encounter times using a three dimensional Generalized Gaussian Distribution (University of South Australia) - Hansani Thanippuli Kankanamalage
- Multivariate optimisation assessment strategies and their application to conjunction assessments (Australian National University) – Richard Samuel

