

# Development of Automated SLR Data Processing at Mt Stromlo SLR Station

Christopher Moore EOS Space Systems Pty Ltd

# **Automated Post Processing**



#### □ What?

#### Automatically...

- o input files containing CSPAD timing event epochs from ranging targets.
- o separate ranging measurements (signal) from noise.
- extract/apply system calibration data.
- o generate output files including full rate and normal points.

#### □ Why?

#### То...

- reduce (eliminate?) manpower requirements
- o improve responsiveness
- improve quality and consistency of results
- o improve productivity

## Challenges



- Manage system (pre- and post-) calibration data and apply them to SLR data in a reliable and consistent way.
- Identification of satellite returns in low S/N conditions and elimination of noise without
  - Significant signal data loss
  - Including noise (false positives)
- Developing a complex system consisting of many system components.

## Challenges



- Managing system (pre- and post-) calibration data and applying them to SLR data in a reliable and consistent way.
- Identify satellite returns in low S/N conditions and eliminate noise without
  - Significant signal data loss
  - Including noise (false positives)
- Developing a complex system consisting of many system components.



# Examples of typical ranging data.

Profits

D

× SH 49

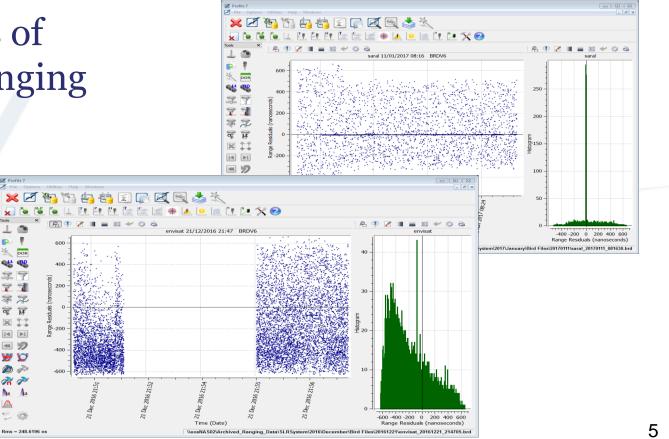
Notifice T  $\overline{\gamma}$ 

1 20 × 13 • 9 1 🗸 🖌 ه ک 2 2

he

5 8

DOR

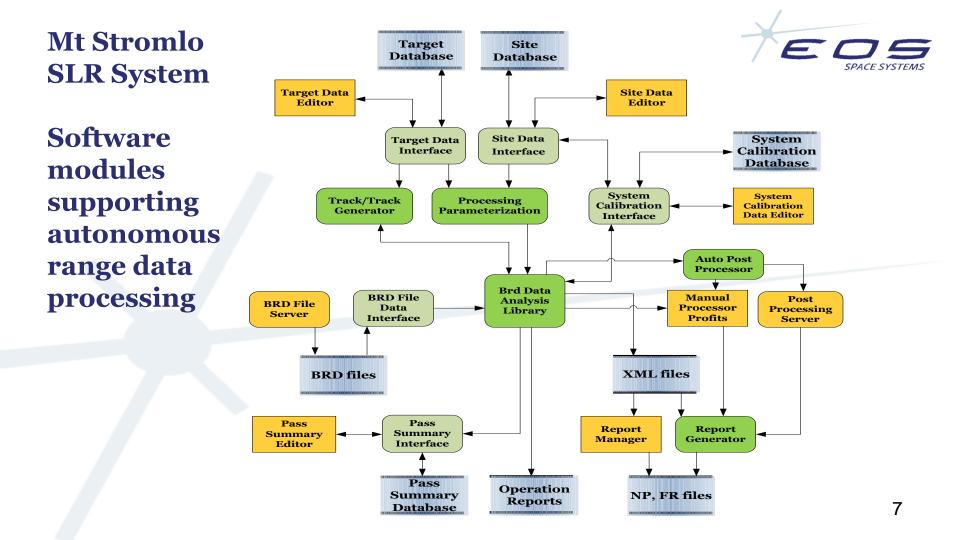


# Challenges



- Managing system (pre- and post-) calibration data and applying them to SLR data in a reliable and consistent way.
- Identification of satellite returns in low S/N conditions and elimination of noise without
  - Significant signal data loss
  - Including noise (false positives)

Develop a complex system consisting of many system components.





- Supports manual and automated processing.
- Input is binary range data (BRD) files generated by the system ranging server.
- Treats calibration target data similar to SLR data and applies the necessary system calibrations.
- Uses a configurable recipe of various data filtering and curve fitting procedures.
- Uses configurable normalized parameters.
- Output is an XML file of meta-data, full rate, normal point, mets and pointing data.
- Independent generation/publication of reports (CRD etc).



#### Supports manual and automated processing.

- Input is binary range data (BRD) files generated by the system ranging server.
- Treats calibration target data similar to SLR data and applies the necessary system calibrations.
- Uses a configurable recipe of various data filtering and curve fitting procedures.
- Uses configurable normalized parameters.
- Output is an XML file of meta-data, full rate, normal point, mets and pointing data.
- Independent generation/publication of reports (CRD etc).



- Supports manual and automated processing.
- Input is binary range data (BRD) files generated by the timing system and ranging server.
- Treats calibration target data similar to SLR data and applies the necessary system calibrations.
- Uses a configurable recipe of various data filtering and curve fitting procedures.
- Uses configurable normalized parameters.
- Output is an XML file of meta-data, full rate, normal point, mets and pointing data.
- Independent generation/publication of reports (CRD etc).

## **Binary Range Data files (\*.BRD)**



#### □ Captures raw data from the ranging server, including;

- Pass metadata (System, Target, Track data)
- Shot Events
- Mets, Cloud data
- Telescope Pointing
- Prediction Element(s)
- System State/Interlocks

#### □ Stored as serialized files using Google's Protocol Buffers.

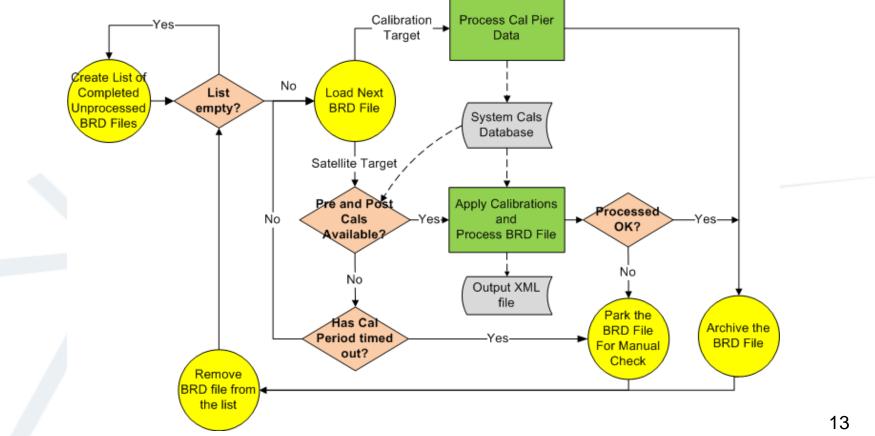
- Compact (<50% of binary files.)</li>
- Efficient (Supports fast processing.)
- Schema based( Supports backward compatibility. )



- Supports manual and automated processing.
- Input is binary range data (BRD) files generated by the system ranging server.
- Treats calibration target data similar to SLR data and applies the necessary system calibrations.
- Uses a configurable recipe of various data filtering and curve fitting procedures.
- Uses configurable normalized parameters.
- Output is an XML file of meta-data, full rate, normal point, mets and pointing data.
- Independent generation/publication of reports (CRD etc).



### **Processing Logic**





- Supports manual and automated processing.
- Input is binary range data (BRD) files generated by the system ranging server.
- Treats calibration target data similar to SLR data and applies the necessary system calibrations.
- Uses a configurable script of various data filtering and curve fitting procedures.
- Uses configurable normalized parameters.
- Output is an XML file of meta-data, full rate, normal point, mets and pointing data.
- Independent generation/publication of reports (CRD etc).



- Supports manual and automated processing.
- Input is binary range data (BRD) files generated by the system ranging server.
- Treats calibration target data similar to SLR data and applies the necessary system calibrations.
- Uses a configurable recipe of various data filtering and curve fitting procedures.

#### Uses configurable normalized parameters.

- Output is an XML file of meta-data, full rate, normal point, mets and pointing data.
- Independent generation/publication of reports (CRD etc).



## **Processing Recipe**

Filter_PostPeak      Filter_FixedWindow      Filter_LargeRMS      Filter_ConstantSignal      Filter_IteratedMean      Filter_Poisson      Filter_Polynomial      Filter_Polynomial      Filter_UndoTrend      Filter_UndoLast	Processing Steps	Options		Selected	
Show each step		Filter_FixedWindow Filter_LargeRMS Filter_ConstantSignal Filter_IteratedMean Filter_Poisson Filter_Background Filter_Polynomial Filter_Noise Filter_UndoTrend	E InsertBefore InsertAfter Remove Clear	Filter_Noise Filter_Poisson Filter_Polynomial Fit_BestPolynomial Fit_OrbitBiases Filter_Polynomial Fit_BestPolynomial Filter_IteratedMean Filter_LargeRMS	m
OK	how each step				

#### **Processing Methods**



Optimized Time Bias	Performs a recursive time bias scan to maximize the histogram peak. Identifies possible signal.	
Noise Filter	<b>r</b> Uses rectangular histogram bins (2 at a time) in time slices to remove as much sparse data as possible.	
Poisson FilterUses rotated trapezoidal histogram bins (2 at a time) in time slices to identify probable signal and rer noise. Based on Ricklefs and Shelus (1993), 8th International workshop on Laser Ranging Instrumer		
Polynomial Filter	Uses polynomials of increasing degree to filter points outside a band around the fitted curve. This technique works well if sparse noise has been removed and the signal dominates the remaining data points.	
Polynomial Fit	This selects the best polynomial to fit to the accepted data such that the polynomial degree does not exceed the maximum allowed, determined using the Akaike Information Criteria to avoid over-fitting. See Akaike H., 1974, IEEE Transactions on Automatic Control 19 (6): 716–723.	
Orbital LS Fit Undertakes a least squares fit to all the accepted data to minimize range bias and time bias. It is m signal dominates noise. This method is applied once noise is removed to estimate range and time any fitting function.		
Iterated Mean Filter	Used when the residual data is expected to be constant and distribution is probably non-Gaussian. During iteration, data on the wings of the distribution may be filtered. See Sinclair (1995) Proceedings of Annual Eurolas Meeting, Munich.	
RMS Filter	Used as a final check for excessive spread of data within time bins.	
Normal Point Generator	tor Generates normal point data according to the ILRS normal point algorithm (Sinclair, 1997).	



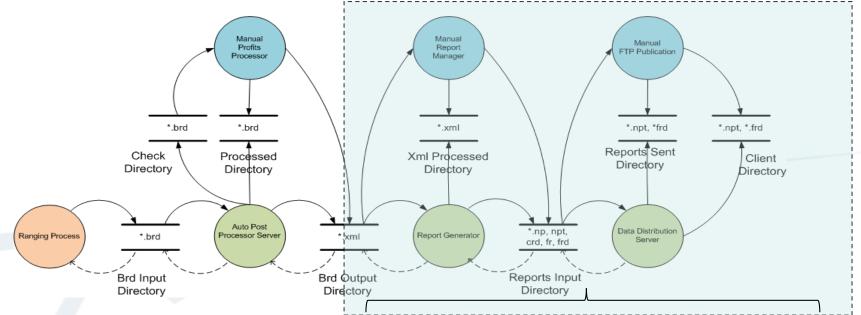
- Supports manual and automated processing.
- Input is binary range data (BRD) files generated by the system ranging server.
- Treats calibration target data similar to SLR data and applies the necessary system calibrations.
- Uses a configurable recipe of various data filtering and curve fitting procedures.
- Uses configurable normalized parameters.
- Output is an XML file of meta-data, full rate, normal point, mets and pointing data.
- Independent generation/publication of reports (CRD etc).



- Supports manual and automated processing.
- Input is binary range data (BRD) files generated by the system ranging server.
- Treats calibration target data similar to SLR data and applies the necessary system calibrations.
- Uses a configurable recipe of various data filtering and curve fitting procedures.
- Uses configurable normalized parameters.
- Output is an XML file of meta-data, full rate, normal point, mets and pointing data.

 Independent generation/publication of reports (CRD etc).

## Autonomous Report Generation and Data Management



#### Processed files managed by the Data Distribution Server

SPACE SYSTEMS



#### **Current Status**

#### On-going analysis and regression testing, including

- Differential analysis of 20000+ manually and automatically processed BRD files.
- o Identification and focus on outliers, especially false positives.
- Minimization of data loss.
- External independent analysis.



#### **Current Status**

- Productivity 90-95% vs manual.
  False positives approaching acceptable level.
  Manual processing hand-off for special targets or inconclusive results.
  - Supports evolutionary improvement.
  - Adoption at Mt Stromlo imminent.