

Introduction:

Metsähovi Geodetic Research Station in Southern Finland is becoming one of the core sites of the Global Geodetic Observing System (GGOS). The station includes all-in-view GNSS receiver, an absolute and two superconducting gravimeters, a seismometer as well as a DORIS beacon close-by. Geodetic VLBI observations have been carried out a few sessions per year and the first and second generation SLR systems were operational 1978-2005. The new modern SLR system is undergoing the final phases of becoming operational. First onsky tests are expected late 2018 and the system will become fully operational during 2019. In addition a new VGOS standard VLBI radio telescope is currently being built at the station. The new VLBI system is expected to be operational 2019 with a broadband receiver. Local ties between the sensors are carried out regularly with total stations and GNSS and new improved methods are studied to achieve GGOS's sub-mm goal.

Upgraded instrumentation at Metsähovi

SLR

- A bistatic kHz SLR-system, 50cm Rx, 10cm Tx telescopes by Cybioms-OMI
- A 15cm refractor for visual imaging Operational 2019
- Delay due to problems with motor
- controllers HighQ laser SEED diode & NLO
- peltier replaced Aug 2018 The system is designed to be modular to allow future expansions for, e.g., more powerful space debris laser or infrared observations.
- Control software by DiGos GmbH

VLBI

- A new VGOS telescope, built by MT Mechatronics GmbH
- Final phases of testing, operational 2019
- Antenna size: ~13 m dish
- □ Slew speed: >=720 deg/min
- □ Sensitivity: <=2500 SEFD
- Recording rate: 8-16 Gbps
- Data transfer: e-transfer
- Broadband receiver (2-14 GHz), built by IGN (Spain, Yebes)
- Backend: DBBC3 full VGOS capable of eiaht 4 GHz
- Recording system: Flexbuff of 480 TB



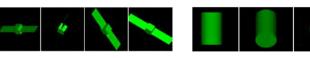
Gravity Upgraded FG5X-221 absolute gravimeter, next measurement is in Antarctica at Scott Base during November 2018, before returning back to Metsähovi Two superconducting gravimeters: iGrav-013 and iOSG-022, continuous gravity measurements since 1994

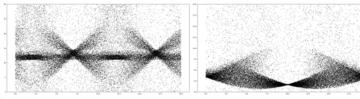
Hydrological and meteorological instrumentation for modelling gravity variations induced by local environmental effects

Ongoing space debris and and system automation research at Metsähovi

Space debris

- Feasibility study on the optimization of the SLR system for debris Possibility for a dedicated powerful debris laser
- Method & software development for spin and attitude determination from SLR and optical lightcurve observations: Lomb-Scargle; Phase **Dispersion minimization; MCMC**
- Method & software for raytracing simulations of SLR observations from an arbitrary shaped objects without retroreflectors (Wilkman 2018).
 - Below: simulations of a box-wing and cylinder shaped objects





Automatic cloud detection

- A Python 2.7 software to automatically detect clouds from an allsky image
- Image manipulation is made with numpy and OpenCV.
- The thresholding of the images is based on the Hybrid Thresholding Algorithm (HYTA) technique by Li et. al (2011), which combines both fixed and adaptive threshold methods.
- Relatively good selection results between images taken on different days compared on using only fixed thresholds.
- Next step: integration to observing software to automatically give go-nogo flags for satellites depending on the cloudiness
- Raw allsky image (left), the binary mask based on the image (middle), the mask-applied raw image (right).



References: Li C., H. and Lee C.,K.,, 2011, Minimum cross entropy thresholding,, Department of Electronic Engineering, Hong Kong Polytechnic, Hung Hom, Hong Kong Wilkman O., 2018. Ray-tracer for modeling interactions of light with space objects. Presented at AMOS 2018 Conference17-20.9.2018, Maui, USA. https://amostech.com/TechnicalPapers/2018/SSA/Wilkman.pdf Acknowledgements:

This work has been supported by the Academy of Finland as well as Finland's Scientific Advisory Board For Defence (MATINE).

