### SLR AND ALTIMETRY: A SUCCESS STORY AN A LASTING PARTNERSHIP

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J.-P. Berthias with contributions from J. Lambin and the CNES POD Team (A. Couhert, L. Cerri)

• A LONG HISTORY, A RICH FUTURE

- A FEW RESULTS
- THE EVOLVING ROLE OF SATELLITE LASER RANGING
- CONCLUSION



19th International Workshop on Laser Ranging "Celebrating 50 years of SLR", Annapolis, Md, October 27-31, 2014

### • A LONG HISTORY, A RICH FUTURE

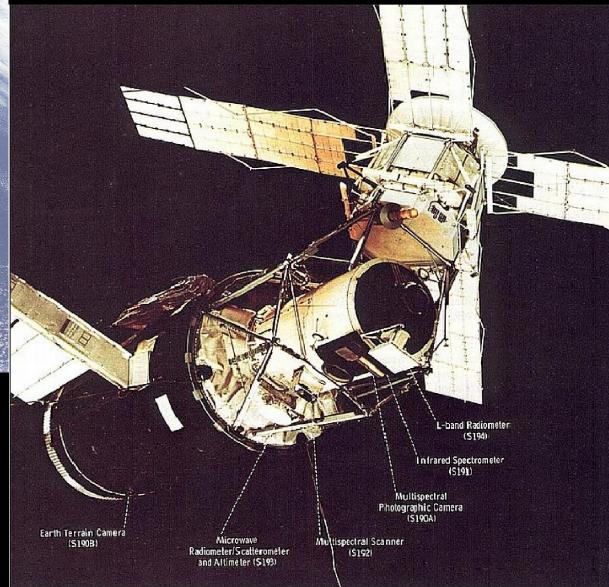
### • A FEW RESULTS

### • THE EVOLVING ROLE OF SATELLITE LASER RANGING

CONCLUSION



### SKYLAB - FIRST ALTIMETER IN SPACE 1973







N/3A HO 15 73-54

## GEOS 3

# Ring LRA around altimeter antenna

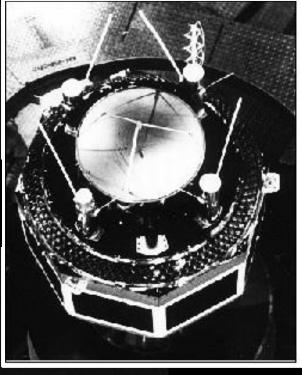
LASER RETROREFLECTOR ARRAY

NU MASS

800M

RADAR ALTIMETER

VHF ANTENNA

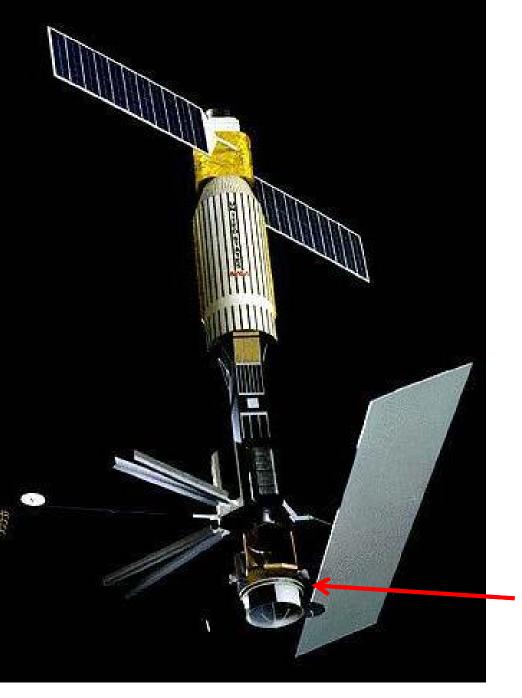


S-BAND TRANSPONDER ANTENNA

> COHERENT C-BAND ANTENNA

NON-COHERENT C-BAND ANTENNA

N/1A HO 15 73-540



### SEASAT

#### NASA/JPL-DoD mission July 1978 – October 1978

The beginning of satellite oceanography using active microwave remote sensing (altimetry and SAR imaging)

Ring LRA around the altimeter antenna; SLR was used for orbit determination and altimeter range calibration

### THE BEGINNING OF PRECISION OCEAN ALTIMETRY

Soon after the loss of SEASAT, NASA started planning for a new altimeter mission, focused on ocean surface topography, the Ocean Topography Experiment

At the same time the French Space Agency CNES started work on a solid state radar altimeter which could fly as a secondary payload on the Earth observation satellite SPOT

CNES and NASA soon joined forces to propose **TOPEX/Poseidon**, a mission dedicated to ocean topography

Poseidon-1 altimeter

The idea to fly an altimeter on a SPOT-like platform was picked by ESA and became **ERS** ....

#### But GEOSAT arrived first!





GEOSAT US Navy March 1985 – Sept. 1986 ERS-1 ESA July 1991 – March 2000

All of these missions relied extensively on SLR for tracking and Cal/Val

GEOSAT and TOPEX still used the ring LRA design of GEOS-3

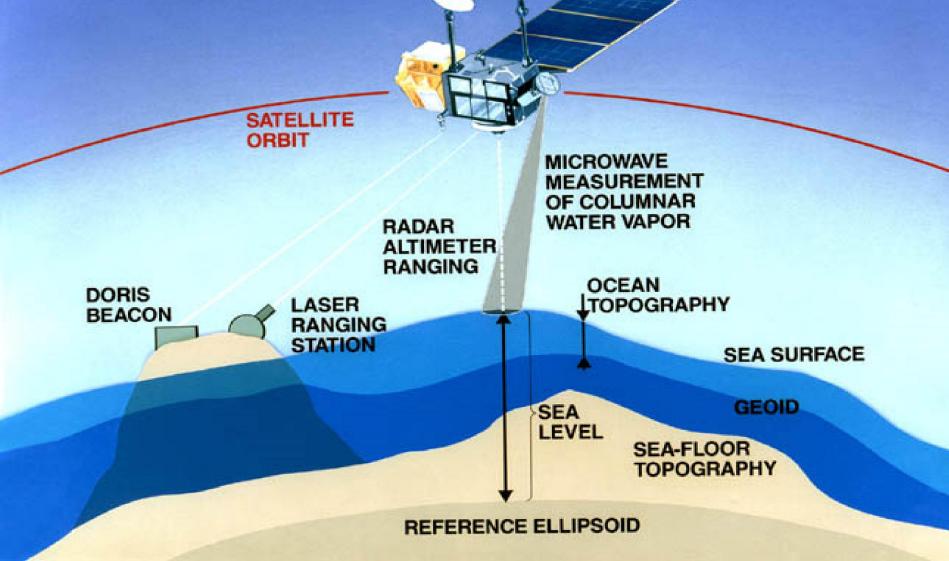


TOPEX-Poseidon CNES-NASA/JPL August 1992 – January 2006

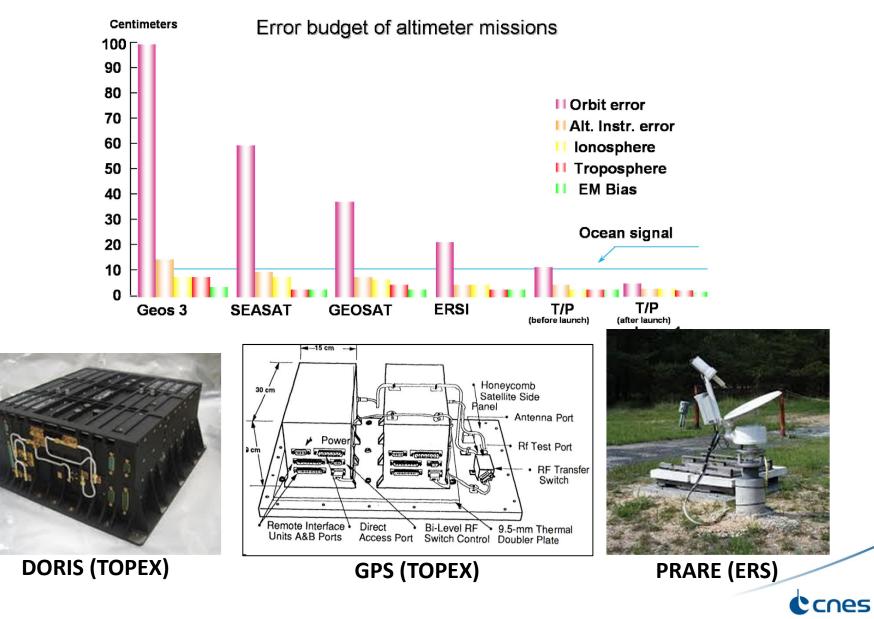
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### TOPEX/POSEIDON MEASUREMENT SYSTEM

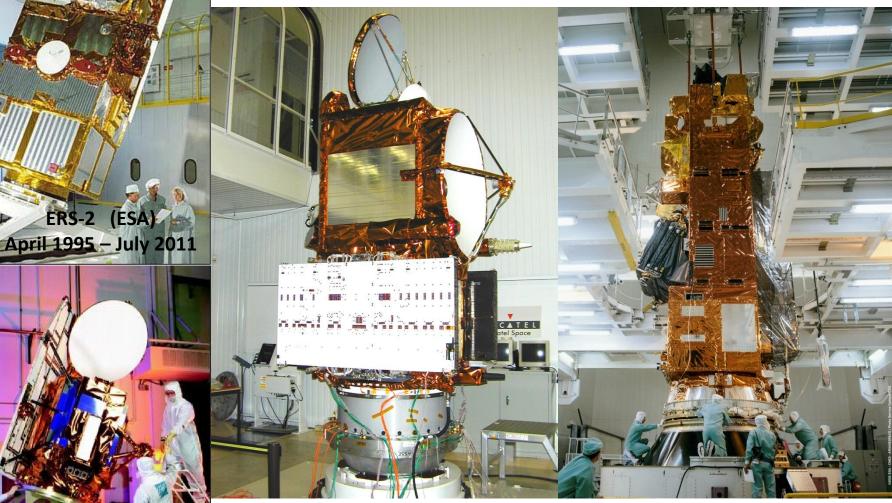




### THE TOPEX CHALLENGE: 10 CM ORBITS







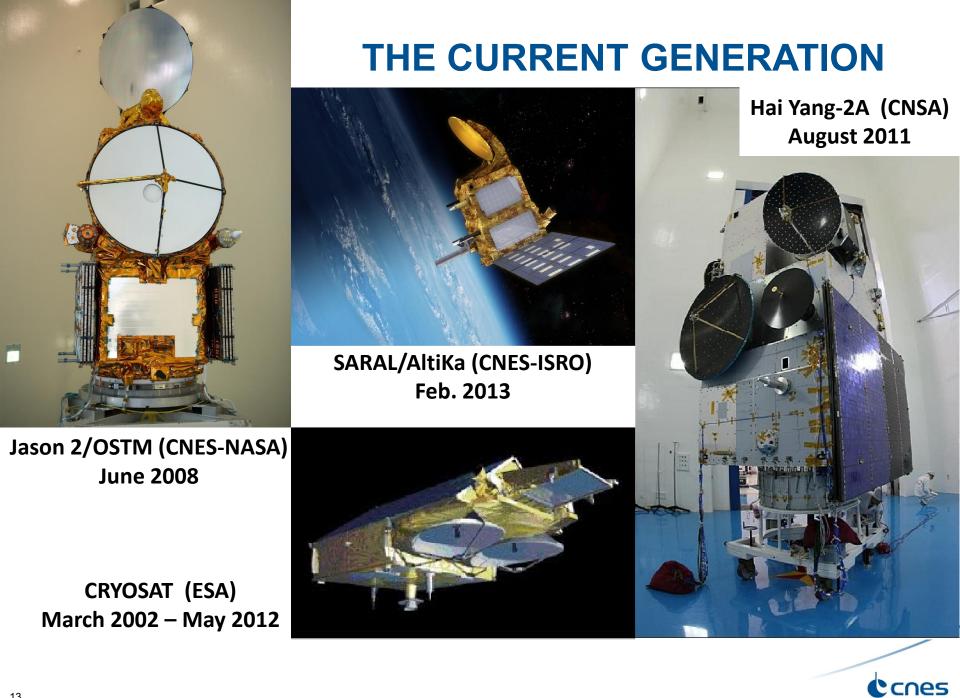
Jason 1 (CNES-NASA) Dec. 2001 – June 2013

1998 - Oct. 2003

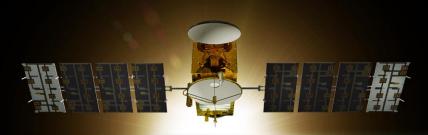
ENVISAT (ESA) March 2002 – May 2012

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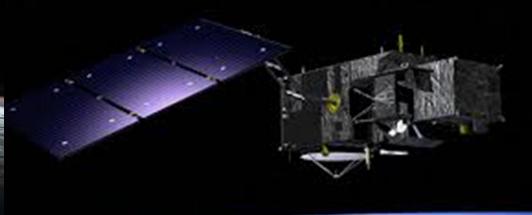


### **THE FUTURE**



#### Jason 3/OSTM (CNES-NASA-NOAA-EUMETSAT) March 2015





SENTINEL-3A / 3B / 3C (EU/ESA) 2015 / 2017 / TBD

Jason-CS/SENTINEL-6 (EU/ESA) To be decided

Hai Yang-2B / 2C / 2D (CNSA)



### • A LONG HISTORY, A RICH FUTURE

### • A FEW RESULTS

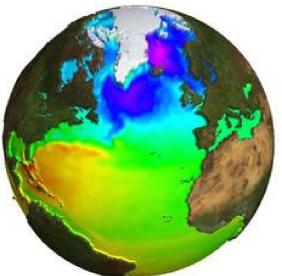
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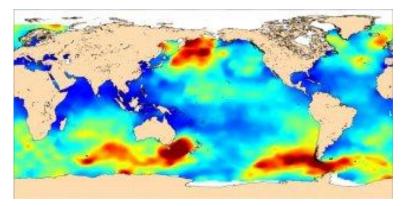


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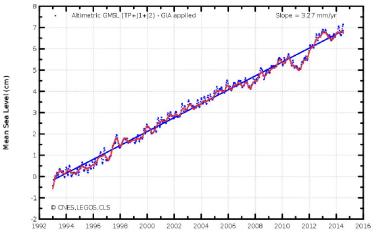
### **PRODUCTS OF ALTIMETRY**



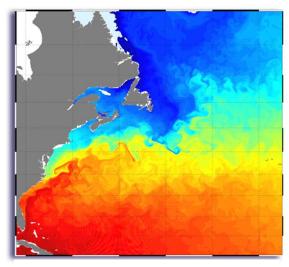
#### **Mean Sea Surface**



Wind-Wave

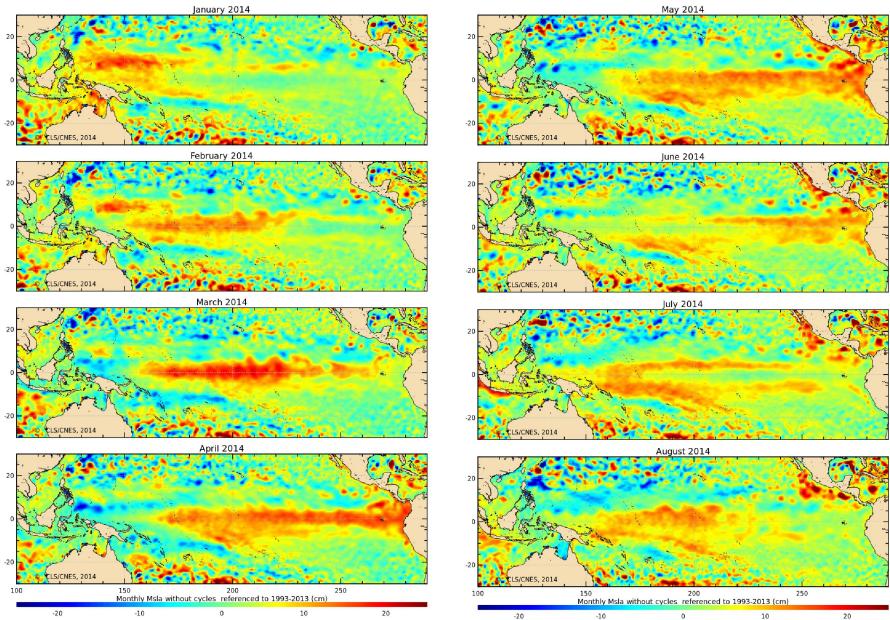


Mean Sea Level



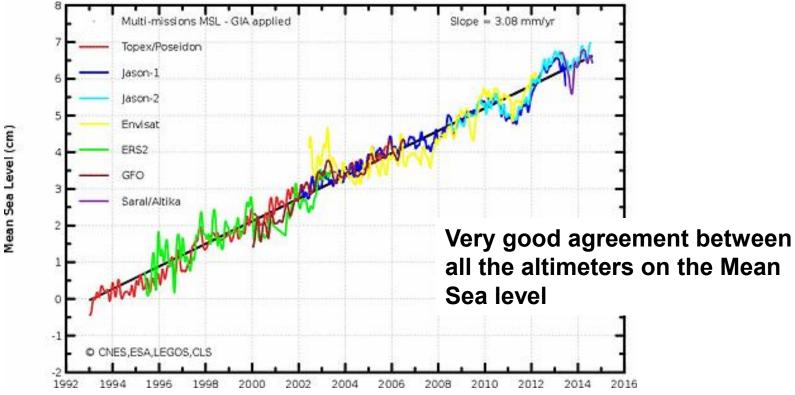
**Dynamic Topography** 

### EL 2014 "PEQUEÑO EL NIÑO"



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### **MEAN SEA LEVEL**

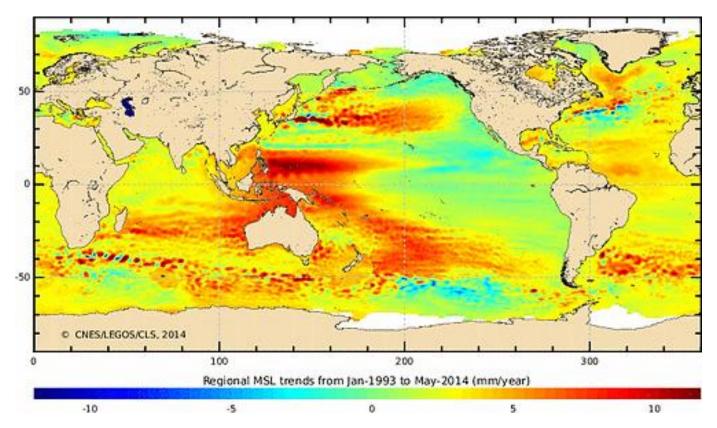


Measuring the mean sea level drift with a precision better than 1 mm/yr over the long term puts strong requirements on the orbit determination:

no drift of more than 1 mm/yr over 5 years is allowed!

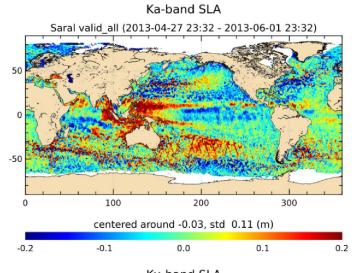
### **MEAN SEA LEVEL**

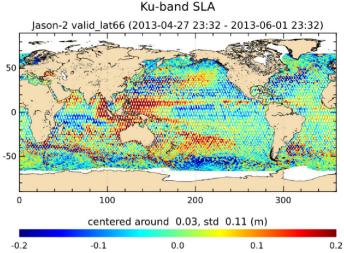
The new objective is to measure the rise in the Mean Sea level at the mm/yr not globally but locally !



This puts strong requirements on orbit stability

### KA BAND EXCELLENT RESULTS (CNES/CLS)

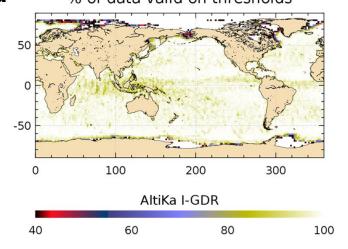




Altimeter parameter 1Hz range 1Hz SWH 1Hz Sigma0	Specifications 1.5 cm 6.3 cm 0.2dB*	Measured on ground 0.9 cm 5.7 cm NA	In flight data 0.9 cm 5 cm 0.012 dB
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\*includes the noise and the non-calibrated drift error

- First Ka band altimeter
- Meets or exceeds all mission requirements
- Impact of rain less important than anticipated % of data valid on thresholds



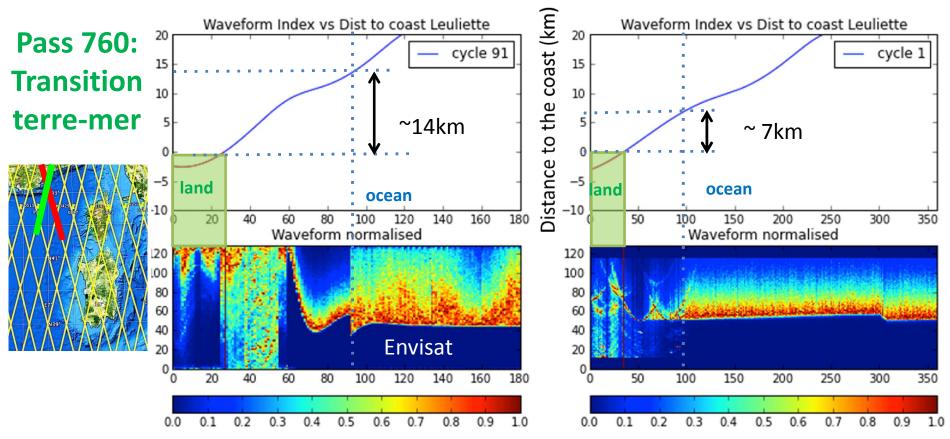
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### **BENEFIT OF KA BAND SMALLER FOOTPRINT**

**ENVISAT** 

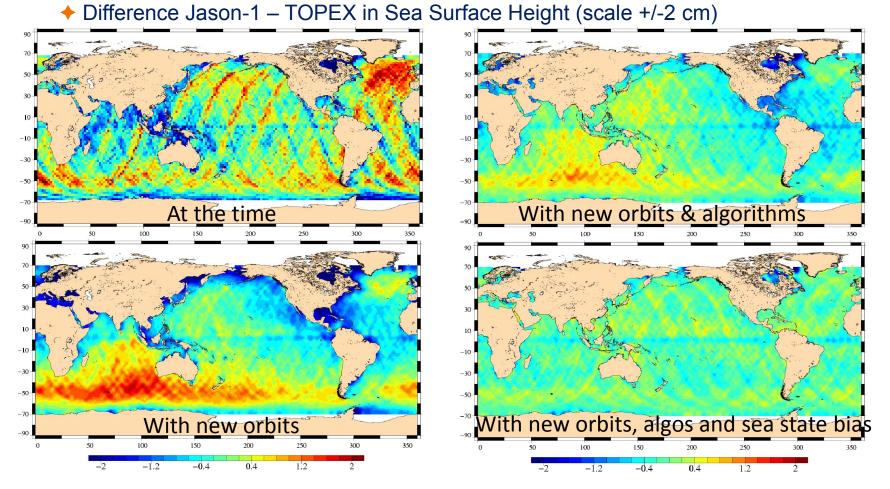
**SARAL** 

cnes



### **TOPEX/JASON TANDEM PHASE REVISITED**

6 months of tandem flight where each measurement can be compared
 5 Difference leave 4 TODEX in One Outford Light (and a 1/0 and a)



The result of years of efforts by the Science Team to improve performance

Courtesy G. Dibarboure, CLS



### • A LONG HISTORY, A RICH FUTURE

### • A FEW RESULTS

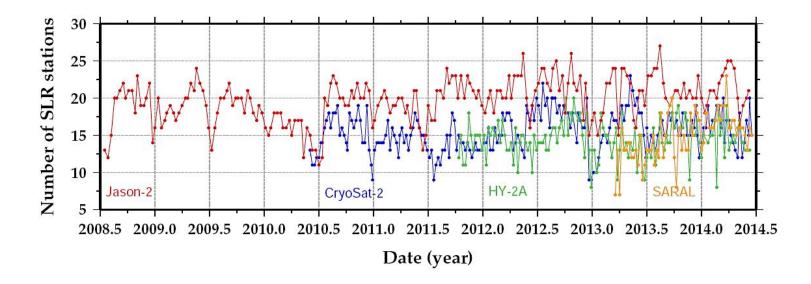
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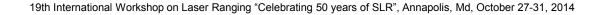


### **SLR TRACKING SUMMARY**

#### Number of SLR tracking stations per satellite



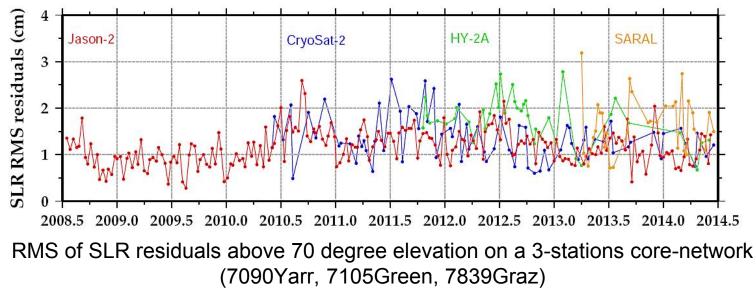
Stable SLR tracking level: about 20 stations track Jason-2 about 15 stations routinely track CryoSat-2, HY-2A and SARAL



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### **SLR AS AN ORBIT PRECISION EVALUATION TOOL**

Nowadays SLR measurements have a relatively low weight in the orbit solution => high elevation residuals provide a good estimate of the radial orbit precision

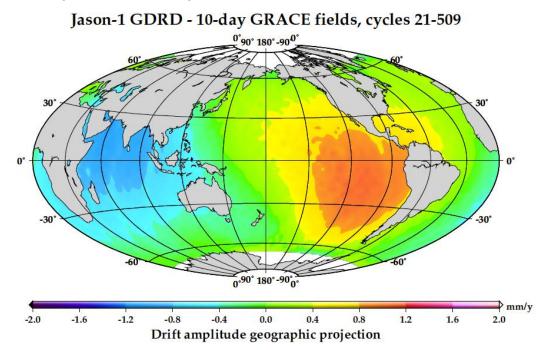


Higher Yarragadee residuals lead to increased RMS between mid-2010 and mid-2012

Current estimate of orbit radial accuracy is 1 to 1.5 cm for Jason-2 and 1 to 2 cm for CRYOSAT, HY-2A and SARAL

#### TIME VARIABLE GRAVITY INDUCED RADIAL ORBIT DRIFTS

Secular trends and aperiodic variations in the Earth gravity field which are not captured in the reference gravity models can induce radial drifts in the orbits which exceed locally the 1 mm/year requirement



These regional drifts can only be independently monitored through the use of SLR (at orbit level) or tide gauges (at sea level)

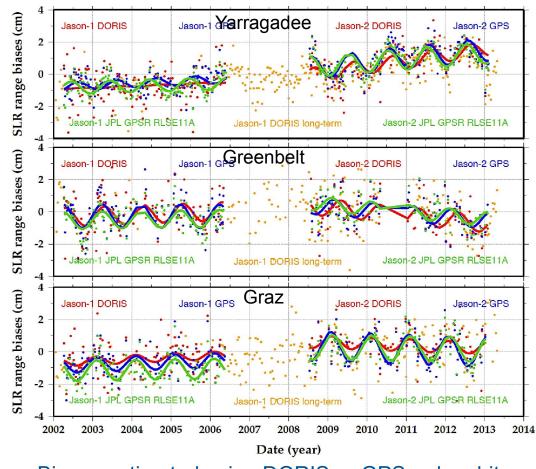
### **SLR STATIONS RANGE BIASES MONITORING**

Careful monitoring of SLR stations range biases is mandatory to use SLR as

a orbit drift monitoring tool

Drifts in biases can hide drifts in orbits

Drifts can have multiple origins (station problems, coordinate errors, etc.)



Biases estimated using DORIS or GPS-only orbits

### CONCLUSION

Satellite Laser Ranging is a natural complement of altimetry missions: like the altimeter, SLR measures the true ground-to-satellite range

SLR was initially the primary tracking system to produce high precision orbits; it is now the reference used to evaluate orbit precision and stability

Monitoring sea level rise on basin scales at the mm/year level over 5 to 10 years requires very stable orbits; monitoring this orbit stability requires stable SLR stations

