



The NAVSTAR 35 and 36 Laser Retro-Reflector Experiments

19th International Workshop on Laser Ranging 27 October 2014 Annapolis, Maryland

> Ron Beard U.S. Naval Research Laboratory Washington, DC



Early Attempts with Laser Retro-Reflector Arrays





GPS OPERATIONS







GPS PASSIVE CONCEPT







Advanced Clock Ranging Experiment (ACRE)





Original Concept:

- Use NAVSTAR Qual Vehicle for technology satellite flight
- Transmit GPS experimental signal
- Incorporate multiple new clocks
- PRARE System for independent ranging system
- VLBI Transmitter
- Laser Retro-reflector Array
- GPS Orbit
- Space Test Program support for integration and Launch



NAVSTAR 21 ORBIT RESIDUALS GPS Week 602







NAVSTAR 21 CLOCK ESTIMATE





Clock Residuals for NAVSTAR 21 comparing DMA post-fit Clock Performance with Data taken at the Naval Observatory.





AFSPACECOM SPADOC Laser Clearinghouse Waiver Response 27 Oct 1987 – blanket waiver for NASA lasers (MOBLAS 2-8, TLRS 1-4, SLR 2, Quantell YG 402 DP

NRL Ltr to GPS JPO 17 Nov 1992 Laser Tracking Experiment for GPS Satellite

GPS JPO Response Laser Tracking Experiment for GPS 12 Jan 1993

GPS JPO SMC 12 April 1993, forwarding Rockwell Int Special Study 60 Final Report, GPS Laser Tracking Experiment dtd 26 Jan 1993

AFSPACECOM to UM approving installation on Two Block IIA satellites 2 Mar 1993

IGS recognized by IAG in 1993, call for participation Feb 1991, test campaign 1992, began operations Jan 1994



LRE ESTABLISHED



Memo Of Agreement USAF-STP, GPS JPO, NRL for NCST-801 ACRE and STP Mission S93-2 and S9401 9 March 1994 (Sent out 26 Aug 1993)

UM Proposal to NRL 17 March 1993 – Three flight panels of 32 Retro's each plus a weight-size dummy panel. Two delivered in May 1993, preceded by dummy panel and followed by a third array in a few weeks. Cost \$100K

Memo Of Agreement NRL GSFC support of LRE on GPS, NRL 9/20/93, GSFC 7/29/1993

NAVSTAR 35 Launched 30 August 1993

NRL Ltr to 2SOPS Laser Tracking Experiment for GPS Satellite 3 Nov 1993

NAVSTAR 36 Launched 10 March 1994







- 32 Retroreflector cubes
- Total weight: 1.27kg
- Dimension: 8in x 10in
- Optical cross section: 20x10⁶ m²
- Return rate from MOBLAS-5 on the order of 2% at MEO
- GPS orbit at 22,000 km

Provided by Grant to Univ Maryland

Built by Russian Institute for Space Device Engineering Three panels provided Dummy Mass model for Fit check Operators Manual Engineering Manual

Integration onto Vehicle by STP



NAVSTAR 35 & 36 Laser Retro-Reflector Experiment





2SOPS PAWG 1998 (O'Toole, NSWC) SLR Residuals (cm) (December 1997 – February 1998)

| | OCS (ZAOD) | | NIMA | | IGS | |
|-------|---------------|-------|------|-----|------|-----|
| SVN | Mea n | RMS | Mean | RMS | Mean | RMS |
| 35 | -23.1 | 51.2 | -3.0 | 8.2 | -3.0 | 6.7 |
| 36 | -106. 3 | 178.4 | -3.3 | 7.5 | -4.1 | 5.9 |
| 35&36 | -71.9 | 140.6 | -3.2 | 7.8 | -3.7 | 6.2 |

Coordinated NRL experiment to investigate separation of orbital and clock errors

Non-interference with GPS Operational Control Segment

Tracking Coordinated by Air Force Laser Clearinghouse

Measurements provided by ILRS through MOA with NASA GSFC

Applications

Initial attempts for SLR-only orbits hampered by lack of daylight tracking

Comparisons with GPS systems RF observations for calibration/validation

Comparisons with Geodetic RF observations

Inclusion in Geodetic orbit determinations





Many Campaigns have been conducted since the experiment began

Goal of SLR only orbit for clock evaluation has been elusive

LRE has contributed to validation of IGS and GPS orbit determination





E. C. Pavlis, "Comparison of GPS S/C Orbits determined from GPS and SLR Tracking Data", Adv. Space Res. Vol. 16 No 12 pp (12)55-(12)58 1995, COSPAR







Table 4 SUMMARY Of SLR RESIDUAL STATISTICS (cm)

Statistics Include Data From Both Satellites With Satellite Center Of Mass (CM) Bias Solutions Carried Out In The GPS Satellite's Local Reference Frame (X,Y,Z). (3242 normal points, 273 in shadow, 2969 in sunlight)

| | GPS35 CM Adjustment | | | GPS36 CM Adjustment | | |
|-----------|--|-------|-------|---------------------|------|------|
| | Х | Y | Z | Χ | Y | Z |
| NIMA | 0.12 | 0.06 | -1.98 | -0.60 | 0.23 | 7.04 |
| JPL | -0.41 | -0.21 | 6.85 | -0.43 | 0.17 | 5.06 |
| IGS | -0.36 | -0.19 | 6.10 | -0.42 | 0.16 | 4.93 |
| | SLR Residuals Including CM Adjustments | | | | | |
| | | Mean | | | RMS | |
| NIMA Data | -0.00 | | 9.49 | | | |
| Shadow | -2.46 | | 8.13 | | | |
| Sunlight | 0.22 | | 9.61 | | | |
| JPL Data | -0.00 | | 4.61 | | | |
| Shadow | -4.49 | | 6.41 | | | |
| Sunlight | 0.41 | | 4.41 | | | |
| IGS Data | -0.00 | | 3.93 | | | |
| Shadow | -0.63 | | 4.01 | | | |
| Sunlight | 0.06 | | 3.92 | | | |

J.W. O'Toole, "Evaluation of NIMA GPS Satellite Ephemerides using NASA Laser Ranging Data", in PLANS IEEE, 1998,pp 371-378



Independent Orbit Validation









NAVSTAR 35 Residuals



| | SVN 35 Mean | SVN 35 Stdev | SVN 36 Mean | SVN 36 Stdev |
|------------|-------------|--------------|-------------|--------------|
| | (m) | (m) | (m) | (m) |
| NGA Final | -0.009 | 0.034 | 0.010 | 0.026 |
| NGA Public | -0.028 | 0.051 | -0.023 | 0.041 |
| IGS Final | -0.010 | 0.026 | 0.009 | 0.024 |
| JPL | -0.003 | 0.029 | 0.009 | 0.026 |
| BROADCAST | 0.832 | 0.477 | 0.094 | 1.308 |

13-26 Jan 2004

M. Davis, et al, NGA GPS Navigation Assessment using SLR Techniques, NRL, March,2005



NAVSTAR 36 Residuals



| | SVN 35 Mean | SVN 35 Stdev | SVN 36 Mean | SVN 36 Stdev |
|------------|-------------|--------------|-------------|--------------|
| | (m) | (m) | (m) | (m) |
| NGA Final | -0.009 | 0.034 | 0.010 | 0.026 |
| NGA Public | -0.028 | 0.051 | -0.023 | 0.041 |
| IGS Final | -0.010 | 0.026 | 0.009 | 0.024 |
| JPL | -0.003 | 0.029 | 0.009 | 0.026 |
| BROADCAST | 0.832 | 0.477 | 0.094 | 1.308 |

13-26 Jan 2004

M. Davis, et al, NGA GPS Navigation Assessment using SLR Techniques, NRL, March,2005



IGS Final Orbits





GPS PRECISE EPHEMERIDES

RMS User Range Errors for NGA Precise GPS Ephemerides







Retro-reflector Arrays

GPS, GLONASS, and GIOVE will have arrays based on similar design COMPASS has a newer design – initial ranging experience indicates considerably stronger return signal

Increased number of satellites with arrays

Network upgrades in process