Abstract number: 3095



# DOMINO – Laser Communication between SOTA, onboard SOCRATES satellite, and MEO Optical Ground Station





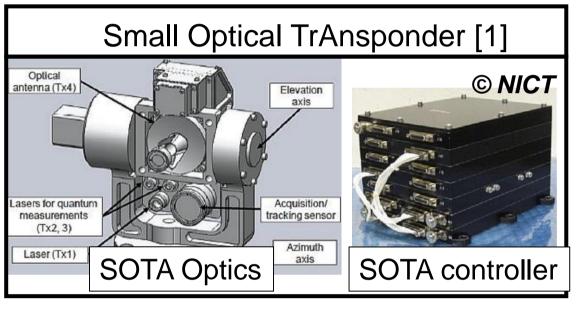
D-H. Phung<sup>1</sup>, E.Samain<sup>1</sup>, N. Maurice<sup>1</sup>, H. Mariey<sup>1</sup>, C. Courde<sup>1</sup>, G. Artaud<sup>2</sup>, J-L. Issler<sup>2</sup> (*Etienne.samain@oca.eu*), <sup>1</sup>Geoazur, Univ. Nice Sophia, OCA and CNRS, 2130 route de l'Observatoire, 06460 Caussols, France <sup>2</sup> CNES, 3CNES - French Space Agency, 18 av Edouard Belin, 31400 Toulouse, France

#### **DOMINO**

(Demonstrator for Optical teleMetry at high data rate iN low earth Orbit).

The project is conducted in collaboration between the French national center for space studies (CNES), the Cote d'Azur observatory (OCA-GeoAzur) and the Japanese National Institute of Information and Communication Technologies (NICT). GeoAzur is the project general contractor. DOMINO project aims to demonstrate the feasibility of a communication link (the establishment of 10 Mbps) between SOTA (Small Optical Transponder) onboard SOCRATES microsatellite (Space Optical Communication Research Advanced Technology Satellite), and the MeO station located at Caussols, France. The main challenges of the project are the characterization of the turbulent atmosphere and the detection at ground of the signal coming from the satellite, for the LEO Direct To Earth scenario at 1.55 µm which interest CNES for Telemetry.

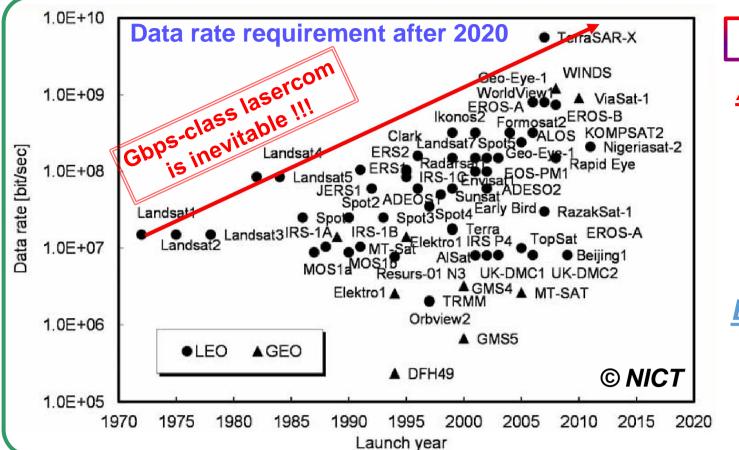
**The SOCRATES microsatellite**, 50-kg-classe satellite bus, engineered by AES, was launched (altitude = 628 km, inclination = 97.69 °) **on May 24, 2014**. The main objectives of SOTA, developed by NICT, are: in-orbit verification of acquisition, tracking and pointing performances; data acquisition of laser beam propagation at various wavelengths; and laser communication experiments with coding (NRZ).



	Downlink from SOTA		
	Issues	Tx1	Tx4
	Wavelength (nm)	976	1549
	Data rate (Mbps)	10 or 1	10 or 1
ļ	Intensity (MW/sr)	0.81	0.57
	Divergence (µrad)	500	223

## Uplink to SOTA for acquisition & tracking Wavelength (nm) 1064 ± 3 Required irradiance (μW/m²) 17 - 209

### [1] Yoshisada K. et al., "COMPLETION OF THE SMALL OPTICAL TRANSPONDER DEVELOPMENT FOR SATELLITE-GROUND LASER COMMUNICATION DEMONSTRATIONS",ICSSC 17-





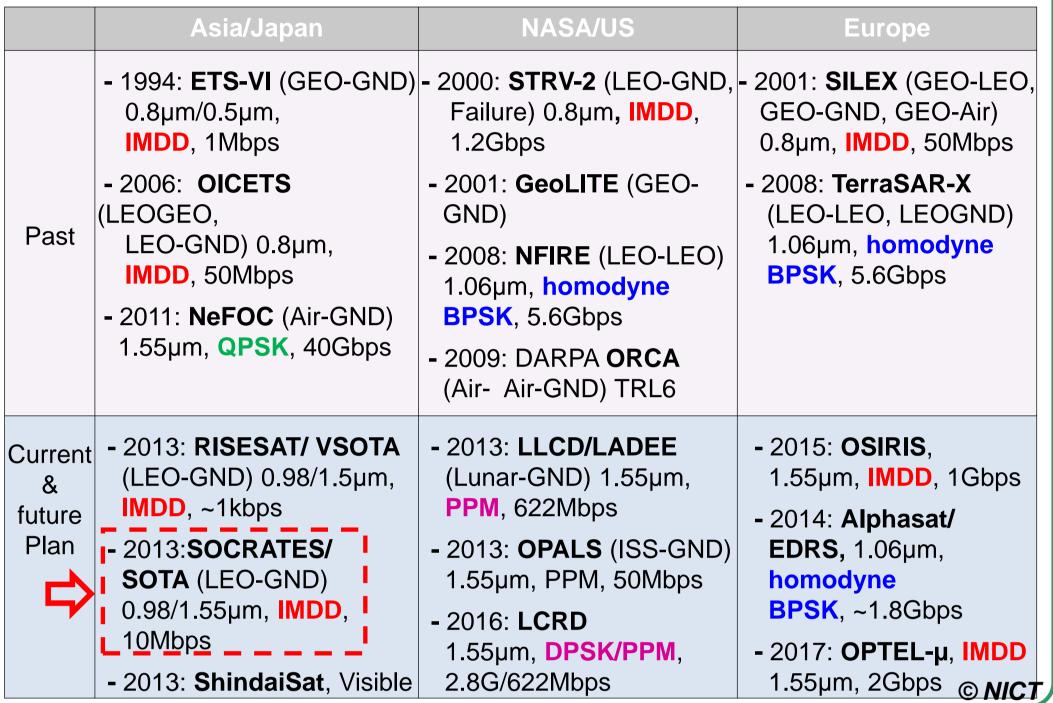
✓ low consommation

✓ greater security

#### Drawbacks

- ✓ losses & turbulences in atmosphere
- ✓ pointing & tracking

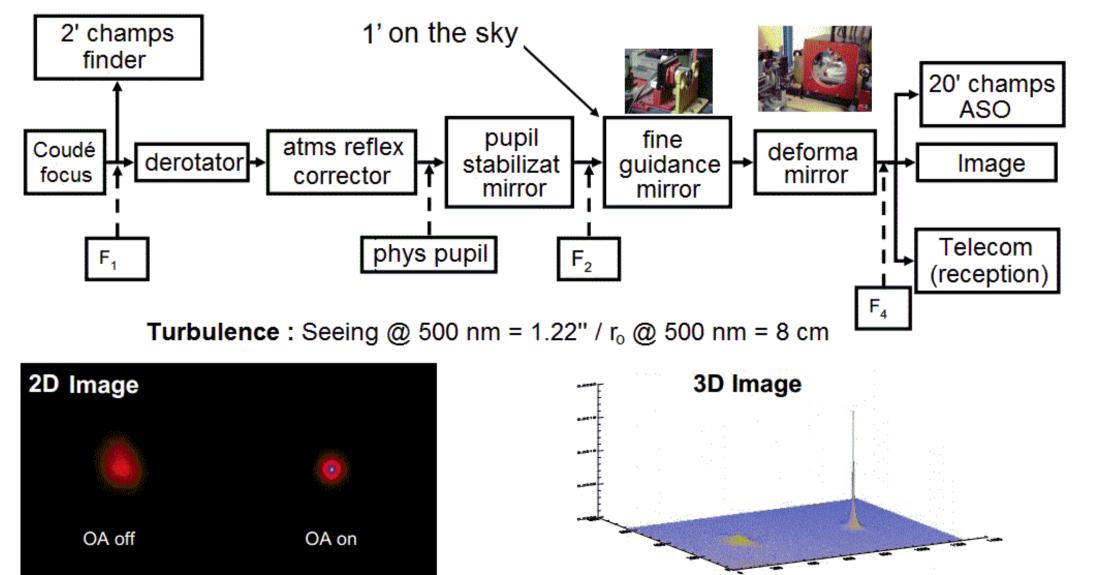
### Space-based laser communication programs

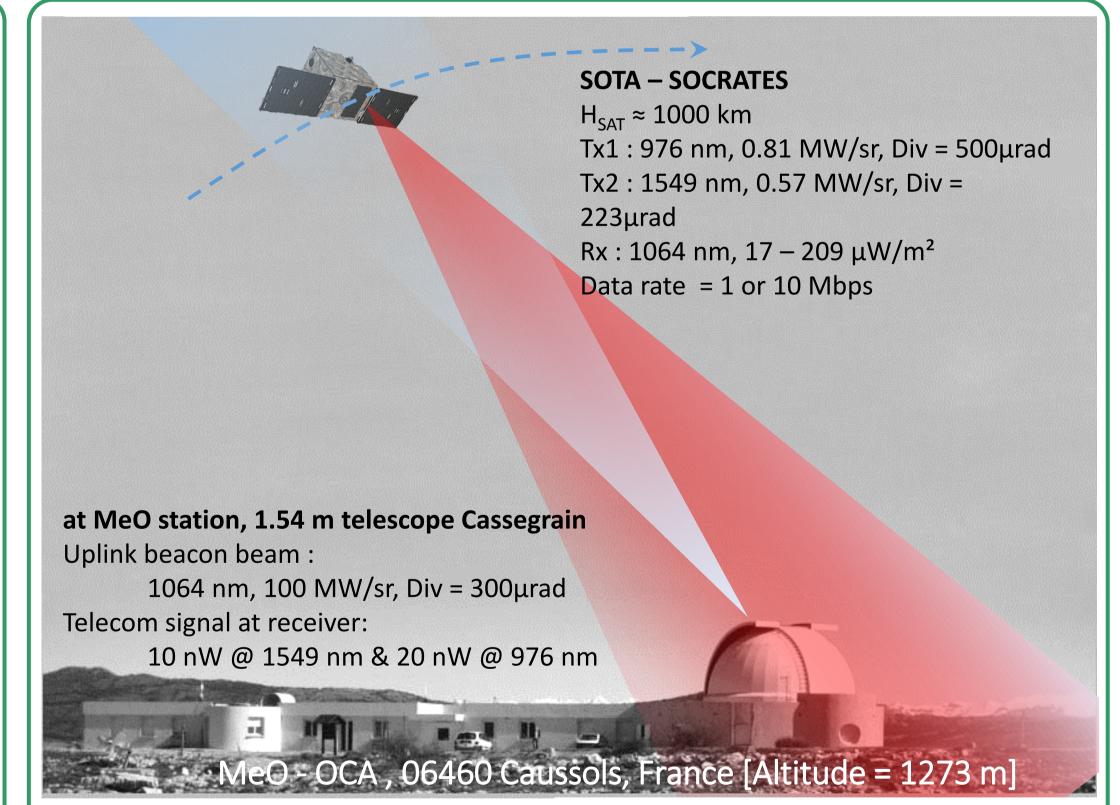


#### **Optical Ground Station - MeO telescope** 1.54 m Cassegrain Telescope type Weight of the mobile elements 20 tons Diameter of the dome 9 m 5°/s maximum speed < 1 arcsec pointing accuracy **Motorization** – Dome pointing precision 0.01 arcsec **Pointing stabilization** 0.2 arcsec at 1000 s 200 mm plat fold mirror type & diameter Coudé: M4 -M7 bandwidth 350 nm to 1200 nm (Laboratories) damage threshold 10 J/cm<sup>2</sup> for ns pulse **Equivalent Focus length** 32 m Field of view 5 arcmin Station altitude 1273 m

2.2013.

The MeO station, installed on an Alt-Az mount, is dedicated for researches on Lunar laser ranging, satellites laser ranging, time transfer, astronomy and laser communication. It comprises an important experimental setup for laser ranging and also an adaptive bench well suited to analyze the turbulent atmosphere (figure below).





#### Configuration of the MeO station-to-SOTA laser link

For a given passage of the satellite over the MeO station, MeO points the satellite according to the predicted orbital information. As soon as the uplink is acquired, the satellite turns on the transmission laser (Tx1 or Tx4) and points back the beam in the Meo orientation. When both uplink and downlink are acquired and slaved together, the communication link is established.

**Geoazur** together with the industrial partners will design the demonstrator instruments. It comprises

- the uplink beacon;
- the downlink receiver;
- the equipment for atmospheric turbulence analysis
- and the software to control the whole experiment.

We also implement a closed loop system to slave the pointing of the telescope on the SOTA beacon signal. This work also includes the integration of a SOCRATES searching algorithm.