

#### 13-0207

# Engineering Changes to The NASA SLR Network to Overcome Obsoleteness, Improve Performance and Reliability

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Paper presented at the International SLR Workshop, Fuji Yoshida, Japan,, Nov 11-15, 2013

Acknowledgement: The author gratefully acknowledges the contributions of ALL hardware and software engineers as well as the management involved in the NASA SLR program for their contributions.



# NASA SLR – Network of 8 Stations, 3 Types



- 1. Moblas 4 Monument Peak, CA, USA
- 2. Moblas 5 Yarragadee, Australia
- 3. Moblas 6 Harteebeesthoek, South Africa
- 4. Moblas 7 Greenbelt, MD, USA
- 5. Moblas 8 Tahiti, French Polynesia

1. MLRS – Fort Davis, TX, USA



TLRS 3 – Arequipa, Peru
TLRS 4 – Haleakala, Maui, USA









# NASA SLR – Network (Eng, Data) Analysis

#### • Scope Engineering Sustainability Issues

- 1. Degree of Obsoleteness;
- 2. Complexity of changing hardware, software (including remote locations);
- 3. System Down-time;
- 4. Cost of Material and Labor;
- 5. HW, SW Standardization;
- 6. Timing of technology / subsystem changes;
- Understand/ Establish Station Data Performance (in particular Range Bias)
  - 1. Work with Analysts to understand Range Bias of each NASA station;
  - 2. Establish what is station unique vs. outside of the station;
- Understanding the Risk Profile
  - 1. Completed NASA Risk chart;
  - 2. Near Term Objective: Lower Network (Operations + Performance) Risks



# M4 - Multi year RB, TB Trends Analysis







# **NASA SLR – Engineering Overview**

- MLRS built in 1960s; Moblas 4-8 built in the late 1970s; TLRS built in the mid 1980s;
- Over the years through the 1990s, significant Improvements were made to the various subsystems to maintain the best SLR performance;
- Only modest improvements/ replacements were performed since then, which has placed the network in a precarious position for maintainability/ sustainability;
- There are subsystems that were maintained over the years with great difficulty and now have come to the point of extreme difficulty to sustain;
- Modern/newer systems have a much shorter lifecycle than the older hardware (and hence software) and is often forgotten in the budgeting and planning process;



- Major areas of concern/ deficiencies
  - Servo-control & servo-Drive system
  - Slip ring assembly
  - Time of Flight Measurement
  - Time and Frequency
  - Miscellaneous electronics
  - Real-time Controller (see also MLRS poster paper)
  - Safety (see also poster paper)
- Minor areas of concern/ deficiencies
  - Laser and its subassemblies
  - Detectors



#### NASA SLR : OLD Servo-control systems

- Moblas Telescope servo-control system
  - Contraves MPACS, 22 bit resolution system, 1970s Vintage
  - Performed very well over the years
  - No change in technology since the 1970s (due to cost, complexity, downtime)
  - NO replacement PCBs available for the Electronics;
  - Considerable time, cost, (and travel) for caring for this old electronics
  - Previous efforts to change this either did not work / scrubbed for funding reasons
- TLRS Telescope servo-control system
  - Mostly an in-house developed servo-control system, 1980s vintage;
  - similar problems as that of Moblas









Modular Precision Angular Control System

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## NASA SLR: NEW Servo-control

- Servo Control system
  - Cybi Servo-Controller;
  - 24+ bit resolution;
  - Sub-arcsec RMS at sidereal rates; arcsec at higher rates;
  - High Quality Surface Mount Electronics to support Inductosyn, Resolver Encoders;
  - Modular maintenance strategy;
- Applicability
  - Moblas or TLRS or any other telescope;
  - <u>2 Moblas to be upgraded initially; M7 to be followed by TBD;</u>



## NASA SLR – OLD Servo-Drives

- Telescope AZ, EL servo-drives
  - Contraves, 1970s Vintage;
  - High average power linear amplifiers;
  - NO replacement PCBs available;
  - Recently found high power transistors capable of replacements of the old ones after significant amount of trials;
  - circuit changes needed to rectify the new characteristics;
  - still interface board level reliability and availability issues remain;



## NASA SLR – SERVO DRIVES: OLD vs. NEW



#### **OLD UNIT**



**NEW UNIT** 



# NASA SLR – OLD Slip Ring

- Slip ring, AZ & EL;
  - Manufacturer: Wendon, 1970s vintage;
  - AZ, EL slip rings transfer signals from a moving frame to a static frame and vice versa; 210 circuits, of which only 70 are used;
  - Brush blocks in contact with a platen provide the ohmic contact:
  - wear and tear leads to large ohmic differences and causes signal glitch /drop;
  - Telescope pointing problems as a result
  - High BW signals transmitted via hanging cables that move with the moving frame;



### NASA SLR – Old vs. New Slip ring











- Time Interval Counter;
  - Manufacturer: Hewlett Packard HP 5370 of 1980s vintage;
  - 20 ps resolution; ~20ps single shot RMS;
  - For Lageos 2 lab measurement, a stack of 5 specially selected, optically calibrated, and optimized TIUs provided sub-mm stability and accuracy (short measurements);
  - Data transfer time: >50ms restricts Lageos to 5 Hz, HEO to 4 Hz and GEO to 2Hz;
  - Performs well, but Obsolete





# NASA SLR – Time of Flight via Event Timer

#### NEW Event Timer

- Manufacturer: Cybioms
- 1 ps resolution; ~2 ps single shot RMS;
- Initial Deployment in M7 concurrently with HP5370;
- Proven performance based migration to Station Operations;
- Deployment in MOBLAS & TLRS: 1-6 months



#### - XL-DC GPS disciplined Rb:: Timing & Frequency Outputs

- manufactured by True Time (now Symmetricom),
- Performs well, but Obsolete No longer manufactured by Symmetricom
- TCG: Timing Outputs ONLY
  - manufactured by Trak Systems
  - Generation of timing signals from 10 MHz by alternate approaches required;
  - 4 Hz, 5 Hz, 10Hz, and 20 Hz needed for station firing, interrupts, gates;
- Distribution Amplifier: Frequency Outputs ONLY
  - Can be consolidation into the clock;
  - Old and Obsolete



#### **NASA SLR – Old T&F standards**

#### XL-DC GPS disciplined Rb



Time Code Generator



**Distribution Amplifier** 



## NASA SLR – New T&F standards

- Xli GPS disciplined Rb: Timing & Frequency Outputs
  - manufactured by Symmetricom,
  - Better than 30ns RMS accuracy to UTC;
  - Better than 10<sup>-12</sup> frequency accuracy;
  - Consolidation of additional timing functions into XIi;
  - 10Hz, and 20 Hz needed for station firing, interrupts;
  - Preliminary maser comparison performed in the SLR lab





## **NASA SLR** - Radar Modifications

- Refurbished + modified the network radar to a standard configuration;
- Added several new tests to strengthen the system testing and validation
- New tests to monitor radar false alarm;
- Maintaining reduced modes of operation
- Effort to enhance the safety awareness and reliability;



# **NASA SLR - TLRS** Modifications

- Remove the mount wobble with a Cybioms enhanced motor casing assembly design; T4 replacement completed; T3 to be completed;
- Replace the mount operator with a combination of Camera + ADS-B RECEIVER for aircraft monitoring;
- Replace the rotating Obsolete TR switch with a static one, which will also improve PRF from 5 Hz to 10Hz for all satellites;
- Replace TIU with Event Timer;





# **NASA SLR – MLRS** Modifications

- Laser Modifications; lab work completed for a 150 mJ (532nm) laser
- Radar Refurbishment;
- Laser and Radar changes to happen simultaneously;
- High sensitivity Optical camera;
- Real-time Controller (Randy Ricklefs has completed this already; see poster paper in this conference)

NASA SLR- Projected improvements to Data Quantity/Quality



- With the ET deployment, the network as a whole will transition to 10 Hz Operation on ALL satellites; Laser can be optimized best for the 10Hz operation;
- This will improve the Data Quantity in the NPT as well as the Data Quality of the Normal point;
- Quality of the NPT (Precision and Range Bias) will be further enhanced by the use of the ET;



### NASA SLR: Modifications & Improvements Summary

- 1. Network sustainability  $\rightarrow$  Increase station availability to perform SLR
- 2. Enhanced reliability and stability  $\rightarrow$  Continuous flow of Data;
- 3. Improved Data Performance Data Quality (Precision & Accuracy) and Quantity
- 4. Reduced cost of operation  $\rightarrow$  Reduced Sustaining engineering, Logistics, Travel