

# Timing System for the Laser Altimeter for Planetary Exploration Technology Demonstrator

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# General Goals

- Technology demonstrator of a Compact Laser Rangefinder applicable in future space projects :
  - Mercury planet altimetry
  - Lunar altimetry and surface mapping
  - on-board optical transponder(s) for Earth orbiter(s)
  - airborne range finder
  - ground based Satellite Laser Ranging (SLR)
- Desired altimeter parameters:
  - one meter ranging precision (no costly interpolators)
  - multiphoton approach
  - diode pumped laser, ns pulses
  - modular construction
  - existing / available technology

# Application

- Technology demonstrator of a Compact Laser Rangefinder
- modular construction
- based existing / available technology
- test bench operation at (any) Satellite Laser Ranging site
- reduced timing resolution (ns- pulse altimetry!)

# Schedule & responsibilities

July 31 st	decision, proposal, quotation	CTU Prague
August 31st	DLR acceptance, contract	DLR
October 30	first version operational	CTU Prague
November	on-site testing	CTU / DLR
November 30	delivery	CTU
December 15	integration at DLR	CTU / DLR

# Altimeter Timing System Characteristics

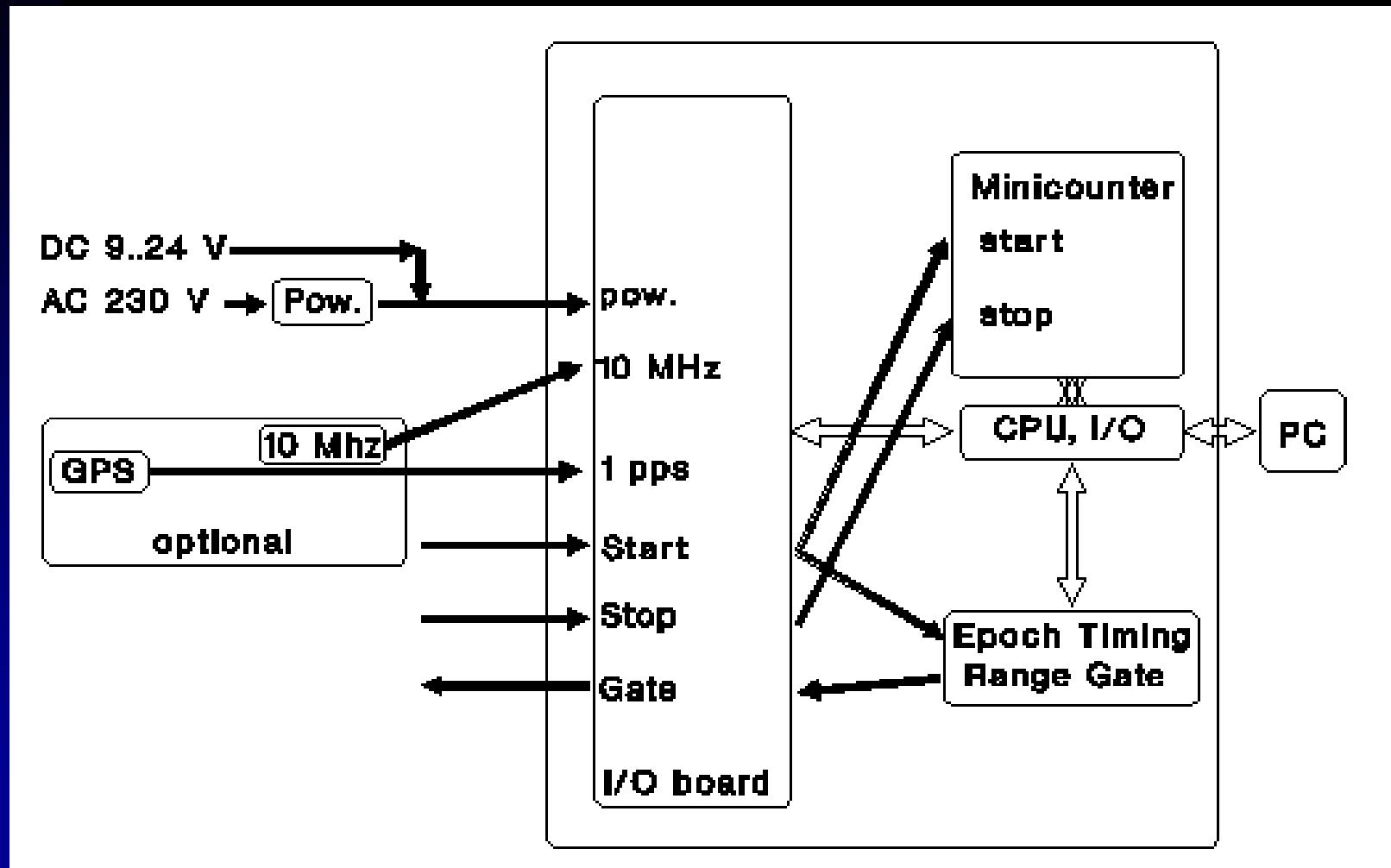
- GENERAL
  - universal timing system for laser ranging with sub-ns resolution
- FUNCTIONS
  - determining the epoch of laser fire
  - measuring the time-of-flight of the laser pulse
  - generating the range gate pulse for the echo signal detector
  - data acquisition and process control.
- PROPERTIES
  - compact, low power (battery operated), low cost
  - based on field - tested components HW & SW
  - simple to integrate into final device

# Altimeter Timing System Concept

- Based on existing P-PET hardware and software concept, the Dassault modules are replaced by integrated TDC chips .
- The timing system consists of the range counter module, the epoch timing and range gate generator module, the control processing unit, the input / output circuits and of the power supplies.
- The entire control logic hardware, epoch timing, range gate, and input/output board is based on the FPGA (ispGAL) programmable logical arrays.

This ensures the maximum device flexibility and upgradability.

# Timing System Technology Demonstrator Block scheme



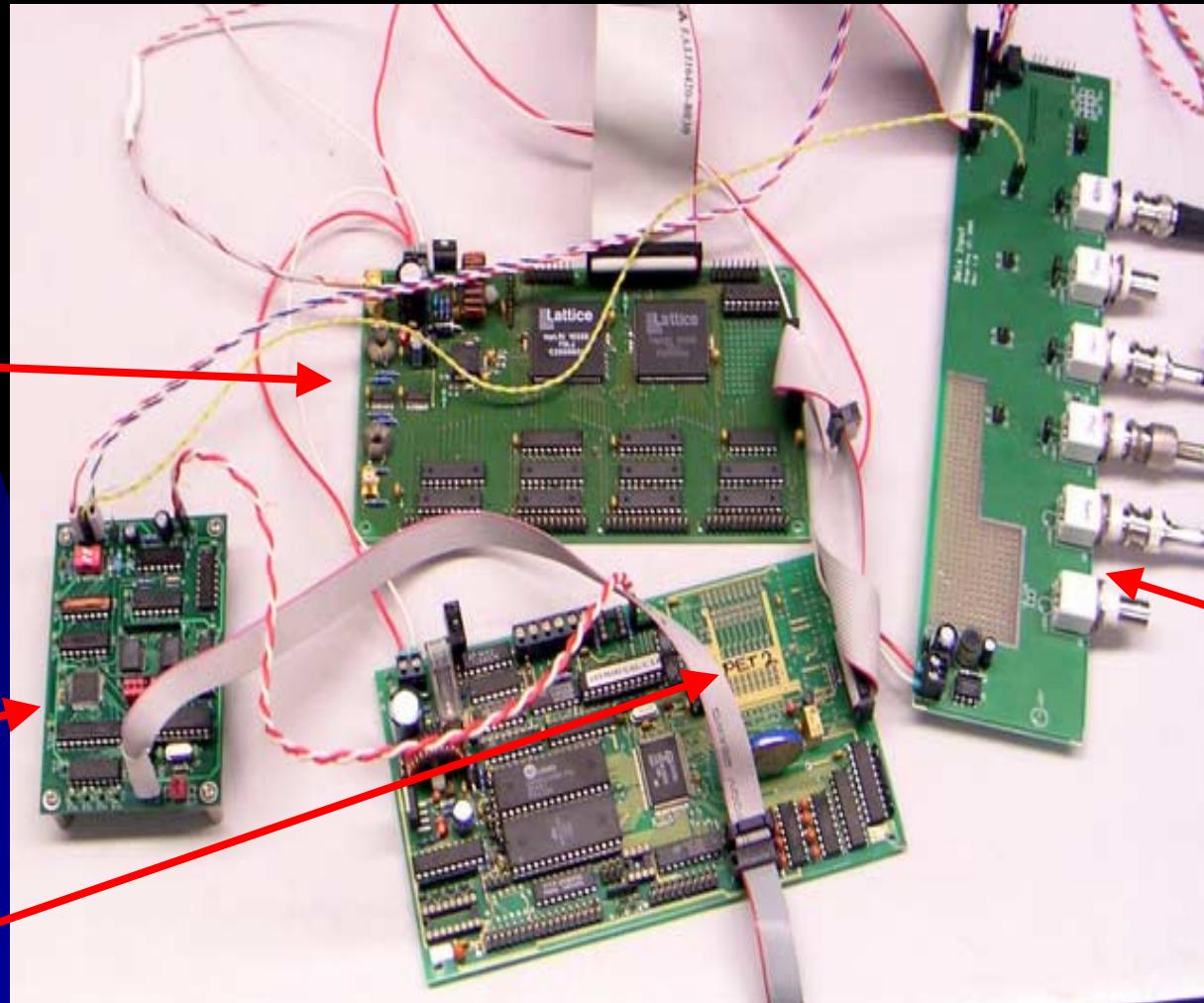
# Timing System Technology Demonstrator Electronics boards

Range gate logic  
PET 2 version

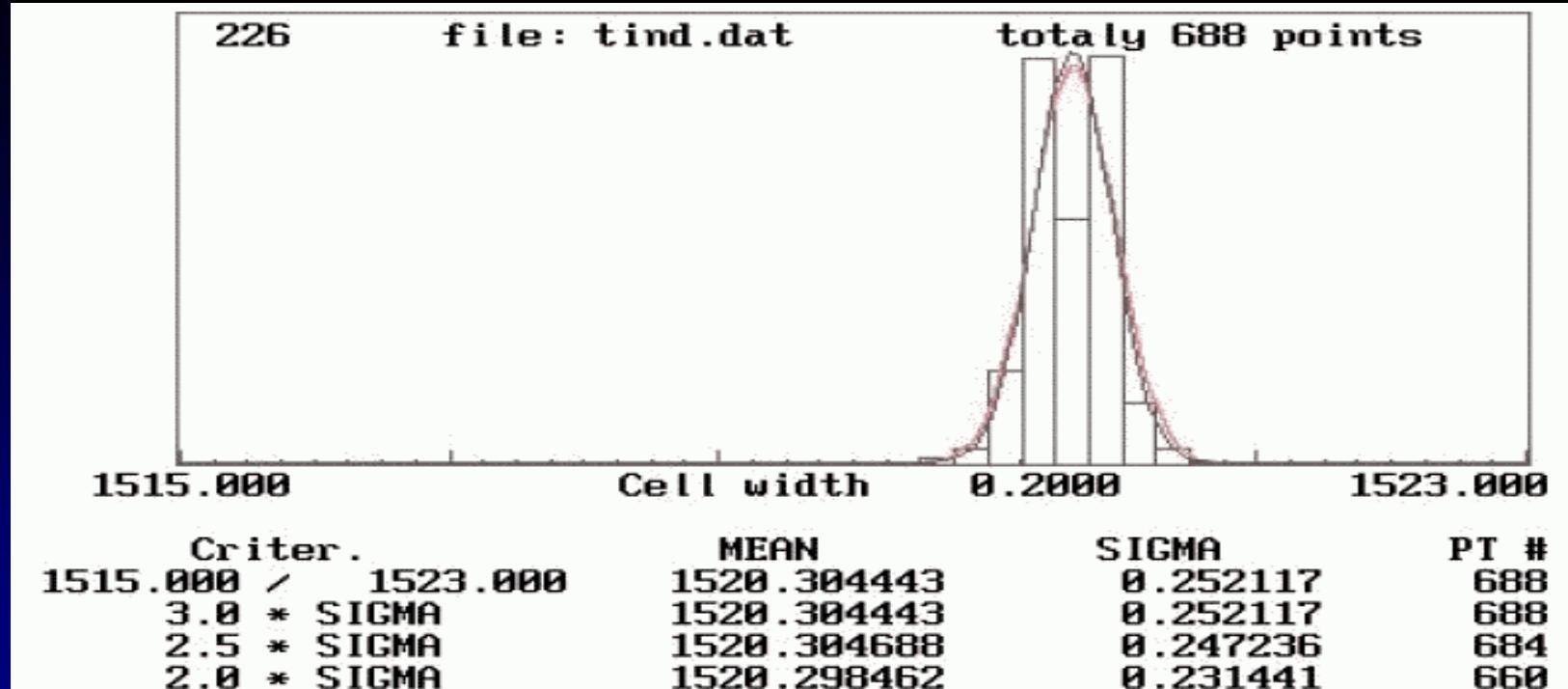
TDC timing board

CPU board  
PET 2 version

I/O  
board



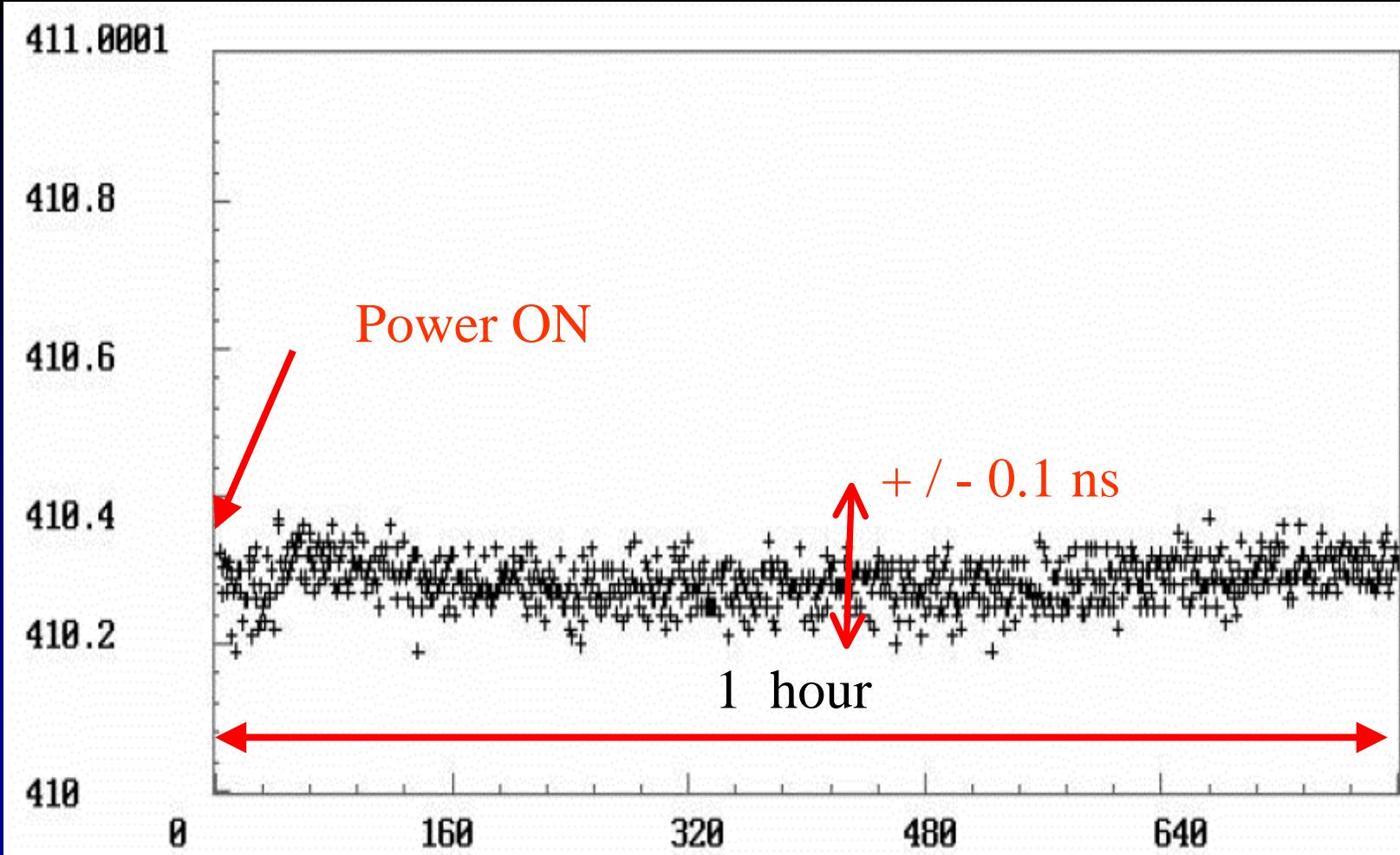
# Timing System Technology Demonstrator Temporal resolution



measured time 1.52  $\mu$ s  
the timing resolution of 0.25 ns  
normal data distribution

# Timing System Technology Demonstrator

## Long-term temporal stability



Jirousek, Prochazka, Hamal, Fedyszynova, Michaelis, Yang, Huang, Canberra 2006

# Timing System Technology Demonstrator Parameters

- universal timing system for laser ranging with sub-ns resolution



- resolution, precision                            0.25 ns, 0.25 ns rms
- non-linearity, stability                        < 0.1 ns, < 0.1 ns/hour
- range gate delay,width                        40 ns steps
- repetition rate                                  24 Hz max.
- mass    2.5 kg
- power    DC 9-38 V, 7 VA  
    > 3 hr operation on AA cells (8x)

# Demonstrator Timing System Technology Summary

- the universal timing system for laser ranging:  
ground-ground, air-ground and ground-satellite  
with sub-ns resolution has been developed and tested
- simple to implement:  
SW package identical to PET devices
- based on tested technology and components  
development period < 3 months      :-)
- In perspective the Altimeter Timing System may be applied  
in deep space laser transpoder experiments