15th International Laser Ranging Workshop

Korean Plan for SLR System Development

2006.10.

Hyung Chul Lim

Korea Astronomy and Space Science Institute



-



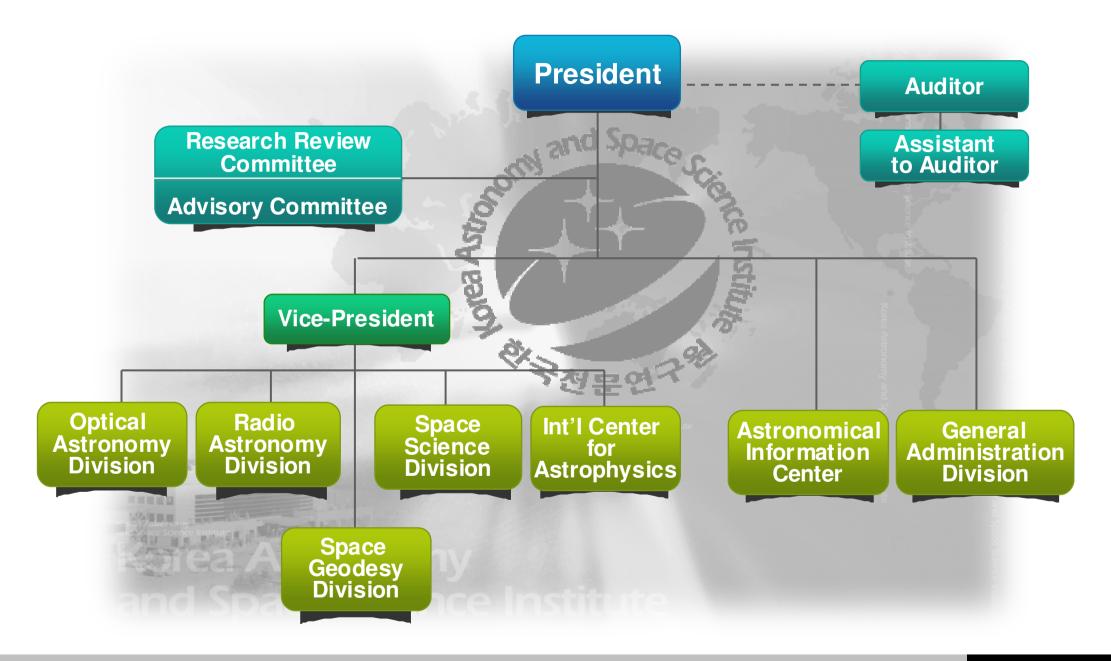
1. Introduction of KASI

2. Present Status of Korea

3. Plan of SLR System Development

4. Future Plan of Space Geodesy





KASI Facilities in Korea



GPS Stations



KASI Headquaters

KVN Yonsei Radio Astronomy Observatory

- 4 -

• 1m x 2

• 2.8m

• 1m

Sobaeksan Optical Astronomy Observatory



Taeduk Radio Astronomy Observatory KVN Ulsan Radio Astronomy Observatory Bohyunsan Optical Astronomy Observatory

KVN Tamna Radio Astronomy Observatory

Global KASI

KASI Facilities in Korea





KASI Facilities in Overseas



 Robotic telescope in Mt. Lemmon, Arizona

- 1m reflecting telescope
- Fully automated robotic telescope

- Robostic Telescope with Wide Field
- All Systems are controlled by remote site
- Survey of NEO and Variable Stars, Satellite Optical Tracking

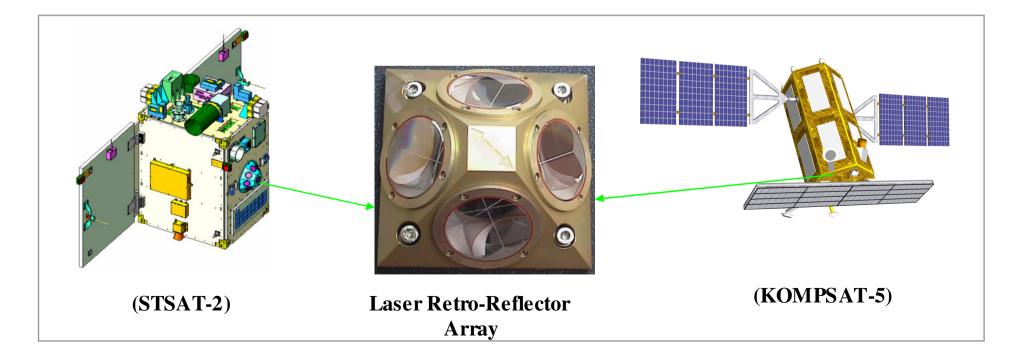
Mt. Lemmon Optical Astronomy Observatory

Australia Station

South Africa Station

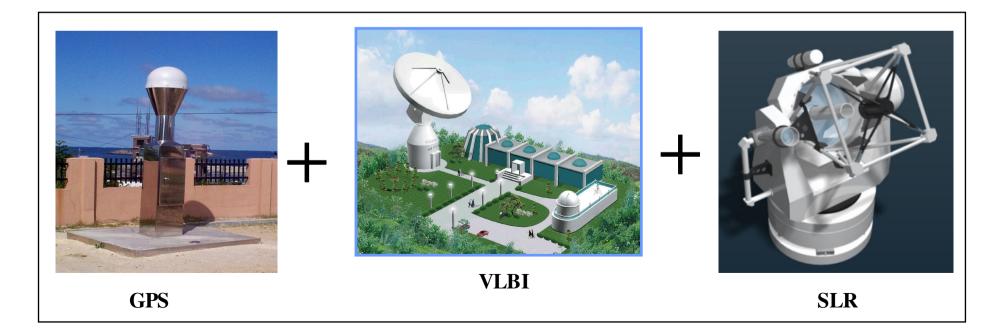
Present Status of Satellites with LRA

- No SLR Station in Korea
- Two Satellites with the LRA(Laser Retro-reflector Array)
 - **STSAT-2**(2007) and KOMPSAT-5(2009)
 - Tracking System which can determine the Precise Orbit

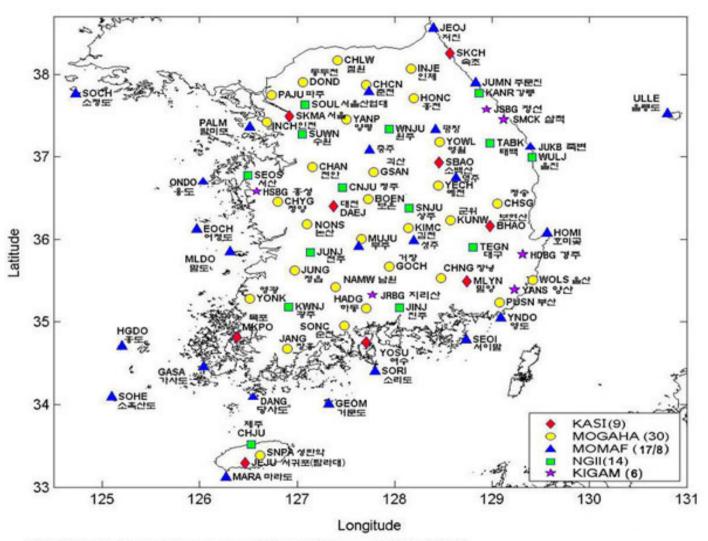


Present Status of Space Geodesy

- No Fundamental Station in Korea
 - ITRF and ICRF Coordinate, EOP, Polar Motion, LOD, etc.
- GPS Station (about 80) and VLBI Station (3) in Korea
 - Crustal movement, Geodetic survey, mapping
- KASI wants to construct the Fundamental Station



Korean GPS Network



한국천문연구원 Korea Astronomy and Space Science Institute (KASI)

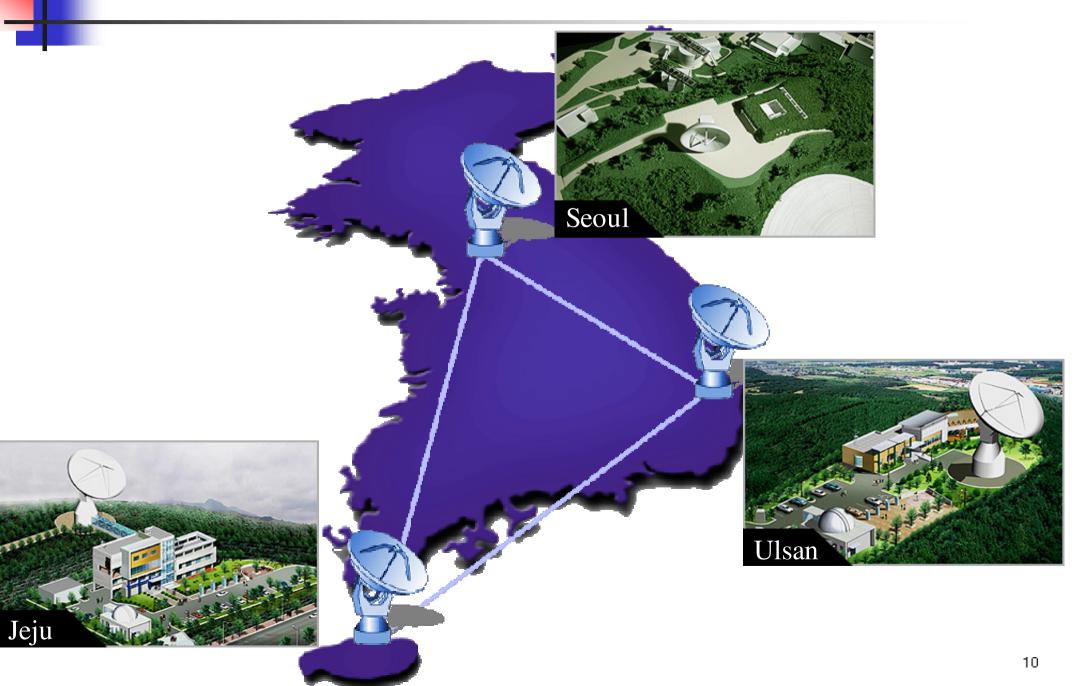
행정자치부 Ministry of Government Administration and Home Affairs (MOGAHA)

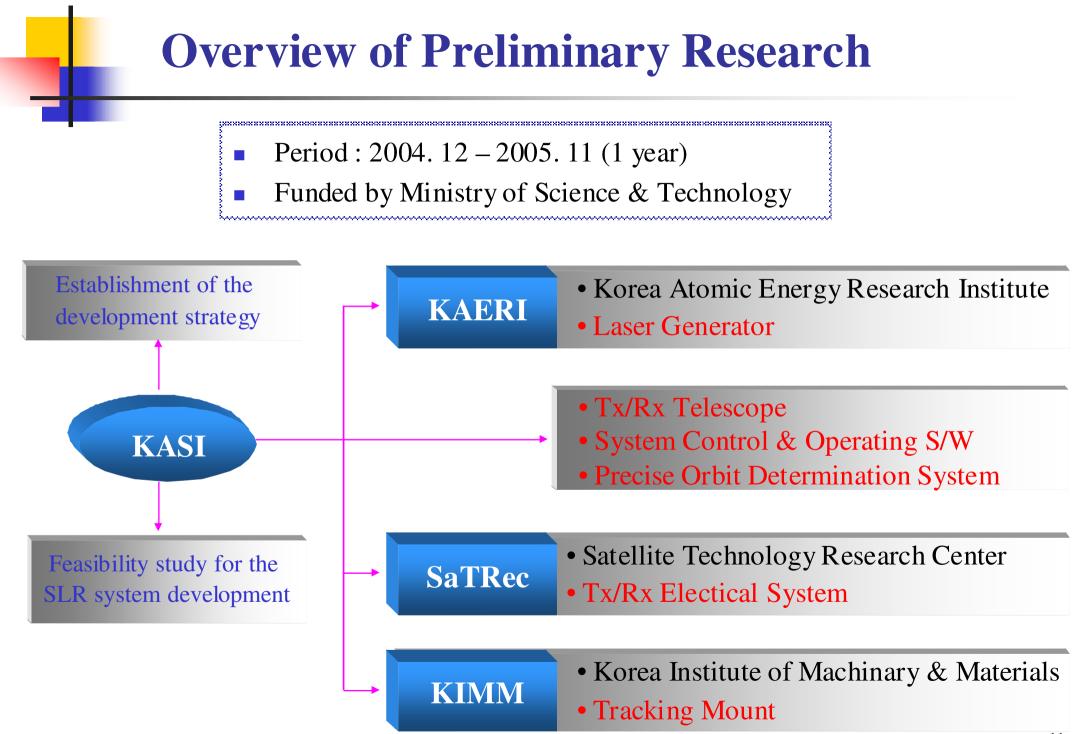
해양수산부 Ministry of Maritime Affairs and Fisheries (MOMAF)

국토지리정보원 National Geographic Information Institute (NGII)

한국지질자원연구원 Korea Institute of Geoscience and Mineral Resources (KIGAM)

Korean VLBI Network



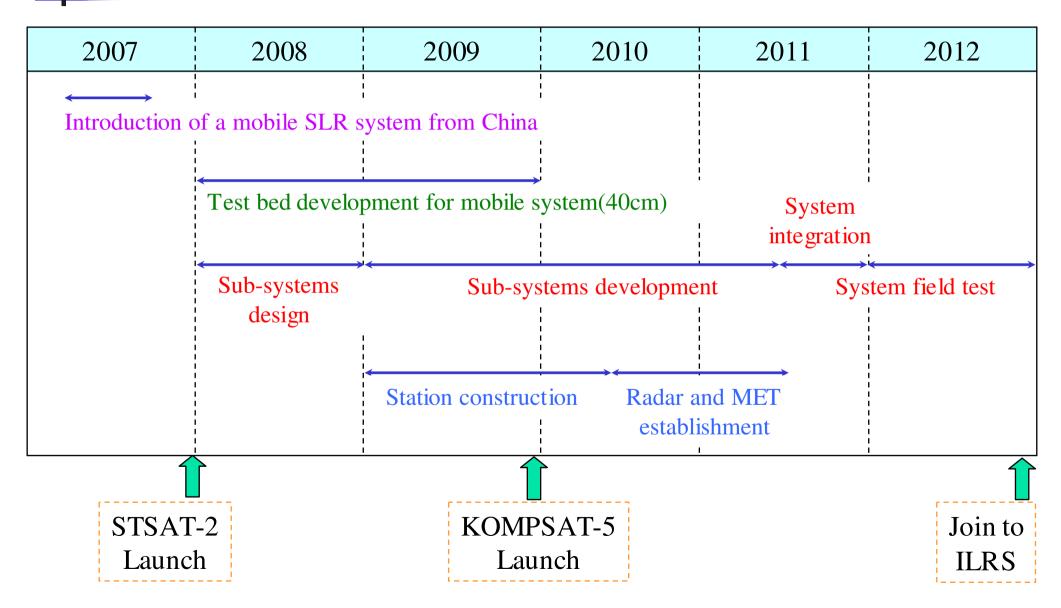


Strategies for SLR System Development

- Final Goal : One Mobile(40cm) & One Fixed SLR system(1m)
 - Development Period : 5 years
 - Mobile system : 2 yrs
 - Fixed system : 5 yrs
 - Subsystem Development (3.5 yr) + SI (0.5yr) + Test Operation (1 yr)
 - Funded by government side
 - Participants

- KASI and other government institutes : system development
- Universities : research on the application of SLR system
- Foreign Cooperation
 - Subsystem development, System integration, Test operation
- Applications
- Satellite Tracking(precise orbit determination), Space geodesy

Time Schedule for SLR System Development



System Requirements

Tracking Coverage

- Possible to track satellites in the <u>altitude of 25,000km</u>
- STSAT-2, KOMPSAT-5, GPS, Galileo Satellites and so on

Ranging Accuracy

- <u>Lageos : 10mm(SS), 1-2mm(NP)</u>
- GPS and Galileo : 20mm(SS), 3-5mm(NP)
- Ground Target : 3mm(SS), 1mm(NP)

Automatic Operation

- All system can be controlled from the remote site
- Aircraft detection using radar and automatic observation according to the schedule

Etc

- Daylight tracking
- Optical tracking of the space launch vehicle (if possible)

Future Plan of Space Geodesy

Joining ILRS(2012) SLR Construction(2008-2012) Project Plan(2005-2006)



Joining IVS (2010) KVN Geodetic VLBI (2001-2007)

IGS Analysis Center(2008)

至

IGS Global Data Center(2005)

Thank You!