

# Status of the NASA Satellite Laser Ranging Network













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## David Carter NASA Satellite Laser Ranging Program Manager

NASA Code 920 Goddard Space Flight Center Greenbelt, Maryland USA

Contributors: Howard Donovan, Daniel Nugent, Donald Patterson, Loyal Stewart Honeywell Technology Solutions Incorporated Lanham, Maryland USA

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# NASA SLR Meteorological Measurement System Upgrade



## **Old Meteorological Measurement System**

#### **Comprised of 2 Separate Devices**

- Paroscientific Barometric Unit Automated
- Sling Psychrometer Manual

Drawbacks

- Temperature and Humidity Measured Once per Hour
- Temperature and Humidity Entered Manually
- Possible Data Entry Anomalies
- Inefficient use of System Operator



# New Meteorological Measurement System

#### **Comprised of 1 Device**

- Paroscientific MET 3
- Totally Automated
- Measurements Made and Recorded every 10 seconds
- NIST Certified Calibration
- Accuracy
  - Temperature £ 0.5 degree C
  - Pressure £ 0.1 millibar
  - Humidity  $\pm 2\%$



## MET 3 GGAO Field Deployment







## NASA SLR Network MET 3 Installation

SLR 2000	July	1997
TLRS-4	June	1998
TLRS-3	November	1998
MOBLAS-6	August	1999
HOLLAS	September	1999
MLRS	September	1999
MOBLAS-5	September	1999
MOBLAS-8	September	1999
MOBLAS-7	February	2000
<b>MOBLAS-4</b>	April	2000



# NASA SLR MOBLAS Encoder Upgrade



- A new encoder system was introduced this year by the manufacture Brashear LP that could be easily adapted to replace the system currently used in all MOBLAS systems.
- Increasing difficulties in maintaining the old systems due to parts obsolescence, non- existent spares, and frequent failures make this upgrade necessary for dependable network operations. (Current encoder systems have been in the field for over twenty years).
- The upgrade would duplicate the existing encoder data format and *not require* any software changes to the current servo controller.
- Total material cost per station for an encoder upgrade ~\$20K.



#### **Current System**

- Model 30J Modular Precision Angular Control System (MPACS)
- 12.25 inch high rack mounted chassis
- System uses outdated analog/digital circuits comprised of discrete components.
- Position Output: Parallel 21 bit (0.62 arc second) binary output per axis at a 20PPS rate.
- Transducer Excitation Signals: Two channel- one inductosyn, one resolver per axis
- Position Input: Two channel one inductosyn, one resolver per axis
- Power: 110Vac

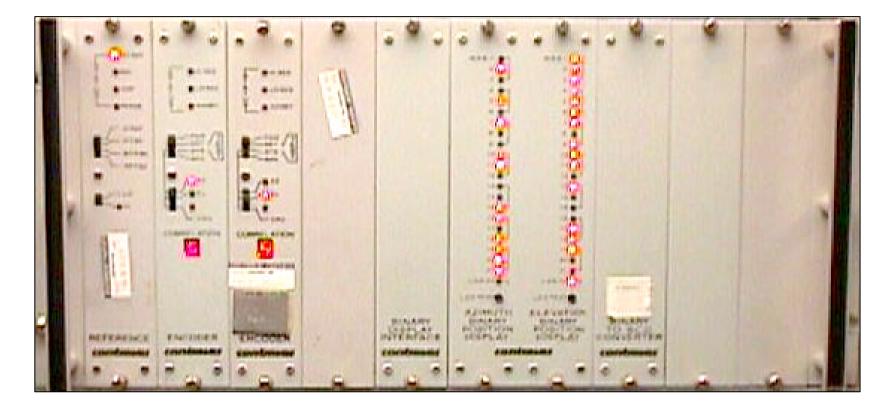


#### **Upgrade System**

- Comprised of two sub-systems:
- Two Axis Converter Modules (ACM) and a serial to parallel data converter chassis (SPC). The ACM interfaces with the inductosyn and resolver transducers and outputs serial position data. The SPC accepts the serial data from the ACM and converts it to a parallel format exactly the same as the MPACS produces.
- SPC Specifications:
- Manufacture Honeywell
- 1.5 inch high rack mounted chassis
- Position Input: Two serial RS485 1Mbaud channels (azimuth and elevation axis)
- Position Output: Parallel 21 bit (0.62 arc second) binary output per axis at a 20PPS rate.



#### Current System Modular Precision Angular Control System - MPACS





#### Upgrade System Axis Converter Module - ACM





# NASA SLR Transportable Laser Ranging System Computer Upgrade Project (TCUP)



## TCUP

#### **Old MIK-11/23 Controller Computer**

- Outdated 1980 Computer Technology
- Replacement Parts Are Difficult to Obtain
- Repair Facilities Are No Longer Available

#### **New Pentium Controller Computer**

- PC Compatible Pentium 166 MHz Controller Computer
- Similar to Moblas Controller Computer
- Enhance the TLRS Controller Capabilities
- Reduce Sustaining Costs
- Guarantee Component Replacement Availability
- Increase Network Standardization



# TCUP

- Upgrade Integration and Verification Testing performed on TLRS-4 at the Goddard Geophysical and Astronomical Observatory in Greenbelt, Maryland
- Included Consolidation and Replacement of Other Subsystem Components Within the Mount Control and Data Acquisition Areas of the System Necessary to Facilitate the Integration of the New Controller Computer



# NASA SLR Transportable Laser Ranging System 4 Mount Observer Automation (MOA)



### TLRS 4 MOA

- Replacement of Mount Observer with 3rd generation Laser Hazard Reduction System
- Incorporation of Laser Interlock to automate abatement of transmitted laser energy
- Incorporation of Surveillance Camera for remote monitoring
- Remote monitoring sensors protect access to Instrumentation van interior and roof
- Enables TLRS 4 for Single Operator Automation



### TLRS 4 MOA





### **Other NASA SLR Network Upgrades**

- GPS Steered Rubidium Frequency Standard
- CNS Clock Independent Time Transfer
- HP Processor Computer Replacement
- OAM Controller Repackaged for Space Savings
- Y2K Software and Hardware Compliance
- HVAC Replacement