Geocenter motion excited by large-scale mass redistribution

Koji Matsuo¹, <u>Toshimichi Otsubo</u>², Hiroshi Munekane¹, Yoichi Fukuda³

- 1. Geospatial Information Authority of Japan
- 2. Hitotsubashi University
- 3. Kyoto University



Definition of Geocenter



Geocenter = CoM w.r.t. CoF

Measurement of geocenter motion from SLR

((((((

Earth

Measuring loading deformation which <u>includes</u> degree-1 components

Measuring gravity variations which <u>does</u> <u>not include</u> degree-1 components

> SLR is the best technique to measure geocenter motion at present

Observed deformation - gravity-derived deformation = degree-1 deformation = <u>Geocenter motion</u>



Objective of this study

- To derive geocenter motion from SLR observation using our original software package "c5++"
- To assess our "c5++" solution by comparing with CSR solution
 - To investigate driving sources of recent long-term geocenter motion



SLR analysis software: CONCERTO 5++ (c5++) (Otsubo et al, 1994; Hobiger et al., 2013)

Implement up-to-date geophysical models and TRF

- IERS Conventions 2010
- EGM 2008 model
- ITRF 2008
- etc



Strategy of SLR data analysis

- 5 SLR satellites data (LAGEOS-1/2, Ajisai, Starlette, Stella) from Jan. 1994 to Dec. 2012
- Arc length is 3 days
- Empirical acceleration (constant and one-per-rev) is estimated at 1.5 days interval
- 60 days -average geocenter motion is calculated

Results: Geocenter motion from c5++



Geocenter motion from CSR (provided by Dr. Ries)



Scatter plot : c5++ solution vs. CSR solution



-

Long-term geocenter motion: c5++ solution

2-year moving average



Long-term geocenter motion: CSR solution

2-year moving average



Trend shift in ΔJ_2 from SLR observation



Main sources of mass redistribution in 2000s

Linear mass trend in 2003-2013 from GRACE gravimetry



Estimation of mass-driven geocenter motion

1. Polar ice sheets

Ice thickness variations from ICESat altimetry from 2003 Oct. to 2009 Sep.

2. Sea level rise

Solve sea-level equation using ice mass variations from ICESat

3. Glacial Isostatic Adjustment

Theoretical values by Greff-Lefftz (JGR 2000)

1. Polar ice sheets: Antarctica



Assumes ice density as 700 kg/m³ for ablation area, 300 kg/m³ for accumulation area

1. Polar ice sheets: Greenland

Linear trend in Ice thickness from ICESat (2003-2009)

Total mass change in Greenland



2. Sea level rise

Sea level equation [e.g. Métivier et al., EPSL 2010]

$$h_{SL}(\theta,\varphi,t) = \frac{\rho_I}{g_o} \Phi(\theta,\varphi)^* h_I(\theta,\varphi,t) + \frac{\rho_{oc}}{g_o} \Phi(\theta,\varphi)^* h_{SL}(\theta,\varphi,t)^{SL} + C(t)$$



3. Glacial Isostatic Adjustment

Theoretical estimation by Greff-Lefftz (JGR 2000)

GIA-driven geocenter motion depends on viscosity of lower mantle and upper mantle

Here, we pick up the average values of the right figure

 $X_g = 0.1 \pm 0.05 \text{ mm/yr}$ $Y_g = -0.1 \pm 0.1 \text{ mm/yr}$ $Z_g = 0.2 \pm 0.2 \text{ mm/yr}$ Rate of geocenter variation (mm/yr)

Theoretical values of GIA-driven geocenter motion vs. assumed viscosity



Results: Estimated geocenter motion



Results: Comparison between SLR and estimation



Results: Linear rates of geocenter motion

	X axis (mm/yr)	Y axis (mm/yr)	Z axis (mm/yr)
SLR (c5++)	-0.04 ± 0.08	+0.22 ± 0.02	-0.60 ± 0.03
SLR (CSR)	-0.05 ± 0.04	+0.53 ± 0.04	-0.84 ± 0.08
ICE+SEA+GIA	-0.22 ± 0.06	+0.22 ± 0.10	-0.53 ± 0.24
ICE	-0.17 ± 0.02	+0.37 ± 0.01	-0.56 ± 0.14
SEA	-0.15 ± 0.02	-0.05 ± 0.01	-0.17 ± 0.01
GIA	+0.10 ± 0.05	-0.10 ± 0.10	+0.20 ± 0.20



Summary

- Recent large-scale mass redistributions move geocenter to south by ~0.5 mm/yr and 135E direction by ~0.3 mm/yr
- Mass losses in polar ice sheets are the main sources of recent geocenter motion
- SLR observation roughly agrees with the estimated results
- Our X component solution appears to be noisy (currently being investigated)





Future works

- To include contributions from ice mass variations in mountain glaciers using ICESat altimetry data
- To examine contributions of massive earthquakes using dislocation theory

Thank you for your attention!



Significance of precise geocenter determination

- Construction of Terrestrial Reference Frame (TRF)
- Precise determination of crustal velocity field
- Construction of global geoid model

Estimation of mass-driven geocenter motion

Computational formula of geocenter motion [e.g. Munekane, JGR 2007]

$$X_g = R\sqrt{3} \frac{\left(1 - \frac{h_1' + 2l_1'}{3}\right)}{1 + k_1'} \Delta C_{11}$$

$$Y_g = R\sqrt{3} \frac{\left(1 - \frac{h_1' + 2l_1'}{3}\right)}{1 + k_1'} \Delta S_{11}$$

$$Z_g = R\sqrt{3} \frac{\left(1 - \frac{h_1' + 2l_1'}{3}\right)}{1 + k_1'} \Delta C_{10}$$

 X_g, Y_g, Z_g : Geocenter motion

 $\Delta C10, \Delta C11, \Delta S11:$

dimensionless Stokes' coefficients of geopotential

R: Radius of the Earth

k₁', h₁', l₁':

load love and Shida number of degree-1 components

Map of SLR stations



http://ilrs.gsfc.nasa.gov/images/slrmap_symbols_2014_large.jpg

Annual variation

Atmosphere (ECMWF model) Ocean (ECCO model) Land water (GLDAS model)

Geocenter motion estimated from geophysical fluid models



Phasor diagram of annual components



 $2.91 \pm 0.30 \text{ mm}$

 $3.85 \pm 0.29 \text{ mm}$

6.84 ± 0.31 mm