ILRS SLR MISSION SUPPORT REQUEST FORM (version: January 2018)

SUBMISSION STATUS:
☐ New Submission (default)
☐ Incremental Submission (accepted only for a follow-on mission; fill-in new information only)
(provide the reference mission and the date approved by the ILRS:)
SECTION I: MISSION INFORMATION:
General Information:
Satellite Name:
Satellite Host Organization:
Web Address:
Contact Information:
Primary Technical Contact Information:
Name:
Organization and Position:
Address:
Phone No.:
E-mail Address:
Alternate Technical Contact Information:
Name:
Organization and Position:
Address:
Phone No.:
E-mail Address:
Primary Science Contact Information:
Name:
Organization and Position:

Address:	
Phone No.:	
E-mail Address:	
Alternate Science Contact Information:	
Name:	
Organization and Position:	
Address:	
Phone No.:	
E-mail Address:	
Mission Specifics:	
Scientific or Engineering Objectives of Mission:	
(specify)	
Role of Satellite Laser Ranging (SLR) for the Mission: (specify)	
Anticipated Launch Date:	
Expected Mission Duration:	
Required Orbital Accuracy:	
Anticipated Orbital Parameters:	
Altitude (Min & Max for eccentric orbits): km	

Inclination:		degrees
Eccentricity:		
Orbital Period:		
Frequency of Orbital M	[aneuvers:	
Mission Timeline: (example) Should include when SLR is	s to start within the mission tim	eline, such as "on insertion into orbit" or "launch +N" days.
Tracking Requiremen	ts:	
Tracking Schedule:	horizon-to-horizon	custom (specify:
Spatial Coverage:	global ILRS network	custom (specify:
Temporal Coverage:	full-time	custom (specify:
Normal Point Bin Size	(Time Span):	seconds
(See the "Bin Size" of o	other satellites on the ILRS	s. Justify if other bin size is required.) S Web site at ns/current_missions/index.html.)
Prediction Center:		
Prediction Technical Co		
Name:		
Address:		
Phone No.:		
E-mail Address:		
Priority of SLR for POI	D: Primary	Secondary Backup
Other Sources of POD:		
\square GNSS \square DORI	S \(\subseteq \text{ Accelerometer} \)	\Box other (specify:)

Other comments on mission information:

(specify) (list backup prediction centers and references/links to non-SLR techniques if available)

SECTION II: TRACKING RESTRICTIONS:

Several types of tracking restrictions have been required during some satellite missions. See http://ilrs.gsfc.nasa.gov/satellite missions/restricted.html for a complete discussion.

- 1) Elevation restrictions: Certain satellites have a risk of possible damage when ranged near the zenith. Therefore a mission may want to set an elevation (in degrees) above which a station may not range to the satellite.
- 2) Go/No-go restrictions: There are situations when on-board detectors on certain satellites are vulnerable to damaged by intense laser irradiation. These situations could include safe hold position or maneuvers. A small ASCII file is kept on a computer controlled by the satellite's mission which includes various information and the literal "go" or "nogo" to indicate whether it is safe to range to the spacecraft. Stations access this file by ftp every 5-15 minutes (as specified by the mission) and do not range when the flag file is set to "nogo" or when the internet connection prevents reading the file.
- 3) Segment restrictions: Certain satellites can allow ranging only during certain parts of the pass as seen from the ground. These missions provide station-dependent files with lists of start and stop times for ranging during each pass.
- 4) Power limits: There are certain missions for which the laser transmit power must always be restricted to prevent detector damage. This requires setting laser power and beam divergence at the ranging station before and after each pass. While the above restrictions are controlled by software, this restriction is often controlled manually.

Many ILRS stations support some or all of these tracking restrictions. You may wish to work through the ILRS with the stations to test their compliance with your restrictions or to encourage additional stations that are critical to your mission to implement them.

The following information gives the ILRS a better idea of the mission's restrictions. Be aware that once predictions are provided to the stations, there is no guarantee that forgotten restrictions can be immediately enforced.

Are there any science instruments, detectors, or other instruments on the spacecraft that can be damaged or confused by excessive radiation, particularly in any one of these wavelengths (532nm, 1064nn, 846nm, or 432nm)?

No Yes (specify the instrument or detector in question, providing the wavelength bands and modes of sensitivity.)

Are th	ere times when the LRA	A (Laser Retroreflector Array) will not be accessible from the ground?
No	Yes (specify:	
(If so,	go/nogo or segmentati	on files might be used to avoid ranging an LRA that is not accessible.)

→ Skip the next questions and go directly to SECTION III if you answered "No" to both of the above questions.

Is there a n	need for an elevation tracking restriction?	Version 01/2018
No	Yes (What elevation (minimum to maximum in degrees)?	degrees)
Is there a ne	eed for a go/no-go tracking restriction?	
No	Yes (Explain the reason(s)	
Is there a n	eed for a pass segmentation restriction?	
No	Yes (Explain the reason(s)	
Is there a ne	eed for a laser power restriction?	
No		
Yes	(Under what circumstances?)
	(What is the maximum permitted power level at the satellite (nJ/e	cm ²)?)
	(Is manual control of laser transmit power acceptable? Ye	s No)
For ILRS following s	stations to range to satellites with restrictions, the mission sportatement:	nsor must agree to the
subcontrac	ion sponsor agrees not to make any claims against the station or tors, or their respective employees for any damage arising from t ch damage is caused by negligence or otherwise, except in the case of	hese ranging activities
Please prov	vide signature to express agreement to above statement:	
Signature:		
Name (prin	nt):	
Organizatio	on and Position:	
Other com	aments on tracking restrictions:	

Is there a need for an elevation tracking restriction?	Version 01/2018
No	_ degrees)
Is there a need for a go/no-go tracking restriction?	
O No Ses (Explain the reason(s) During specific demo phases (to be	specified as nec
	*
Is there a need for a pass segmentation restriction?	
No)
Is there a need for a laser power restriction?	
● No	
O Yes (Under what circumstances?)
(What is the maximum permitted power level at the satellite (nJ/cm ²)?	?)
(Is manual control of laser transmit power acceptable? O Yes O	No)
For ILRS stations to range to satellites with restrictions, the mission sponsor following statement:	must agree to the
"The mission sponsor agrees not to make any claims against the station or stat subcontractors, or their respective employees for any damage arising from these whether such damage is caused by negligence or otherwise, except in the case of will	ranging activities,
Please provide signature to express agreement to above statement:	
Signature:	_
Date: 21st October, 2019	
Name (print): Andrea Puppa, Tim Flohrer	
Organization and Position: Astroscale Flight Dynamics Engineer, ESA Senior S	pace Debris Mg
Other comments on tracking restrictions: (specify)	

SECTION III: RETROREFLECTOR ARRAY INFORMATION:

A prerequisite for accurate reduction of laser range observations is a complete set of pre-launch parameters that define the characteristics and location of the LRA on the satellite. The set of parameters should include a general description of the array, including references to any ground-tests that may have been carried out, array manufacturer and whether the array type has been used in previous satellite missions. So the following information is requested:

Retroreflector Primary Contact Information:
Name:
Organization and Position:
Address:
Phone No.:
E-mail Address:
Array type:
Single reflector Spherical Hemispherical/Pyramid Planar
other (specify:)
Attach a diagram or photograph of the satellite that shows the position of the LRA, at the end of this
document.
☐ Attached
Attach a diagram or photograph of the whole LRA at the end of this document.
Attached Same as above, Not attached (acceptable only for a cannonball satellite)
Array manufacturer:
Link (URL and/or reference) to any ground-tests that were carried out on the array:
Has the LRA design and/or type of cubes been used previously?
No Yes (List the mission(s):

For accurate orbital analysis it is essential that full information is available in order that the 3-dimensional position of the satellite center of mass may be referred to the location in space at which the laser range measurements are made. To achieve this, the 3-D location of the LRA phase center must be specified in a satellite-body-fixed reference frame with respect to the satellite's mass center. In practice this means that the following parameters must be available at 1 mm accuracy or better.

ame
_)
xed

List the position (XYZ) of the center of the front face of each corner cube, and the orientation (two angles or normal vector) and the clocking (horizontal rotation) angle of each corner cube. Note that the angles should be clearly defined.

Attached at the end of this document
Listed here (acceptable for small number (10 or fewer) of corner cubes) (specify) (add a diagram in the attachment)
(specify) (add a diagram in the attachment)
Is the corner cube recessed in its container (i.e. can the container obscure a part of the corner cube)?
No Yes (specify below)
(specify) (add a diagram)
The size of each corner cube: Diameter () mm Height () mm
The material from which the cubes are manufactured (e.g. quartz):
The refractive index of the cube material
= for wavelength $\lambda = 0.532$ micron
= as a function of wavelength λ (micron):
The group refractive index of the cube material, as a function of wavelength λ (micron):
= for wavelength $\lambda = 0.532$ micron
= as a function of wavelength λ (micron):

Dihedral angle offse	et(s) and manufacturing tolerance (in arcseconds):	
Radius of curvature	e of front surfaces of cubes:	
Not applied	Yes (specify:)
Flatness of cubes's	surfaces:	
Back-face coating:	Coated (specify the material:)

Other comments on LRA:

(specify) (add a reference to a study of the optical response simulation/measurement if available) (add a diagram if applicable)

SECTION IV: MISSION CONCURRENCE

301-614-6015 (Fax) Carey.Noll@nasa.gov

The ILRS is a voluntary organization that operates under the auspices of the International Association of Geodesy (IAG). The ILRS adheres to the IAG policy to make all acquired laser ranging data and derived products publicly available. We request that the mission website, as well as mission publications, reference the scientific work derived from ILRS data and derived products, **acknowledge** the role of the ILRS. This acknowledgment is crucial for the continued support from the funding agencies of the ILRS participating organizations.

As an authorize request and aut	ed representative of the thorize the ILRS to track the satellite described in this documents.	mission, I hereby
Name (print):		
Organization a	nd Position:	
Signatura		
Signature:		
Date:		
Send form to:	ILRS Central Bureau c/o Carey Noll NASA GSFC Code 61A Greenbelt, MD 20771 USA 301-614-6542 (Voice)	

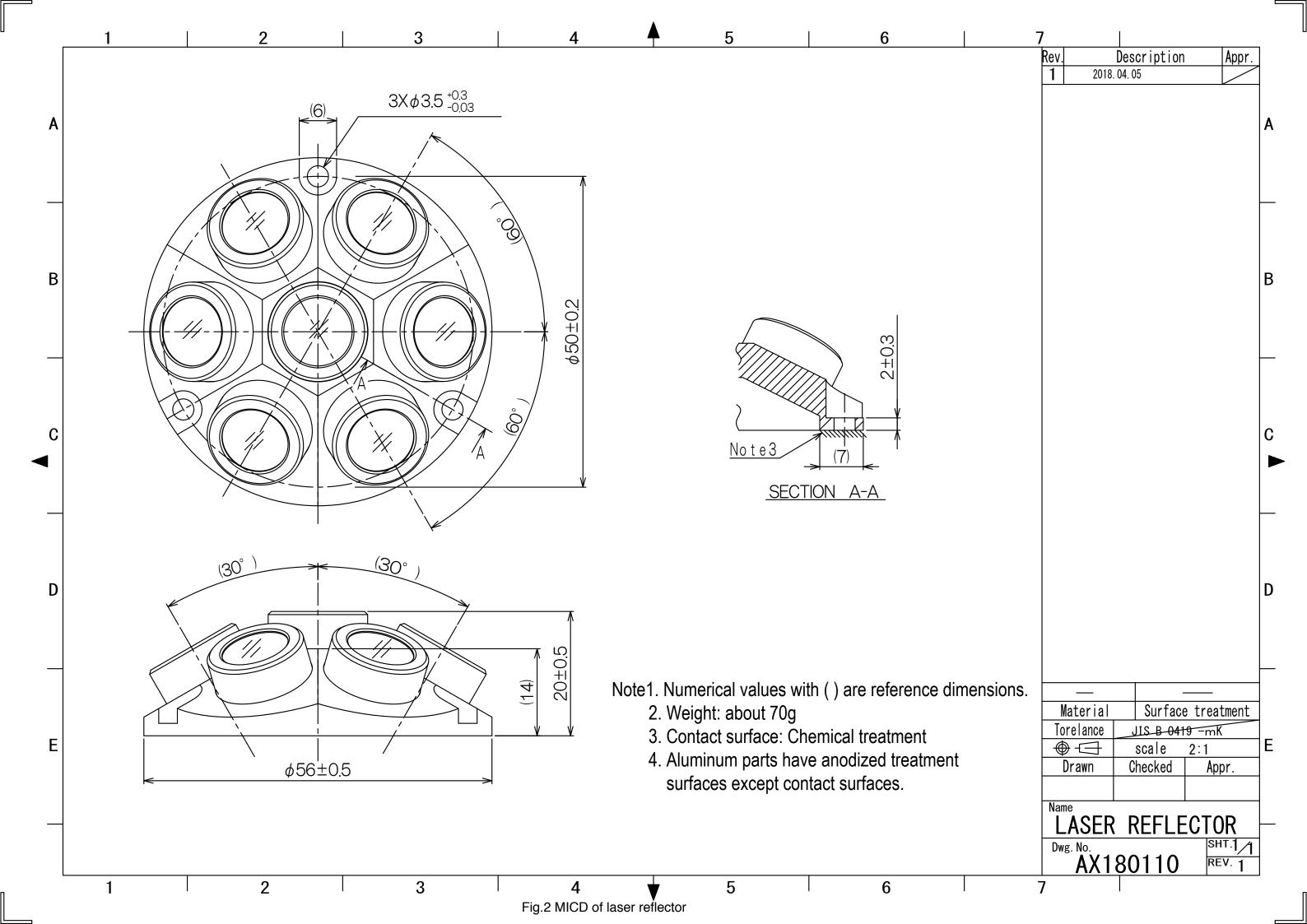
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As an authorize request and aut	ed representative of the _ horize the ILRS to track	ELSA-d the satellite descri	bed in this docur	ment.	mission, I hereby
Name (print): _	Andrea Puppa, Tim Flo	hrer —			
Organization a	nd Position: Astroscale	Flight Dynamics I	Engineer, ESA	Senior Sp	eace Debris Mc
Signature: Date: 21st Oct	tober, 2019			to the S	
Send form to:	ILRS Central Bureau c/o Carey Noll NASA GSFC Code 61A Greenbelt, MD 20771 USA 301-614-6542 (Voice)				

SECTION V: ATTACHMENT(S)



NOTES:

- 1. SUBSTRATE: FUSED SILICA
- 2. BLACK OVERPAINT IS 30-60 µm THICK

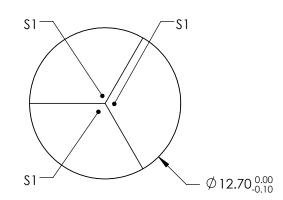
3. COATING (APPLY ACROSS COATING APERTURE)
S1: PROTECTED ALUMINUM
R(avg) >85% @ 400 - 700nm W/BLACK OVERPAINT
0.3 J/cm² @ 532nm & 1064nm, 10ns

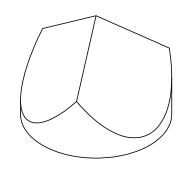
S2: UNCOATED

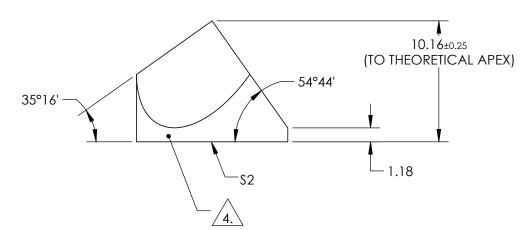


FINE GRIND SURFACE

5. ROHS COMPLIANT







PARTS TO THIS DRAWING

SPECIFICATIONS SUBJECT TO CHANGE WITHOUT NOTICE DIMENSIONS ARE FOR REFERENCE ONLY

REV A SURFACE FLATNESS	\$1 & \$2 λ/10				Edmund Optics ®
SURFACE QUALITY WAVELENGTH RANGE	20-10 400 - 700 nm	THIRD ANGLE _ PROJECTION	ϕ	TITLE	12.7mm ALUMINUM COATED, FUSED SILICA CORNER CUBE
ANGLE TOL. (arcsec) BEVEL	PROTECTED AS NEEDED	ALL DIMS IN	mm	DWG NO	49013 SHEET 1 OF 1

12.7mm Alu	minum Coated, Fused Silica Cor	ner Cube (Edmund Opt.)	
Stock #49-0	<u> </u>	. ,	
	Diameter (mm):	12.70 +0.00/-0.10	
	Height (mm):	10.16 + 30-60µm w/Black Overpaint	
	Coating:	Protected Aluminum (400-2000nm)	
	Beam Deviation (arcsec):	5	
	Coating Specification:	Entrance: Uncoated Reflective Surfaces: Ravg >85% @ 400 - 700nm w/Black Overpaint	
	Height Tolerance (mm):	±0.25	
	Image Orientation:	Left-Handed Black Overpaint is 30-60 µm Thick Left-Handed Black Overpaint is 30-60 µm Thick	
	Note:		
	Image Orientation:		
	Note:		
	Ray Deviation (°):	180	
	Substrate:	Fused Silica	
	Surface Flatness:	λ/10	
	Surface Quality:	20 - 10	
	Type:	Retroreflector	
	Typical Energy Density Limit:	Reflective Surfaces: 0.3 J/cm2 @ 532nm 8 1064nm, 10ns	
	Wavelength Range (nm):	400 - 700	
	RoHS:	Compliant	

Location of Laser Retroreflectors on ELSA-d Chaser

