

ILRS Governing Board

Westin San Francisco Market Street San Francisco, CA

December 06, 2011 19:00-21:30



ILRS Governing Board Agenda

1.	Opening Remarks		G. Appleby
2.	Central Bureau Update		M. Pearlman/C. Noll
3.	GGOS Activities		M. Pearlman
4.	Update on Missions		G. Appleby/S. Wettzell
5.	CRD Format Conversion		R. Ricklefs/C. Noll
6.	Quality Control Data Reports		T. Otsubo
7.	Analysis and Data Products		E. Pavlis
8.	Data Flow Issues		C. Noll/E. Pavlis/R. Ricklefs
9.	Task Force Reports		
i	a.	Communications	M. Torrence
	b.	Spacecraft Center-of-Mass Corrections	G. Appleby/T. Otsubo
(C.	Beam Divergence	M. Davis
(d.	In Sky Safety	
10.	Station Status Reports		
i	a.	NGSLR	J. McGarry
	b.	KASI	J. Park
(C.	Other reports	
11.	Update on GNSS Ranging		G. Appleby
12.	Lun	Lunar Laser Ranging J. Mueller	
13.	Website Development		C. Noll
14.	ILR:	ILRS Special Issue in Journal of Geodesy E. Pavlis	
15.	Bi-Annual Report		C. Noll
16.	Other Business		M. Pearlman
13. 14. 15.	Website Development ILRS Special Issue in Journal of Geodesy Bi-Annual Report		C. Noll E. Pavlis C. Noll





ILRS Central Bureau Report

Westin San Francisco Market Street San Francisco, CA

December 06, 2011 19:00-21:30



ILRS Governing Board 2011-2012

Director of the Central Bureau

Secretary of the Central Bureau

President of IAG Commission 1

IERS Representative

EUROLAS Network Representatives

NASA Network Representatives

WPLTN Network Representatives

Data Center Representative

LLR Representatives

Analysis Representatives

At-Large Representatives

Mike Pearlman (appointed)

Carey Noll (appointed)

Tonie Van Dam (appointed)

Bob Schutz (appointed)

Giuseppe Bianco, Francis Pierron

David Carter, Jan McGarry

Ramesh Govind, Hiroo Kunimori

Horst Mueller

Juergen Mueller

Cinzia Luceri, Erricos Pavlis

Graham Appleby*, Georg Kirchner

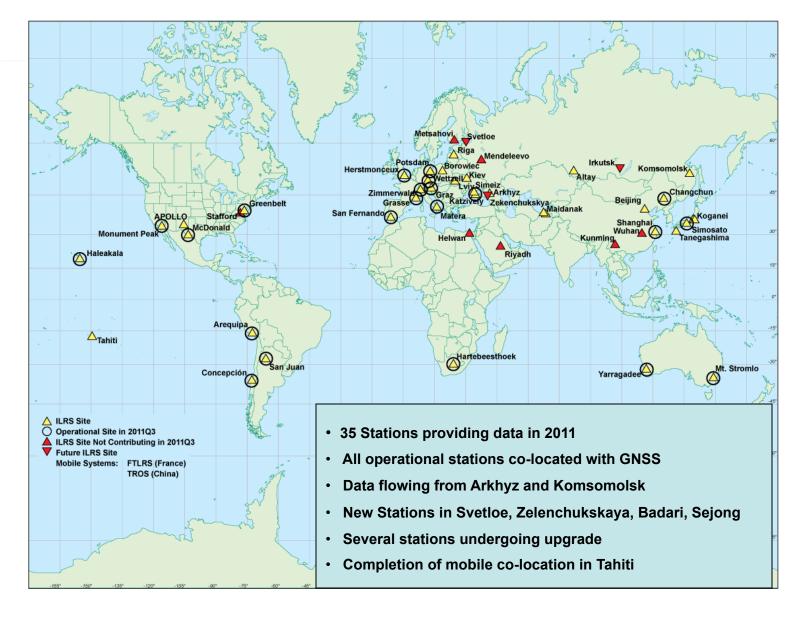
^{*} Chair



ILRS Working Groups

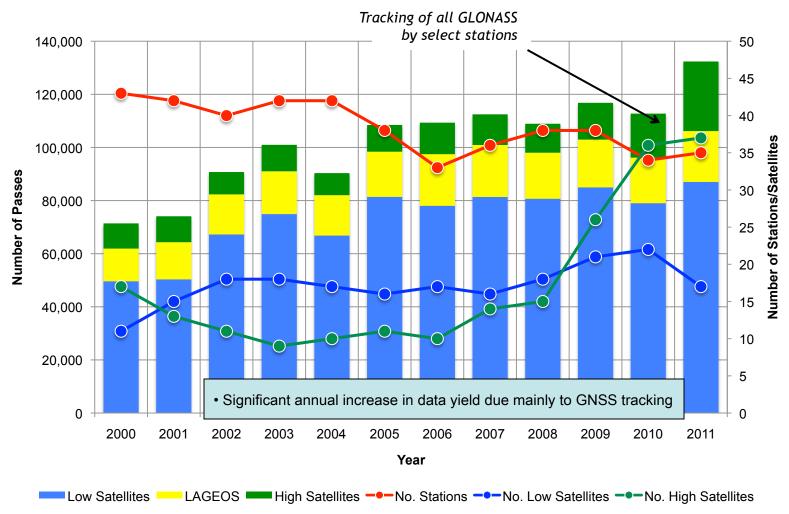
- Analysis
 - E. Pavlis/C. Luceri
- Missions
 - G. Appleby/S. Wetzel
- Data Formats and Procedures
 - H. Mueller/R. Ricklefs
- Networks and Engineering
 - G. Kirchner/M. Wilkinson
- Transponder
 - U. Schreiber/J. Degnan/J. McGarry

International Laser Ranging Service (ILRS) Network in 2011 Q3





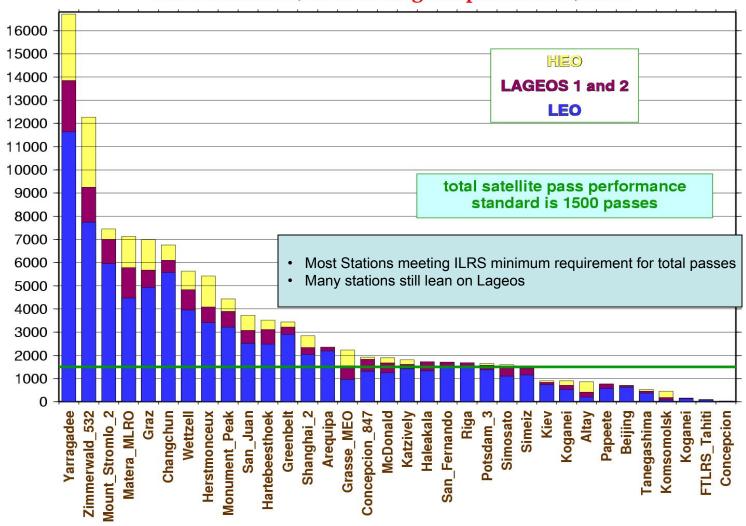
2011 Annual Data Yield





Station Performance (2011Q3)

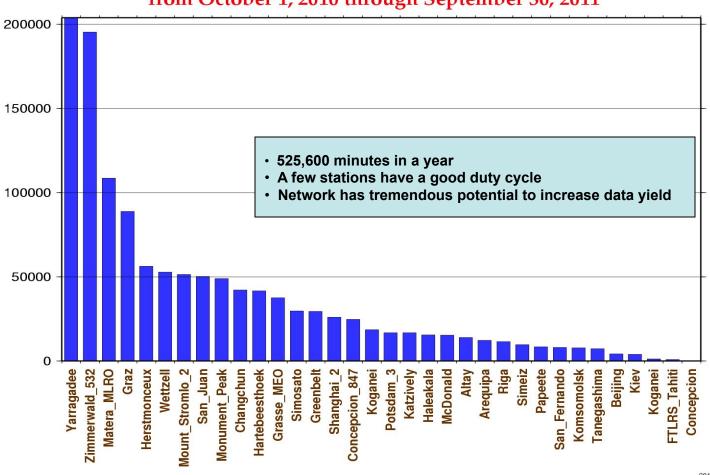
total passes from October 1, 2010 through September 30, 2011





Station Performance (2011Q3)

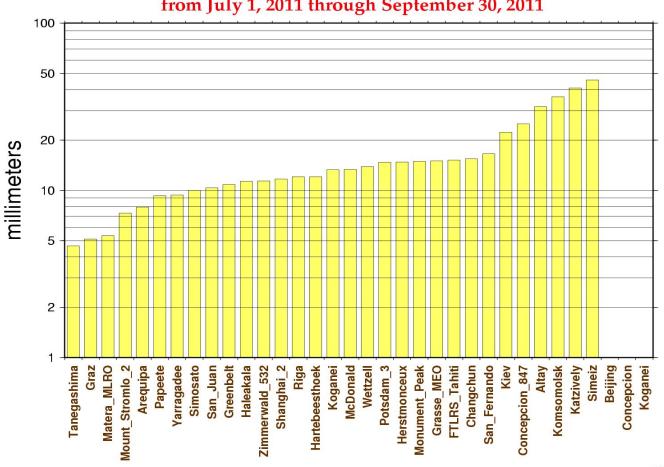
minutes of data from October 1, 2010 through September 30, 2011





Station Performance (2011Q3)



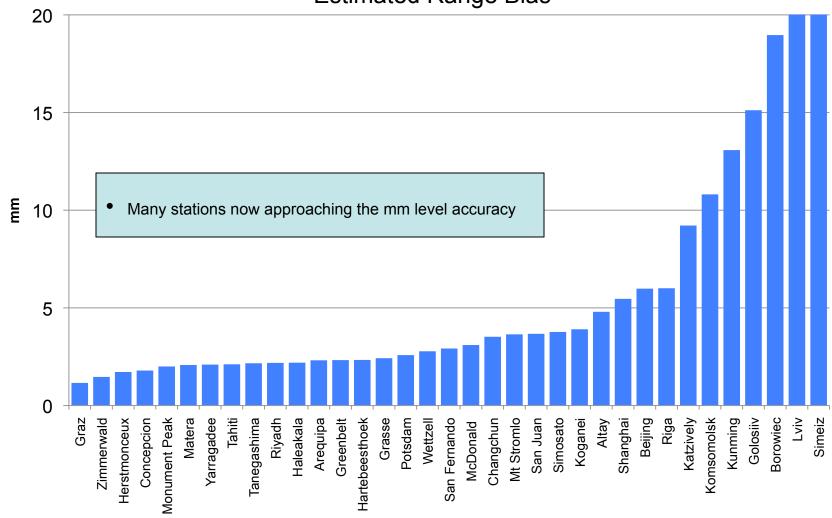


20111006



Station Performance

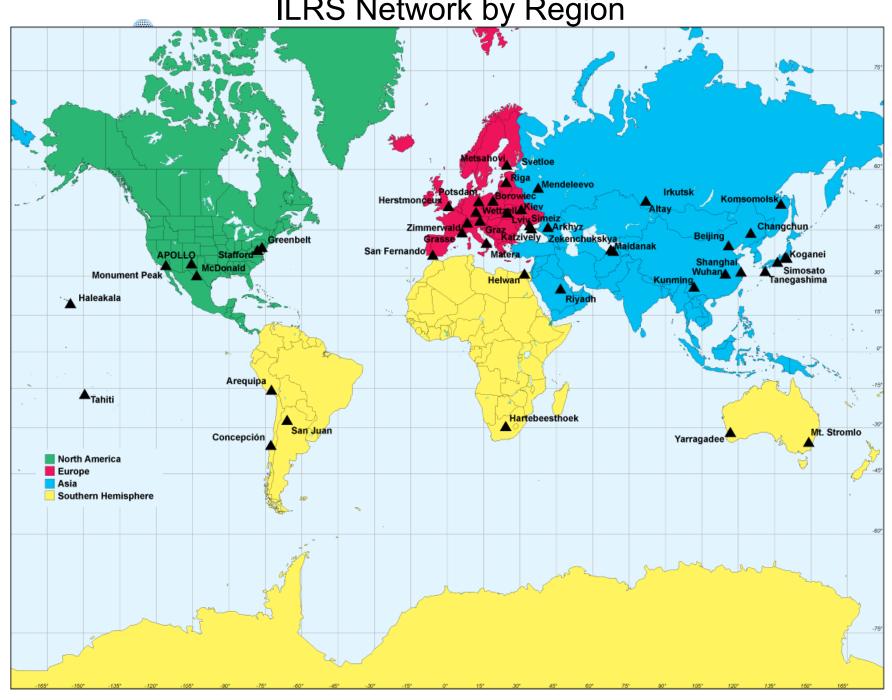
Estimated Range Bias

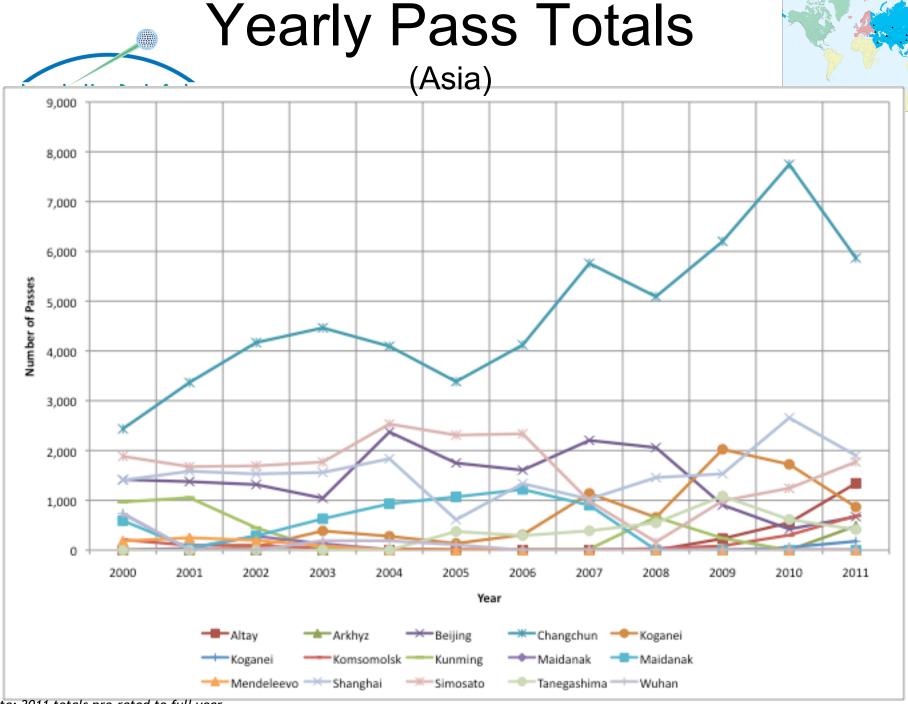


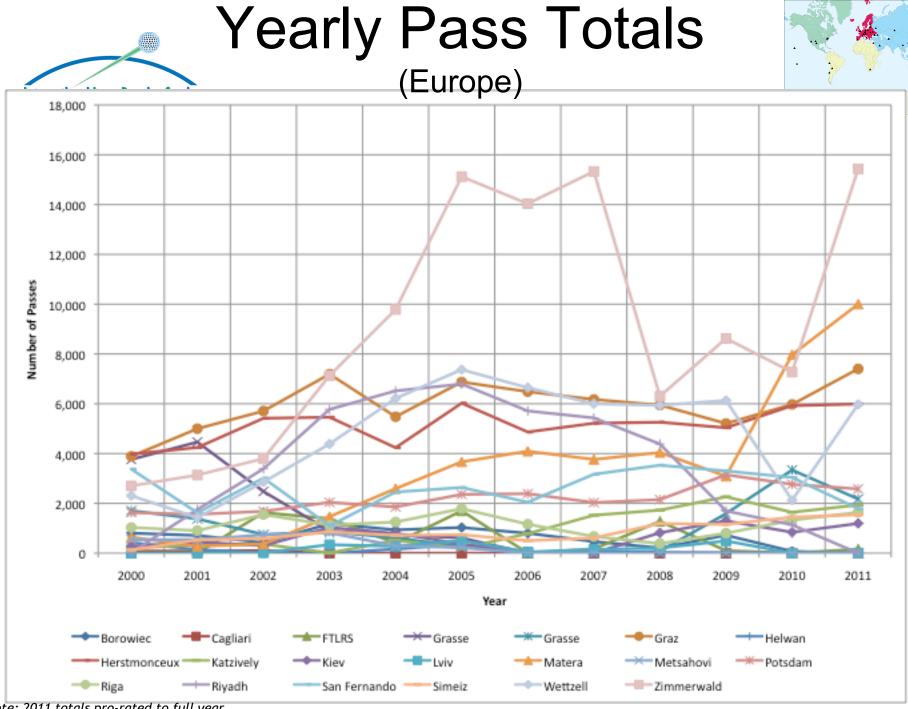
Toshi Otsubo/Hitotsubashi University, Japan December 6, 2011

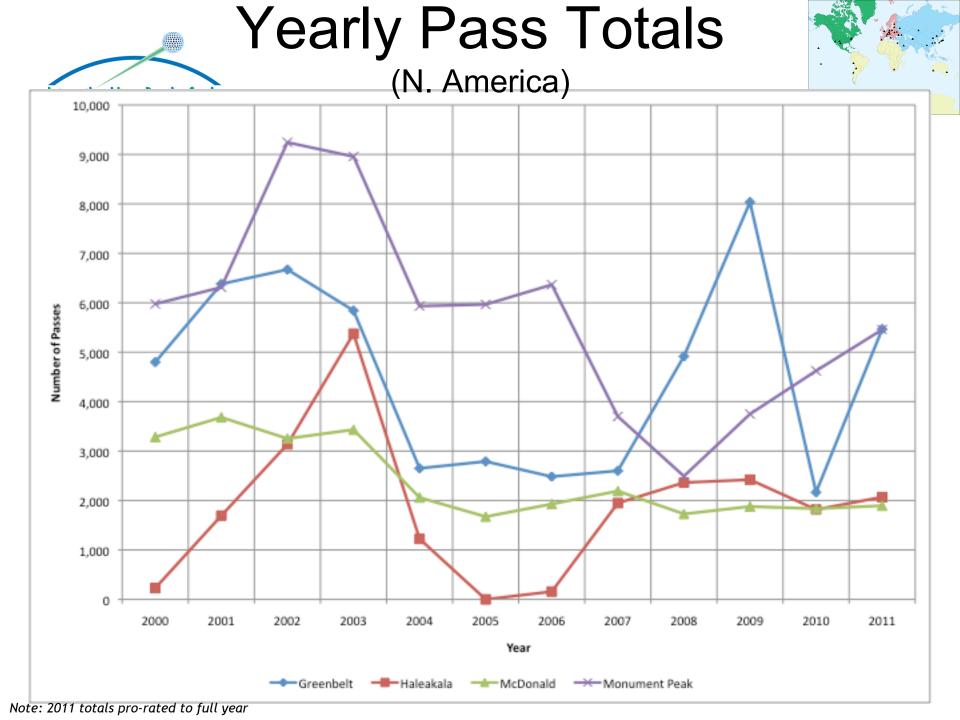
Site Name
ILRS Governing Board Meeting
San Francisco CA

ILRS Network by Region









Yearly Pass Totals (S. Hemisphere) 25,000 20,000 15,000 Number of Passes 10,000 5,000 2000 2007 2001 2002 2003 2004 2005 2006 2008 2009 2010 2011 Year → Mount Stromlo → Arequipa Conception San Juan ——Tahiti Yarragadee

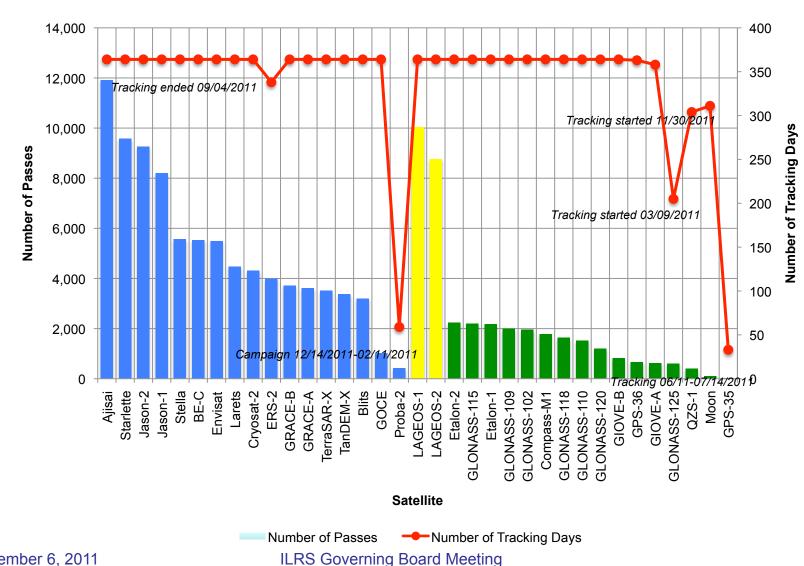


Mission Developments

- Currently supporting 57 missions (includes 26 GLONASS satellites) and lunar tracking
- Recent launches:
 - Radioastron (18-Jul-2011)
 - HY-2A (16-Aug-2011)
 - GLONASS-126 (02-Oct-2011) GLONASS-M satellite
 - Galileo-101 and -102 (21-Oct-2011)
- Upcoming:
 - LARES: Jun-2012
 - IRNSS (ISRO): mid-2012 (needs GB approval)
 - ZY-3 (CASM): Jan-2012 (needs GB approval)
 - SWARM (ESA): Jul-2012 (needs GB approval)
 - KOMPSAT-5 (KARI): 2012
 - SARAL (CNES/ISRO): 2012



Satellite Tracking (2011Q3)



San Francisco CA



Central Bureau Items

- CDDIS and EDC data center structures, Q/C, and quarantining procedures supporting CRD-formatted data are being harmonized
- New normal point population recipe under review to take advantage of the high repetition systems
- All stations encouraged to submit full-rate data (including kHz) to be archived by the Data Centers
- Trying to strengthen the timely feedback and response procedures from the stations on maintenance, modification, and upgrades
- Adherence to processes for certification of new stations and requalification of stations after upgrading or significant downtime required
- Simplified algorithm to encourage stations to better distribute tracking efforts perhaps using the real-time web facility at AIUB needs to be developed
- ILRS 2009-2010 Report continues in preparation
- Proceedings from 17th International Laser Ranging Workshop in preparation
- Re-design of ILRS website underway to make it more responsive to user needs
- Deadline for CRD conversion has been pushed to March 15, but some stations have not been answered our continuous inquiries



Revised Definition of the Normal Point (Draft)

- Current Definition of the Normal Point specifies a standard normal point interval (SNPI) based on satellite altitude;
- Issue some of the newer systems achieve plenty of FR data in far less time that the current FR interval;
- Task New definition of the NP to accommodate this;
- Formula under discussion:
 - Target mm precision
 - The Normal Point is complete on Satellite 1 when either (1) 1000 <u>valid</u> FR points have been taken or (2) the SNPI has elapsed, whichever comes first;
 - Do not return to Satellite 1 until at least the SNPI has elapsed;
 - The "new normal points" can start at any time;
 - The epoch of the normal is that of a central FR data point.
- Task Committee: Georg Kirchner, Mike Pearlman, Jan McGarry, Graham Appleby, etc.



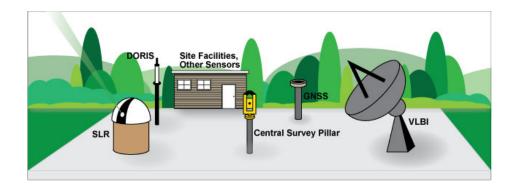
Meetings

- March 04-09, 2012: 7th IVS General Meeting, Madrid Spain
- April 22-27, 2012: EGU General Assembly, Vienna, Austria
- April 20, ILRS AWG Meeting, Vienna, Austria
- April 21, GGOS Coordinating Center, Vienna, Austria
- July 23-27, 2012: IGS Analysis Center Workshop, Olsztyn Poland
- August 13-17, 2012: AOGS-AGU Joint Assembly, Singapore
- August 20-31, 2012: XXVIII IAU General Assembly, Beijing China
- September 25-26, 2012: IDS Workshop, Venice Italy
- December 06-10, 2012: AGU Fall Meeting, San Francisco CA
- Fall 2013: 18th International Workshop on Laser Ranging, Japan



GGOS Bureau for Networks and Communications

Bureau Lead: Michael Pearlman

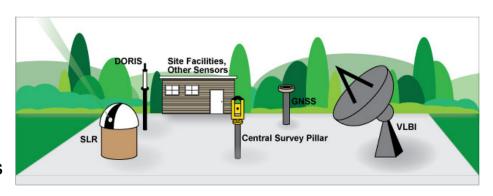




What is a Core Site?

(Terrestrial Reference Frame)

- A ground site with co-located SLR, VLBI, GNSS and DORIS (where available) so that their measurements can be related to sub-mm accuracy
- Why do we need multiple techniques?
 - Measurement requirements are very stringent
 - Each technique makes its measurements in a different way and therefore each measures something a little different:
 - Terrestrial (satellite) verses celestial (quasar) reference
 - Range verses range difference measurements
 - Broadcast up verses broadcast down
 - Radio verses optical
 - Active verses passive
 - Geographic coverage
 - Each technique has different strengths and weaknesses
 - The combination allows us to take advantage of the strengths and mitigate the weaknesses



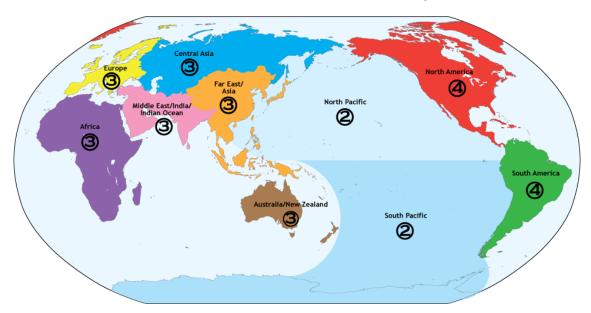


Simulation Studies to Scope the Network

(Erricos Pavlis)

- First Phase completed
 - ~30 globally distributed, well positioned, co-location Core Sites with proper conditions;
 - 16 of these Core Sites must track GNSS satellites with SLR to calibrate the GNSS orbits;

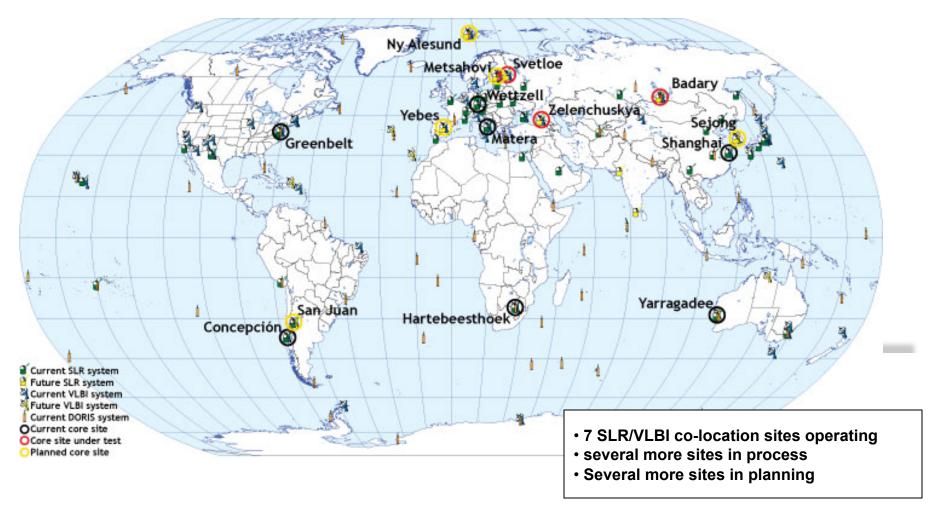
- Follow-on Phases (Impact on the ITRF)
 - Sensitivity to intersystem vector accuracy
 - Phased deployment; evolution of the products
 - Impact of errors and outages;
 - Additional space objects
 - Tracking scanarios
 - Impact of GRASP





Co-located VLBI, SLR, GNSS

(Some with DORIS)





Techniques are all Making Progress

- Satellite Laser Ranging
 - Several systems working in the Khz regime;
 - Increased data yield and daylight ranging on the GNSS satellites
 - Steady progress on the new SLR prototype at GSFC;
 - Progress on the GPS-3 arrays;
- VLBI
 - Prototype VLBI 2010 in testing at GSFC
 - New Systems Systems
 - Tasmania, Katherine, Yarragadee Stations
 - · Wettzell twin telescopes are being constructed;
- GNSS
 - Multiple constellations
 - Additional frequencies
 - New ground stations
- DORIS
 - Nearly complete network already
 - Additional satellites
 - New beacons
- Calibration
 - GRASP Concept



GGOS Site Requirements Document

(http://cddis.gsfc.nasa.gov/docs/GGOS SiteReqDoc.pdf)



- Introduction and Justification
 - What is a Fundamental Station?
 - Why do we need the Reference Frame?
 - Why do we need a global network?
 - What is the current situation?
 - What do we need?
- Site Conditions
 - Global consideration for the location
 - Geology
 - Site area
 - Weather and sky conditions
 - Radio frequency and optical Interference
 - Horizon conditions
 - Air traffic and aircraft Protection
 - Communications
 - Land ownership
 - Local ground geodetic networks
 - Site Accessibility
 - Local infrastructure and accmmodations
 - Electric power
 - Site security and safety
 - Local commitment



GGOS Call for Participation; The Global Geodetic Core Network: Foundation for Monitoring the Earth System

We seek proposals from organizations that would participate in the development, implementation and maintenance of the GGOS Global **Geodetic Core Network:**

- To implement and operate core space geodesy stations including:
 - existing stations that already have the four techniques implemented and plan for upgrade to the next generation systems;
 - existing stations that have one or more techniques operational, are planning for upgrade to the next generation systems and for the implementation of the remaining techniques;
- To support the network design and planning activity with analysis, simulations, site research (geology, weather, logistics, personnel, etc). To help design and develop the inter-technique vector systems and operational procedures.
- To provide applicable space geodetic instruments for implementation at a GGOS Global Geodetic Core Site in cooperation with a local organization.
- To implement and operate core stations offered by others;
- Call for Participation has been issued through the Services and the IAG.



Call for Participation

http://www.ggos.org/ (news page)

- CfP Issued 8/15/11; Responses due 11/15/11;
- 11 responses received covering 17 stations;
- Several more in process;
- Responses span include;
 - Current Legacy Core Sites
 - Current Legacy sub-core sites
 - Good intentions
 - Land
- Evaluations and answers scheduled for 12/31/11
- Members of the Review Team include:
 - Mike Pearlman
 - Zuheir Altamimi
 - Erricos Pavlis
 - Richard Gross
 - Representatives from the Services
- Meeting of core group scheduled for 12/7/11



GGOS Bureau for Networks and Communications Call for Participation

Responses Received

- Herstmonceux, GB
- Shanghai, Beijing, Changchun, Wuhan, Kunming, Urumqi,
- Wettzell, Germany
- Metsahovi, Finland
- Borowiec, Poland
- Yebes, Spain
- Onsala, Sweden
- Toro, Nigeria
- Medicini/Noto, Italy
- Pecny/Skalka, Czech Rep
- Yarragadee and Mt. Stromlo, Australia

Responses in Process

- Matera
- Hartebeesthoeck, South Africa
- NASA
- Warkworth, New Zealand

Not heard from:

- Russian Stations
- Sejong, Korea
- San Juan (China)



GGOS Bureau for Networks and Communications Call for Participation Issues and Steps Forward

- Decide on strategy of CfP acceptance and send out responses;
- Articulate description (or guidelines) for a Core Site both Legacy and "Ultimate";
 - system performance,
 - site conditions,
 - local reference network, etc,
- Encourage more groups to participate;
- Encourage stations to upgrade to newer technologies;
- Task Services with identification of proper reference point access;
- Task the Services with Technique Acceptance Criteria for Operational Stations;
- Decide how much "local motion" we can accept what can we model?



NASA Space Geodesy Project

- Provide NASA's contribution to a worldwide network of modern space geodesy Core Sites;
- Phase 1 Proposal developed for a 2–year activity:
 - Complete network simulations to scope the network and examine geographic, operational and technical tradeoffs based on LAGEOS and GNSS tracking with SLR;
 - Complete the prototype SLR (NGSLR) and VLBI (VLBI 2010) instruments;
 - Co-locate these instrument with the newest generation GNSS and DORIS ground stations at GSFC;
 - Implement a modern survey system to measure inter-technique vectors for co-location;
 - Develop generalized station layout considering RFI and operations constraints;
 - Undertake supporting data analysis;
 - Begin site evaluation for network station deployment;
 - Develop a full network implementation plan;
- Follow-on phase for deployment for up to 10 stations;



NASA Space Geodesy Project

Network Site Criteria/Evaluation Task

- Develop Site Selection Requirements Document
- Evaluate current NASA Sites as candidate Core Sites;
- Begin discussions with existing and possible new partners on Core Sites
- Work with GGOS (IAG) and other international organizations to develop plans for international participation and partnerships;

ILRS Missions Working Group

Report to Governing Board Tuesday December 6, 2011

Graham Appleby, Scott Wetzel



Mission support requests

- Mission sponsors fill in the ILRS webbased request forms
 - A general mission description, need for SLR, etc.
 - A detailed description of the LRA
- MWG then asked to comment via email
 - Includes AWG, SP, NEWG, DFPWG chairs
- Recommendation then to GB

Recent missions

RadioAstron

- In-space VLBI
- Highly-elliptical, apogee at 350,000km
- Link estimates (Davis) put returns in reach of several stations
- Mission publishes regular station-schedules
- GRASSE-MEO so far only station to track successfully
- LLR-capable stations in particular are encouraged to track

Recent missions

- Galileo (101 and 102)
 - Support approved, launched October 21
 - Tracking commenced mid-November
- GRASP
 - Letter of support written on behalf of ILRS
- Under review:
 - Swarm (ESA. magnetic field, three LEO satellites)
 - IRNSS (India, Regional GEO GNSS)
 - -ZY-3

General remarks

- Quite a lot of new missions applying for support;
- Need a more-responsive MWG
 - Full membership participation, timely
- To be discussed within MWG:
 - Should future general availability of mission data (e,g., onboard GPS) be an issue when ILRS is deciding whether or not to recommend tracking support?

General remarks

- Levels of support?
 - Full support when whole network is tasked
 - 'recognized mission' when a sub-set is required?
 - For example IRNS (GNSS GEO, over India, asking for a few specific stations)
 - Then more onus on mission to solicit tracking support
 - ILRS provides data archive for ranges, predictions



CRD Format Implementation

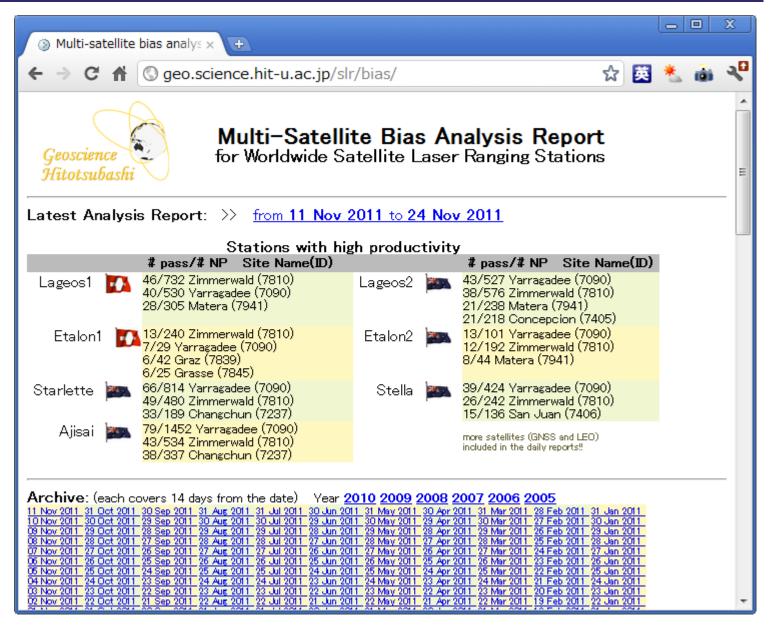
- Currently, there are 34 stations validated, and 3 awaiting validation; 7 have not been heard from.
- All AWG ACs are able to ingest CRD data.
- There are concerns about some stations taking shortcuts ("cheating"), by simply converting legacy data to CRD format, thereby loosing any advantages of the new format.
- Final transition date has been delayed several times due to lack of stations and recently to transitions at the Ocs...
- Both OCs are on track to make ALL new data available in both legacy and CRD formats by January 1, 2012.
- During January and February, 2012, one of the analysis centers will confirm the consistency of data (CRD vs legacy) at both Data Centers.
- The goal is to have these checks done by March 1, 2012. When they are done, the ILRS CB will announce the completion of transition to the CRD format.
- After transition, validated stations will stop sending legacy format data, and OCs will stop back-converting CRD data. All new data will be available in the CRD format only.

Quality Control Data Reports

Toshimichi Otsubo (Hitotsubashi Univ, Japan), and Horst Mueller (DGFI, Germany)

Quality Control Reports (HIT-U)





Quality Control Reports (HIT-U)



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# sat		date		aur	rb mm				tb us	error	prec		to	
AJI1	7090	2011/11/23	01:20	1	-17	(7)	(·)	2	0	/	5
STRL	7090	2011/11/23	03:03	1	9	(6)	(·)	3	0	/	4
AJI1	7090	2011/11/23	03:20	5	5	(6)	-2.5 (4.2)	2	0	/	13
LAG2	7090	2011/11/23	03:41	28	11	(3)	-0.5 (2.4)	1	0	/	10
STEL	7090	2011/11/23	05:06	1	27	(2)	(·)	0	0	/	5
AJI1	7090	2011/11/23	05:19	12	21	(5)	-4.3 (1.5)	4	0	/	27
STEL	7090	2011/11/23	06:42	7	1	(3)	-7.4 (0.8)	1	0	/	15
LAG1	7090	2011/11/23	07:03	16	10	(8)	6.9 (7.2)	3	0	/	10
AJI1	7090	2011/11/23	07:21	14	18	(3)	1.2 (0.7)	1	0	/	26
LAG2	7090	2011/11/23	08:09	18	4	(4)	1.0 (7.4)	3	0	/	11
LAG1	7090	2011/11/23	10:35	33	-12	(3)	-4.7 (1.7)	2	0	/	17
LAG2	7090	2011/11/23	12:09	47	-4	(3)	6.9 (1.5)	3	0	/	13
ETA2	7090	2011/11/23	13:53	2	-26	(18)	(·)	3	0	/	2
GL02	7090	2011/11/23	14:09	31	-19	(27)	-71.2 (102.2)	3	0	/	8
STRL	7090	2011/11/23	16:16	8	-7	(4)	2.5 (0.8)	1	0	/	14
STEL	7090	2011/11/23	16:19	1	-13	(5)	(·)	1	0	/	4
GP36	7090	2011/11/23	16:48	157	-14	(5)	10.2 (15.0)	3	0	/	8
STEL	7090	2011/11/23	17:56	5	-26	(8)	12.3 (2.1)	3	0	/	12
STRL	7090	2011/11/23	18:05	8	-3	(3)	-4.3 (1.0)	2	0	/	18
AJI1	7090	2011/11/23	20:16	6	32	(4)	-3.3 (2.6)	1	0	/	14

Quality Control Reports: Worldwide

Table 1 Analysis institutes providing quality control information. All: The Satellite and Duration should done publicly to the community, not what you did privately or you can potentially do. Are these info all controls are the satellite and Duration should be a satellite and Duration should be

Institute	Software	Output	Satellites	Update
Institute	boltware	Output	Datemites	Opdate
Astronomical Institute, Uni-	Bernese 5.1	Range bias	GPS and	Daily
versity of Bern, Switzerland			GLONASS	
Crustal Dynamics Data Infor-	-	Performance card	All	Quarterly
mation System, NASA, USA				
(Torrence: Inst Name ok?				
ILRS CB?)				
DGFI, Germany	DOGS 5.1	Range & time bias	ETALON and LA-	Daily
			GEOS	
Hitotsubashi University,	concerto 4.10	Range & time bias	GPS, GLONASS,	Daily
Japan			ETALON, LA-	
			GEOS and LEOs	
Joint Center for Earth Sys-	GEODYN II	Range & time	ETALON, LA-	Daily
tems Technology, USA	and SOLVE II	bias, Residual	GEOS and LEOs	
		map		
Information-Analytical Cen-	STARK-C 7.7	Range & time bias	LAGEOS	Daily
ter, Russia				
NERC Space Geodesy Facility,	SATAN_SX	Residual map	ETALON and LA-	Daily
UK			GEOS	
Shanghai Astronomical Obser-	SHORD-II	Range & time bias	ETALON and LA-	Weekly
vatory, China			GEOS	

"RapidServiceMail"

New framework proposed by H Mueller at AWG, Bad Koetzting

Mailing list for alerting bias issues

Common header

E-Mail Address: rapidservicemail@dgfi.badw.de

Web: http://rapidservicemail.dgfi.badw.de/

(Largely supported by Christian Schwatke, DGFI)

12 alerts released since June 2011.

7 from DGFI and 5 from HIT-U.

"RapidServiceMail": Example (Message 0011)

Date: Thu, 10 Nov 2011 15:34:59 +0900

Subject: Rapid Service Mail (HITU) 1824 large range bias due to no calibration

From: Toshimichi Otsubo <t.otsubo@r.hit-u.ac.jp>

To: medved@mao.kiev.ua, RapidServiceMail@dgfi.badw.de

Subject: Rapid Service Mail (HITU) 1824 large range bias due to no calibration

ILRS/AWG Rapid Service Mail (HITU) Message 0011
1824 large range bias due to missing calibration

Dear Mikhailo and Golosiiv (Kiev) staff,

A series of large range bias (> 30 metres) were detected in your data obtained on 8 Nov. It is very likely that it is linked with the missing calibration data (= zero).

Please visit:

<u>http://geo.science.hit-u.ac.jp/slr/bias/</u> (and check Latest Analysis Report) and consider resubmitting the data if possible.

Best Regards, Toshi

Ongoing and Future issues

Writing a paper for Journal of Geodesy

"Data Quality Control Service for the ILRS Tracking Network" by Otsubo, Mueller, Pavlis, Torrence, Thaller, Glotov, Xiaoya and Appleby.

Ideas for the future?

Faster/more frequent reporting?

More satellites? Multi-technique?

Automatic anomaly detection?



ILRS Analysis Working Group Report to

ILRS Governing Board Meeting

San Francisco, CA, Dec. 6, 2011

Erricos C. Pavlis and Cinzia Luceri

Analysis Coordinators



ILRS AWG Update

Analysis:

- Operational products (weekly & daily) delivered routinely and on time from all nine ACs:
 - ASI (AC & CC), BKG, DGFI, ESA, GA, GFZ, GRGS, JCET(AC & CC), & NSGF
- New CoG model for LAGEOS & ETALON (site- and time-dependent with few mm accuracy) adopted and tested in current Pilot Project
- Once this PP is completed, the DAILY analysis product will become the "official" ILRS product and the WEEKLY product will be used in several PPs to test improved modeling and new analysis products (atmospheric gravity and loading, low degree harmonics, orbits, etc.)
- All PPs are expected to be finalized by Spring of 2012
- JCET/GSFC AC will have to move between Dec. 23, 2011 and Jan. 3, 2012 to a new on-campus location, implying delays and down-time until the new facility is operational again (mid-January at best)



ILRS AWG Update - cont.

Analysis (cont.):

- Re-analysis for 1983 to present to begin once all improvements have been checked and validated by all ACs (Spring/Summer of 2012)
- The ILRS AWG will continue validating the implementation of the new format at sites which have not yet implemented the CRD format (their data will be reformatted to CRD by the OCs until they pass validation tests)
- The AWG held a brief meeting at the 17th ILRS Workshop in Bad Kötzting, Bavaria, and a full-day meeting in Zürich, CH, the day before the UAW.
- ILRS had strong participation in the last UAW
- The next ILRS AWG all-day meeting will take place in Vienna, Austria, prior to the EGU 2012 (Saturday, April 21) at TUW



Publications

ILRS Special Issue in the Journal of Geodesy:

- Progressing slowly mainly due to the editors' limited amount of time for this task
 - Over 24 submissions, three abstracts pending finalization, selection process in January 2012
 - Planning for a completed review process by end of summer 2012

Future Meetings:

• 18th International Workshop on Laser Ranging will be held in Tokyo in the fall of 2013, and an ILRS AWG meeting is planned to occur prior to the workshop week (TBD).



Breaking News

- Cannonball constellation will soon acquire a new member LARES
- LARES launch set for January 29, 2012 from Kourou (on VEGA)





Data Flow Issues

111129_daily_sate_stats.txt

Tue Dec 06 13:10:04 2011

1

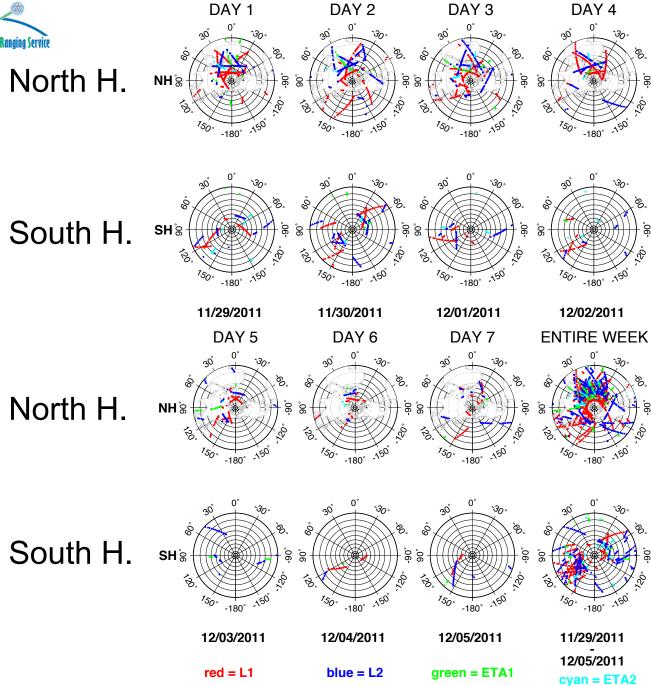
RESIDUAL SUMMARY STATISTICS FOR ARC 111129 BY DAY AND BY TRACKING STATION

	11/11/29	11/11/30	11/12/01	11/12/02	11/12/03	11/12/04	11/12/05	TOTAL
SITENAME SITE_NUM	AVG STD NPTS	AVG STD NPTS	AVG STD NPTS	AVG STD NPTS	AVG STD NPTS	AVG STD NPTS	AVG STD NPTS	AVG STD NPTS
Kiev 18248101 Katzivel 18931801 Mcdonald 70802419 Yarragad 70900513 Monument 71100412	7.4 11.8 18 6.2 25.6 7 9.6 12.8 56 -16.9 15.9 7	5.5 21.8 10 -25.3 17.4 11 0.9 9.7 9 -1.2 17.6 74 14.4 22.2 31	3.1 8.6 9 -1.4 11.0 36 1.3 10.9 57	-10.9 14.6 5 2.3 23.3 40 0.1 20.2 53 -5.8 28.7 19	3.2 16.8 18 -3.2 9.8 16	-1.3 24.9 25 -14.2 21.3 25	-3.2 19.3 23 -11.0 7.0 20	0.0 20.8 15 0.0 21.5 121 0.0 13.5 52 0.2 17.3 304 0.0 23.9 77
Papeete 71240802 Changchu 72371901 Koganei 73085001 Conc@847 74057914 San Juan 74068801	-5.9 11.3 27 -2.7 17.0 24 2.2 20.8 20	0.0 25.7 11 -3.9 5.1 18 0.7 18.6 74 49.0 8.1 5	-0.1 14.5 62 -10.9 1.2 7 -10.8 18.6 18	21.3 13.6 10	-8.7 15.9 6 -28.6 25.4 14	32.2 53.6 9 12.3 4.3 7	0.0 10.2 23	0.0 25.7 11 0.0 20.7 122 0.0 10.2 23 0.0 17.5 112 -1.4 28.8 67
Hartebee 75010602 Zimm@532 78106821 Shanghai 78212801 Mount St 78259001 Simosato 78383603	0.0 3.8 4 2.8 16.5 142	1.5 12.1 131 0.0 16.4 19	-1.7 12.1 142	-4.8 13.7 89 -27.1 15.5 12 4.3 4.0 3	0.0 16.3 17 6.8 27.5 45 -12.9 1	2.4 13.4 4		0.0 14.7 21 -0.1 14.0 508 -0.3 28.9 57 0.0 9.2 4 0.0 16.4 19
Graz 78393402 Herstmon 78403501 Potsdam 78418701 Grasse 78457801 Matera 79417701	0.0 16.3 15 0.1 16.8 30 -3.5 14.7 77 -2.2 15.7 45 -8.4 13.8 52	1.1 11.1 27 5.9 6.4 33 23.3 1.4 3 2.2 16.2 63	-2.5 15.7 67	9.8 15.3 13 3.0 20.6 83	-2.5 16.8 23 7.0 4.0 7	-8.3 24.0 15	2.2 26.6 43	0.0 16.3 15 0.0 21.0 115 0.0 14.4 146 -0.6 16.5 48 -0.6 17.5 272
Wettzell 88341001	-2.8 16.1 48	3.3 4.1 5	2.2 5.4 15	3.0 8.7 28				0.0 12.7 96
GRAND TOTAL 21	-0.2 16.2 572	1.9 17.0 524	-1.5 13.1 413	-0.4 19.7 355	-1.1 22.6 147	-1.5 29.7 85	-1.9 20.1 109	0.0 17.9 2205

NEW	PERSEUS-SERIES2010	2008	RESULTS	FOR ARC:	o11129

MJD	X	Υ	UT1-UTC	SIG_X	SIG_Y	SIG_UT1	RMS	NS	NNP	ND
55894.5007	0.16246	0.28749	-0.385335	0.00006	0.00007	0.001177	16	16	572	1
55895.5007	0.16097	0.28633	-0.386308	0.00006	0.00006	0.001177	17	16	524	1
55896.5007	0.16006	0.28476	-0.387421	0.00006	0.00008	0.001177	13	10	413	1
55897.5007	0.16009	0.28425	-0.388673	0.00007	0.00009	0.001177	20	11	355	1
55898.5007	0.15962	0.28228	-0.389800	0.00017	0.00020	0.001177	23	9	147	1
55899.5007	0.15837	0.28332	-0.390971	0.00027	0.00029	0.001177	30		85	
55900.5007	0.15742	0.27956	-0.391425	0.00023	0.00032	0.001177	20	5	109	1





E C Pavlis 12/06/11 ILRS GB, San Francisco, CA



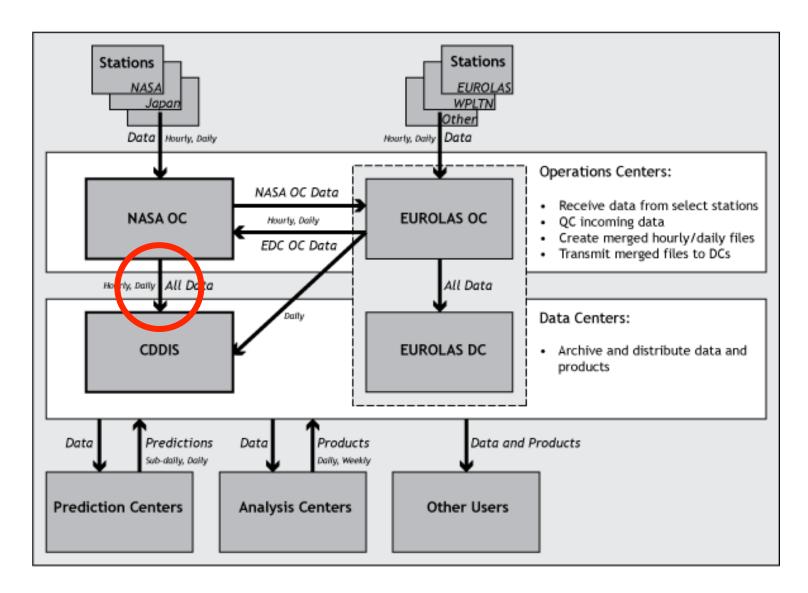
ILRS Data Flow Issues

ILRS CB

ILRS Governing Board Meeting San Francisco, CA December 07, 2011



ILRS Data Flow





Issues

- Two ILRS Operational Data Centers, NASA and EDC, collect data from subnetworks
- Two ILRS Global Data Centers, CDDIS and EDC, provide user access to data and products
- In April 2011 NASA SLR operations center contractor changed
- New group still coming up to speed with this unique task
- Data flow, and therefore, ILRS operations, have not been smooth:
 - Flow of operational data set (i.e., old format) has problems:
 - EDC data not correctly incorporated into daily deliveries to CDDIS ==>
 - Missing data in operational files
 - EDC and CDDIS data holdings are not identical
 - Quarantined data released in operational files
 - Data flow inconsistent and not reliable
 - NPT data arrive late or not at all
 - FR data flow stopped for several weeks
 - ==> Impact to routine AC operations
 - CRD data flow working well for most part
 - Flow of FR data from EDC to CDDIS resumed and old data pushed



Resolution?

- NASA contractor installed new network and new servers
- Putting new automated checks in place to monitor data flow
- Puts more work on CDDIS and EDC (as data centers) to ensure data are archived properly
- CDDIS and EDC need to compare data holdings

Task Force-1

Charter:

- Address concerns about inadequate two-way communication between the stations and the analysis centers to provide:
- (a) unambiguous, timely reports to the stations regarding data quality and bias information, and
- (b) timely reports to the analysis centers on configuration changes and other events that could affect system biases.

Task Force-1

- Methodologies and parameterization information obtained from each "quick-look" analysis center (QLAC) are available at the ILRS web site
- Communication of bias observation by QLAC's is ongoing by T. Otsubo and H. Muller through direct email contact with the station(s).
- The number of data anomalies has been steadily decreasing

Task Force-1

Status:

- (a) unambiguous, timely reports to the stations regarding data quality and bias information addressed by T. Otusbo rapid identification and communication of anomalies; the AWG is constantly updating the bias files. "keep the ILRS routine product to a high quality standard in close contact with the site engineers."
- (b) timely reports to the analysis centers on configuration changes and other events that could affect system biases: are the stations are changing the SCF and SCH? Are the AC's are using this information historically, yes.

Spacecraft Centre of Mass Corrections ILRS Task Force II

Graham Appleby¹, Toshi Otsubo²

1 SGF Herstmonceux, UK

2 Geoscience Laboratory, Hitotsubashi University, Kunitachi, Japan





Background

- * A strength of the LR technique is its longevity;
- * Data at few cm-level of precision is available from launch of the LAGEOS in 1976
- * But requirement now is for mm-level products, so:
- * Can we improve satellite centre-of-mass models for all historical data, one of the key accuracy issues, impacting scale determination and GM;
- * And, importantly, is the ground-segment technology going in the right direction to improve this issue for the present and the future

Satellite signature effect

- * The satellite signature effect needs careful station/ epoch-dependent treatment in order to refer range measurements to the centres-of-mass of the geodetic satellites
- * Up to 10mm station-dependent differences for LAGEOS, 30mm for Etalon (Otsubo & Appleby, 2003)
- * These effects are similar to the antenna phase-centre effects on GNSS satellites and receivers, as being addressed in IGS

New CoM values for L&E

- * ILRS stations' site logs are a valuable source of relevant information:
- * Detectors, laser pulse-length, operational practices (return-energy regimes), etc.
- * Used to derive time-series of CoM corrections and their uncertainties for each station for LAGEOS and for Etalon
 - * using the published models and comparison with LAGEOS-2 pre-launch tests for some station configurations

New CoM values for L&E

- * Results released in September 2011 to the analysis community for evaluation;
- * AWG weekly pilot solutions since October 2011 include use of new LAGEOS and Etalon CoM values
- * SGF AC recent (Aug-Sep 2011) 7-day arc, 4-satellite solutions for coordinates and EOP show small improvement in post-fit WRMS at sub-mm level;
- * Residual mean value changes ± 0.2mm
- * Plus some suggestion that LAGEOS-2 solutions worse (Pavlis, AWG Sept 2011)

Detail from CoM table for LAGEOS

Station	Time-span	detector info	CoMr	nin, m	ax, ac	lopted (mm
		50 20 MCP CSM		0		248 250
		08 100 MCP CSM 00 300 PMT NC				248 250 241 243
7839 01	11 1981 08 10 20	03 35 CSP NCM	2.2	3	9 255	250 252
7839 09	10 2003 31 12 20	50 10 CSP NSF	2.2	3	9 255	250 252
7840 01	02 2007 31 12 20	50 10 CSP CS	2.5	3	9 245	245 245
7840 31	03 1983 31 03 19	92 100 PMT NCF	3.0	35 43	5 252	244 248
7840 31	03 1992 31 12 20	50 100 CSP CS	3.0	6 13	5 246	244 245
7841 20	07 2001 31 12 20	50 50 PMT CSF	2.5	10 1	8 254	248 251

Availability of CoM data tables

- * Complete for LAGEOS and Etalon for 1980s onwards;
- * Some missing stations/epochs discovered during discussions within AWG have been included;
- * Some conflicts for stations with multi-configurations
 - * Have implemented use of system configuration flags
- * Almost ready to release data for Ajisai
- * Starlette/stella under preparation
- * Fortran code and two text files released

conclusions

- * CoM corrections for LAGEOS and Etalon for all stations and for period 1980s onward completed
 - * Software and text files released during Sept 2011
 - Evaluation by ACs underway
- * New ILRS stations tending towards high-rate, lower energy
 - * -> Less systematic problems wrt CoM values

ILRS Task Force Report: Beam Divergence Mark Davis

ILRS GB/AGU December 6, 2011

- Procedure developed and presented at the Bad Kötzting Workshop in May 2010
 - Available at http://cddis.gsfc.nasa.gov/lw17/docs/presentations/ session10/01a-Session10_DavisDivergence.pdf
- Received divergence tests data from Stafford, Herstmonceux, Graz, Shanghai, Changchun and Yunnan(?)
 - Processing data and interpreting results
 - Need greater participation by ILRS sites
 - Possible ILRS sponsored campaign
- Continuing to develop format for divergence test data
- Developing a spreadsheet to calculate divergence
 - Stations can use to determine system divergence based on "Davis Divergence" procedure
- Need to develop data archival procedure and format and establish repository at the CDDIS

ILRS Task Force Report: Beam Divergence

6-Dec-2011

Summary of Issues

- Crew Procedure
- Reporting uniformity
- Results Interpretation
- Archiving efforts
- Proposed Format
- Utilization of measurements for guidance future daytime GNSS array design
- Timeline

Crew Procedure

- This is outlined in Bad Kotzting workshop ppt
 - Session 10 Wednesday
 - http://cddis.gsfc.nasa.gov/lw17/docs/presentations/session10/01a-Session10_DavisDivergence.pdf
- Minimum step guidance
 - is 1/20th expected beam size or 1 arcsec
 - practically achievable by KHz
 - Likely will be atmospheric jitter limited
 - Measure the time to make the measurement
 - Realtime Automatic return rate computation logging
 - Duration over each step uniform to keep the rate data consistent
 - Graz used 0.1 sec
 - Hz uses 1.0 sec for kHz and 8 sec for Hz
 - Realtime Signal vs Dark Noise separation needed for the realtime rate computation
- Pairs of Measurements
 - Same sky conditions
 - Same hardware configuration
- Station Practices
 - Many will haven additional practices or observations which will be useful to future measurements at other stations
 - Verbose area for comments

Reporting Uniformity: Proposed Format

- Each File is a measurement on a particular satellite
- Standard Required information
 - Epoch
 - Satellite
 - Station
 - We can get most of this from the matching normal point file
 - Average range
 - Minimum step used
 - Steps from "barely there to barely there"
 - Duration for measurements
 - Time between final centering and final measurements
- Optional
 - Weather conditions
 - Sky clarity
 - System dependent variable parameters
 - Divergence
 - Tx power
 - Fireing rate
- Optional station specific measurements
 - To permit the automatic return rate and angle offset logs from Herstmonceaux and Graz

Results Interpretation

- Requires Pairs of Satellites at the same elevation
 - Same sky conditions
 - Ideally Starlette/Stella/Ajisai and Lageos I/II combinations
 - Getting ok results with Lageos and GNSS
- Stability of result as function of centering
 - Time consuming part is the boresite finding
 - this can be done with much bigger steps
 - Area of research to see how sensitive this will be to final result
- Measured Steps Interpretation
 - Excel worksheet is available to convert from steps to size
 - Will likely evolve as we get better
 - Will need to accommodate the time to make the measurement.
 - There are beam offsets in boresite center as the pass occurs
 - There is going to be changed in atmosphere
 - Elevation changes
 - Even the high light clouds
 - Stability of the return rate is likely going to play a role

Archiving Efforts

- If the stations make the measurements
 - Record what was OBSERVED
 - Do not mix final interpretation with observations
 - Different operators at the same station will be useful
 - (but don't mix them up until shown compatable)
- Similar to Sitelog updates
 - (is this just simply mail them to the CB address?)
- Set up a tree that is parallel to the CRD normal point archive
 - Divergence / yyyy / satellite / unique naming .divergence
 - There can be more than one measurement in the file
 - Make the unique name close enough to actual normal point file name so they can be used together for automatic assessment

Utilizing Measurements

• MAD to add a summary chart

Timeline and Participation

- Very enthusiastic responses from Stafford, Herstmonceaux, Graz,
 Shanghai, ChangChun and Yunnan prior to the workshop in May
- Other stations have expressed interest
 - No responses yet
- Need participation from the key contributing sites and typical configurations envisioned for GNSS support in 5+ years
 - Performance data for GNSS array design finalization is the key driver



NGSLR UPDATE Jan McGarry ILRS GB Meeting December 6, 2011





NGSLR Activities under SGP

- Will be moving to a non-eyesafe laser for future of NGSLR dictated by need for 24/7 GNSS ranging. Have ordered a Photonics Industries (PI) 2.5+ mJ/pulse 50 ps pulsewidth 2 kHz laser.
- Modifying NASA built mJ laser to improve stability so it can be used in interim until PI laser is delivered. Plan is to perform intercomparison with MOBLAS-7 using this laser in early 2012.
- Replacing current NGSLR optical bench with new design and new parts.
 Reasons for replacement include: improved alignment capability, space for automated controls, improved isolation between Xmit/Rcv, higher damage threshold optics. Design complete parts (make/model are being identified).
- NGSLR Development Lab in back of 1.2 m Telescope Facility has been setup and is in use to do software development, optical bench build and alignment, and automation testing. We will build up and test the new (automated) optical bench there before moving to NGSLR.
- Final parts of the NGSLR automation software are being worked. Automated ground calibration software has been written and is in testing. Closed loop tracking design has been started.



Procuring Higher Power Shorter Pulse Laser

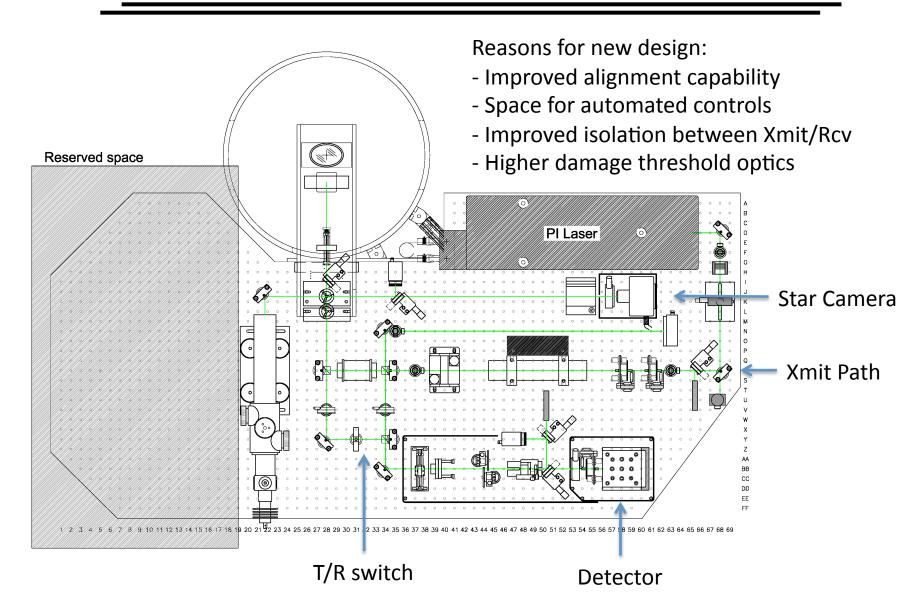
Photonics Industries Short Pulse, Hi Energy, Hi Rep Rate Laser: Conversations with vendor have led to final laser specifications and configuration changes needed for new optical bench.

- Model RGL532-2.5
- Maximum Energy = 3 mJ
- Pulse Width FWHM = 50 ps
- Repetition Rate = Single Shot to 5 kHz
- Beam Divergence < 1 mR
- Output Beam Diameter = 1.7mm
- Spatial Mode Profile = TEM₀₀
- Long Term Stability < +/- 2%
- Pulse to Pulse Stability < 2% RMS





Building a New Optical Bench Design





Very Preliminary NGSLR Schedule

Major milestones under SGP

Complete prep for Inter-Comparison	Feb 2012
Inter-Comparison with MOBLAS-7 done	Mar 2012
New optical bench build/testing done	Mar 2012
Complete move of optical bench to NGSLR & test w/system	Aug 2012
Complete automated system checkout	Nov 2012
Collocation w/MOB-7 complete	Apr 2013

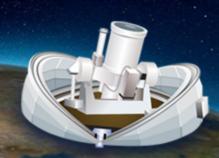


Status and Progress of ARGO-M System Development

2011. 12. 06

Korea Astronomy & Space Science Institute(KASI)

















Overview of ARGO Program



ARGO (Accurate Ranging system for Geodetic Observation)

Development Phase

2008 - 2014 (7years)



Final Goal

- One mobile system(40cm/10cm) : ARGO-M
- One fixed system(1m): ARGO-F

Objectives

- Space geodesy research and GEOSS/GGOS contribution by laser ranging for satellites with LRA
- Precise obit determination(POD) through laser ranging measurement with mm level accuracy
- Contribution to international SLR societies and ILRS network participation

Development Strategies

- KASI and other governmental institutes in developing the ARGO-M system
 - KIMM (Korean Institute of Machinery & Materials): Tracking Mount
 - KRISS (Korea Research Institute of Standards and Science): Telescope Mirrors
- (Semi) Turnkey based system with SLR/LLR capability for ARGO-F
- Cooperates with foreign institutes in China, Austria, Swiss and other countries

Major Characteristics of ARGO-M



ARGO-M Structure (6 subsystems)

OPS(OPtics System), TMS(Tracking Mount System), OES(Opto-Electronic System), CDS(
 Container-Dome System), LAS(Laser System), AOS(ARGO-M Operation System)

Tracking Capability

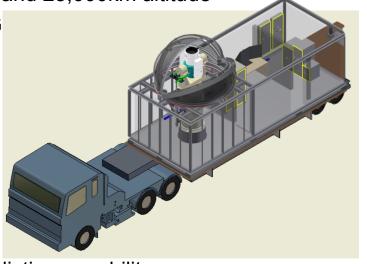
Capable of tracking satellites between 300km and 25,000km altitude

STSAT-2(300x1,500km), KOMPSAT-5, G

- KHz laser ranging
- Daylight and night tracking

Ranging Accuracy

- Lageos : 10mm(SS), 5mm(NP)
- Ground Target: 3mm(SS), 1mm(NP)
- Operational Functions
- Can be controlled from the remote site
- Automated scheduling, planning and orbit prediction capability
 - Automatic ranging based on schedule and aircraft detection(using radar)
 - Automated diagnostic warning to monitoring system
 - Etc
 - Container and central locking dome (move by using a trailer)

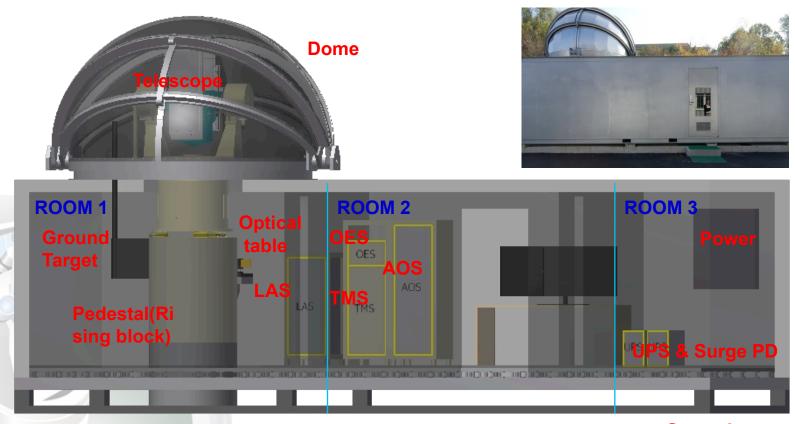


ARGO-M System Integration



ARGO-M Structure

- Room1(Laser room): TMS, LAS, optical table, ground target
- Room2(Operation room): OES, TMS, AOS devices
- Room3(Accessory room): Power distribution panel, UPS, Surge protection devices



Pier

Ground Supports

ARGO-M System Integration













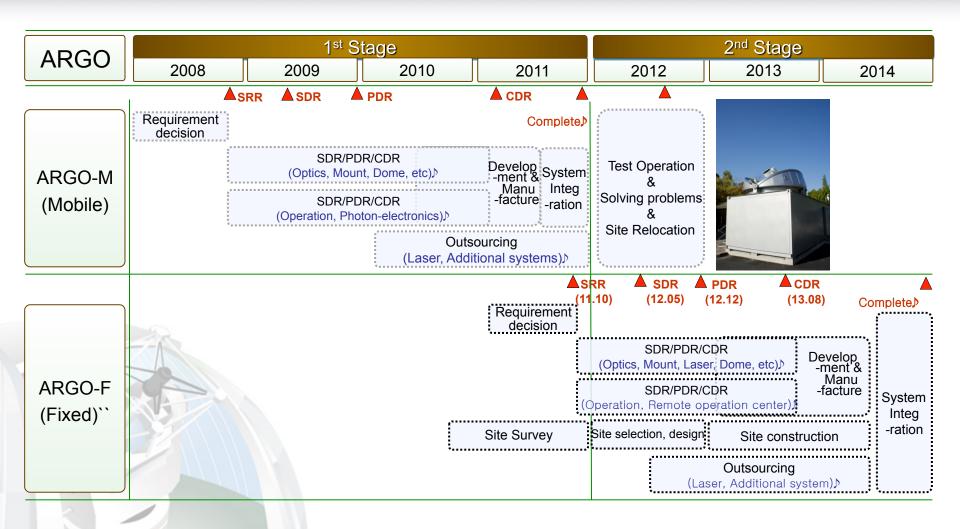






Milestone of ARGO-M Program





Milestone of ARGO-M Program



ARGO-M Design Review

- System Requirement Review : 2008.09
- System Design Review : 2009.05
- Preliminary Design Review : 2009.12
- Critical Design Review : 2011.03

ARGO-M System Integration

- Container for ARGO-M site installation: 2011.08.05
- Dome installation : 2011.09.22
- Telescope, tracking mount installation : 2011.10.05
 Present
- Tracking mount, dome, laser interface
- Alignment Telescope, coudé light path

ARGO-M System Test Operation

- test operation and resolving problems (~ 2012.07)
- Relocate ARGO-M system to official site (~ late 2012, Sejong city with VLBI)
- Official Operation for ILRS Societies (late 2012 ~)



ILRS Support for GALILEO: first impressions

Report to Governing Board Tuesday December 6, 2011

Graham Appleby



ILRS tracking to date

(Nov 28 – Dec 5) GALILEO-101

Sat	Station	PAD_I	D	Wave	Passes	Points
GALILEO	Yarragad	7090)	5320	3	16
GALILEO	Mt Strom	782	5	5320	1	4
GALILEO	Herstmor	n 7840	С	5320	1	6
GALILEO	Matera	794	1	5320	6	20
					11	46

ILRS tracking to date

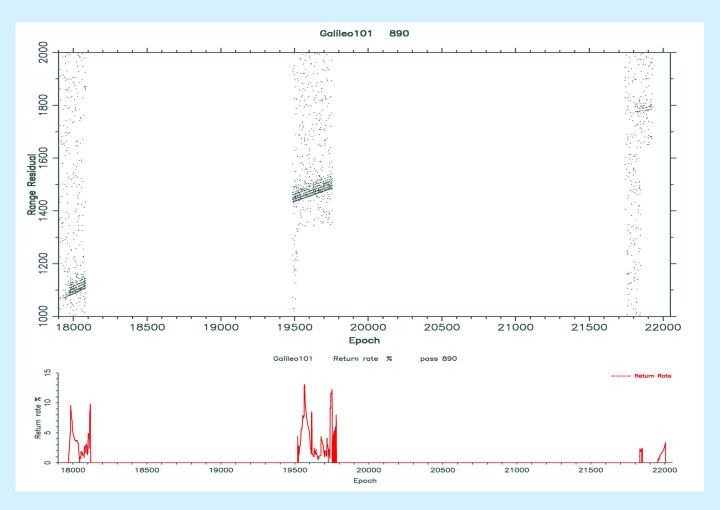
(Nov 28 – Dec 5) GALILEO-102

Sat	Station	PAD_I) Wave	Passe	es Poir	nts
GALII FO	Yarragad	7090	5320	2	11	
	Concepci			1		
GALILEO	Mt Strom	7825		1	3	
GALILEO	Herstmon	7840	5320	2	9	
GALILEO	Matera	7941	5320	1	3	
	-			 7	 36	

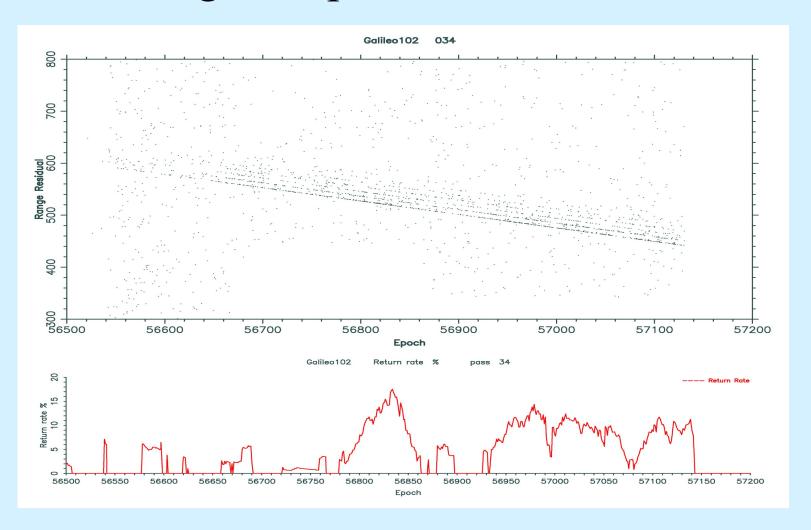
Some statistics from Herstmonceux

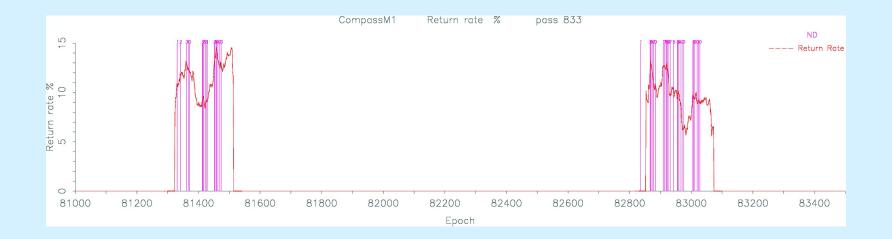
- Tracking achieved in daytime as well as at night
- Impression is that signal strength is at least as good as COMPASS-M1:
 - A detailed published study (ASR, 2011) using return-signal showed that the COMPASS-M1 cubes are the most efficient currently in GNSS orbit
 - Average return-rate for Hx 14Hz system:
 - COMPASS-M1: 5-15%; GALILEO: 5-15%

Tracking O-C plot for GALILEO 101



Tracking O-C plot for GALILEO 102





Some relative statistics

- There are 42 cubes on COMPASS-M1, diameter 33mm, un-coated;
- There are 84 similar cubes on GALILEO 101 and 102
- Extra height of GALILEO implies a signal 0.75 x that from COMPASS (23,200 vs 21,500 km)
- 2x number of cubes on GALILEO then implies 2x0.75 =
 1.5x signal of that from COMPASS
- Very early results from SGF do not contradict this analysis

LLR - Status Report

Jürgen Müller

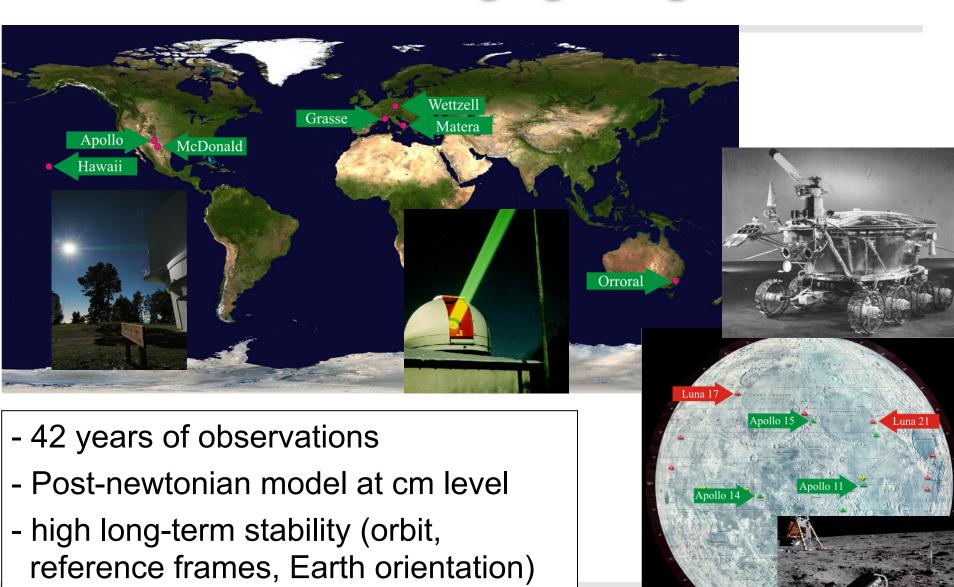
Institut für Erdmessung (Institute of Geodesy)

Leibniz Universität Hannover (University of Hannover)



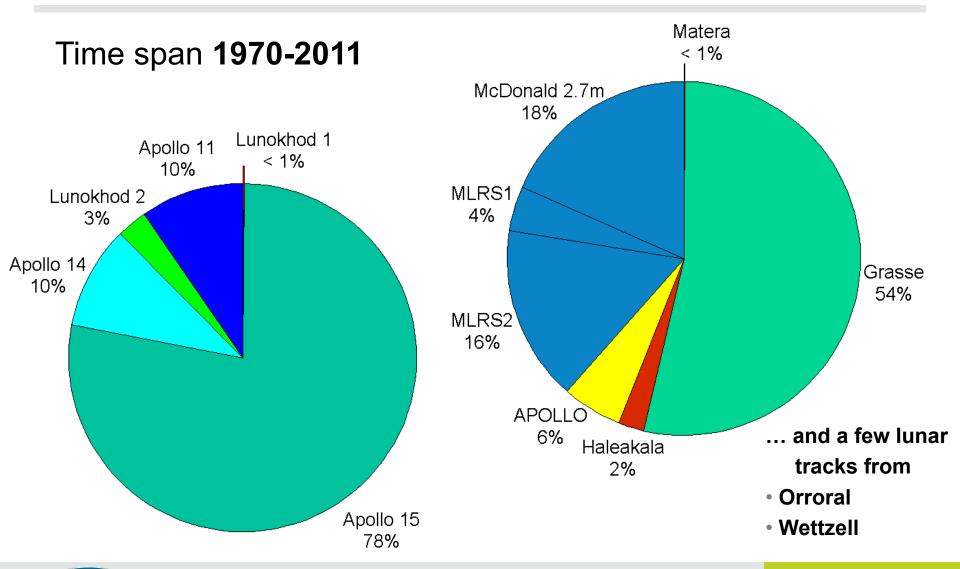


Lunar Laser Ranging – in general



- relativity tests

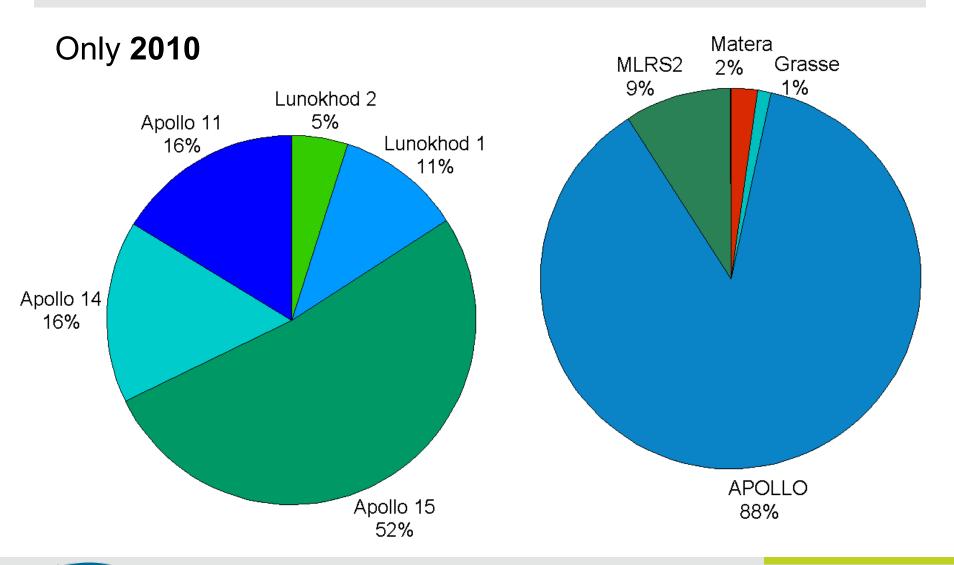
Statistics - retro-reflectors and observatories







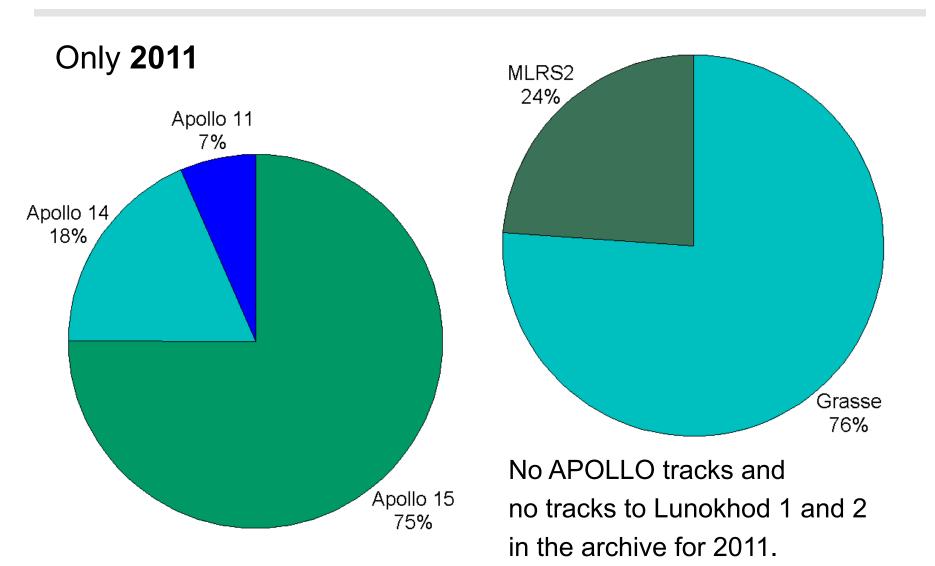
Statistics - retro-reflectors and observatories







Statistics - retro-reflectors and observatories

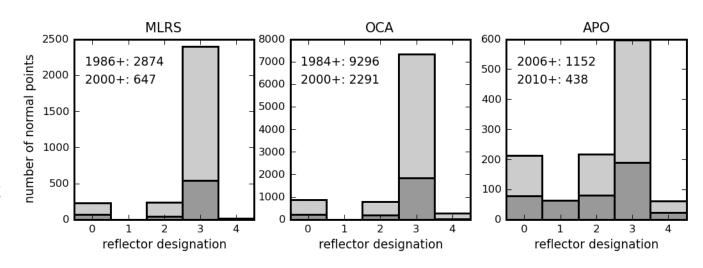


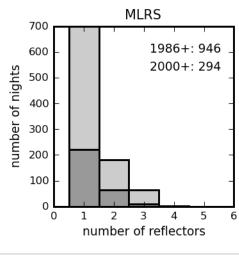


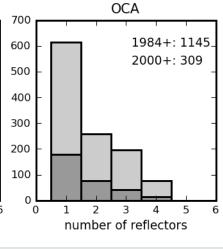


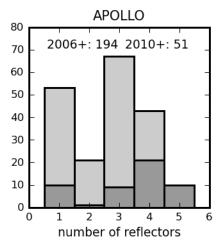
Statistics – retro-reflector acquisition

Number of normal point measurements per reflector for the major LLR sites dark shade is only "recent years"









Number of reflectors acquired per night of observation

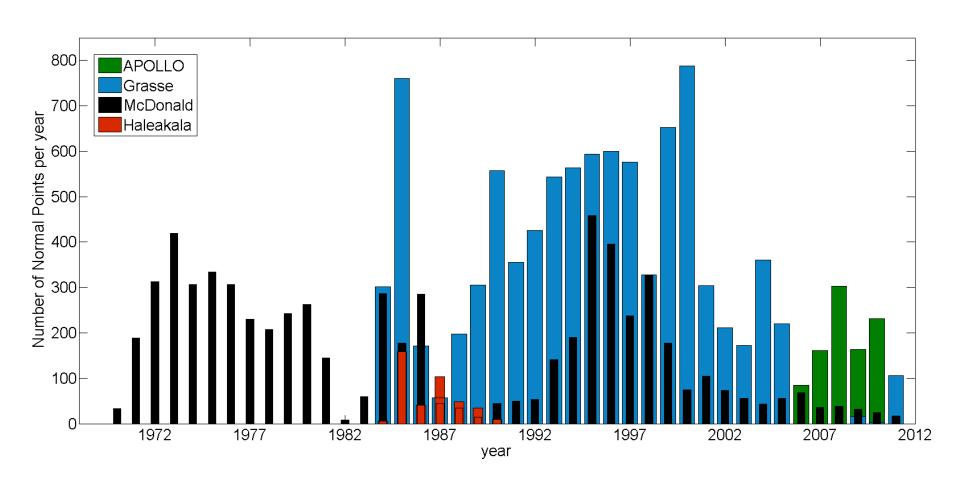
dark shade is only "recent years"





Number of normal points

1970 - 2011: ca.17,000 normal points







Status, perspective at the LLR sites

- McDonald continued lunar tracking (at low level only) as well as LRO tracking
- APOLLO good LLR data, also LRO tracking
- Grasse is back into the game since end of 2009, but less LLR tracking in 2010
- Matera re-started LLR tracking in spring 2010, but not routinely at the moment
- Wettzell will soon resume first attempts have been made





Perspective for the LLR retro-reflectors

- Future lunar missions, e.g., pushed by Google Lunar X Prize (http://en.wikipedia.org/wiki/Google Lunar X Prize) may damage the retro-reflectors on the moon in the worst case (casting of dust onto, shift of retro-reflectors, etc.). In the best case, those missions could also be helpful for us (visual inspection or even "cleaning" of retro-reflectors, ...).
- NASA report (NASA-USG_lunar_historic_sites.pdf) shows awareness of the ongoing LLR effort and the importance of the LLR sites on the moon.
- Position of ILRS?
 ILRS should support appropriate treatment of retro-reflectors.





Further activities

- ISSI workshop series on LLR modelling and analysis (start 2009), final meeting in spring 2012
- Boston workshop 2010 on comparison of LLR software packages
- ILRS initiative on LLR data qualification
- In Germany: New DFG Research unit "Reference systems" (speaker A. Nothnagel, Bonn) with 2 LLR related projects
 - Moon related systems
 - Barycentric ephemeris will start in spring 2012.





Available software at the analysis centers

Software packages for LLR data analysis

- Hannover: LUNAR
- Paris: INPOP
- Pasadena: JPL software (cooperation with NAOJ)
- Harvard CFA: PEP
- MIT: PEP
- Austin, Univ. Texas: a version of PEP (in the past)

Comparison of post-fit residuals in 2010 (ISSI inspired and Boston workshop) showed major differences.





Main research at lunar analysis centers

- Jet Propulsion Laboratory (JPL)
 - lunar interior, lunar core
 - relativity
- Paris Observatory Lunar Analysis Center (POLAC)
 - libration theory
 - reference frames
- Institute of Geodesy (IfE)
 - Earth orientation
 - lunar interior
 - relativity
- Others: special topics ...





LLR tests of general relativity

Strong equivalence principle

$$\eta = (1 \pm 5) \times 10^{-4}$$

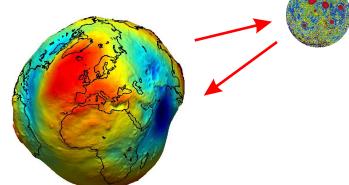
$$\left[\frac{M_G}{M_I}\right]_{SEP} - 1 = (-0.5 \pm 2.3) \times 10^{-13}$$

Temporal variation of the gravitational constant

$$G = G_0 \left(1 + \frac{\dot{G}}{G} \Delta t + \dots \right)$$

$$\frac{\dot{G}}{G} = (1 \pm 4) \times 10^{-13} \,\text{yr}^{-1}$$

Factor 2 improvement due to refined modelling and more LLR data



Hofmann, Müller, Biskupek, Astron. & Astroph., 2010









Grasse/MEO and tracking RadioAstron in November 2011

F. Pierron and Grasse Laser staff



Grasse/Meo Laser Ranging station for Operations from 400 km to the Moon...





- Specific configuration for poor orbit predictions like Radioastron
 - -Large Field of view and very sensitive camera
 - -Spad detector with gating high voltage tuned to decrease dark noise
 - » Range gate of 30m (100 ns) on standard target .
 - » Range gate of some kilometers with gating voltage decreased Real time tunable when echoes detected..

Grasse/MEO and tracking RadioAstron in November 2011



Usual RadioAstron Range:

50 000 km/300 000 km

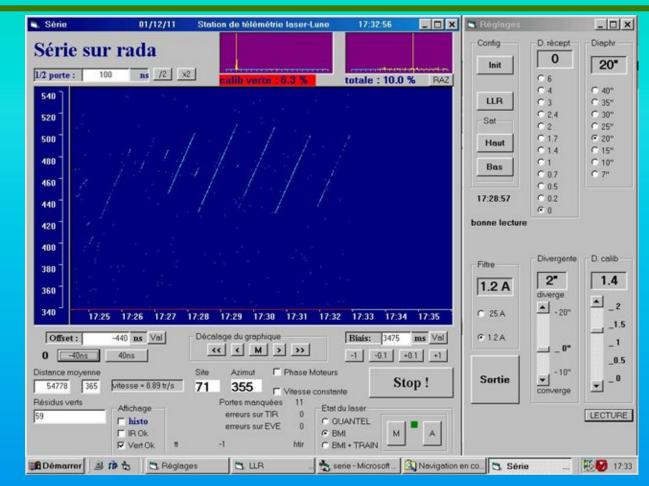
Predictions accuracy:

Time Bias:

~ 1 to some sec of time

Visibility with camera:

- -easy with Meo system
- -Very Helpful

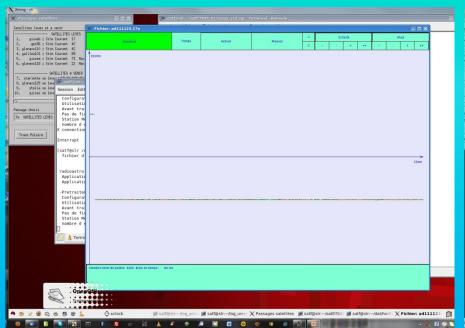


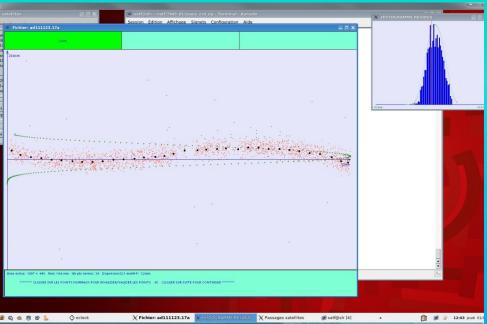
Real Time display on Meo software with:

TB: 3457 ms and steps of 80 ns/every minute of time

Grasse/MEO and tracking RadioAstron in November 2011 Preprocessing and normal points computation







Plot with no corrections in Time or Range Bias (Vertical Scale: +/- 4 km)

Final iteration with orbit adjustment and Normal points computation

-Vertical scale : 20 cm -Returns number : 2000

-RMS: 12 mm

-Normal points: 1900 in 33 minutes

First Radioastron echoes with Meo on November 15 th 2011 ~ five 30 mn sequences from the beginning