

The importance of ground surveys and how we do them?

J. J. Eckl, T. Klügel, S. Mähler, T. Schüler

Geodetic Observatory Wettzell

Federal Agency for Cartography and Geodesy





Geodätisches Observatorium Wettzell

(Bayerischer Wald)



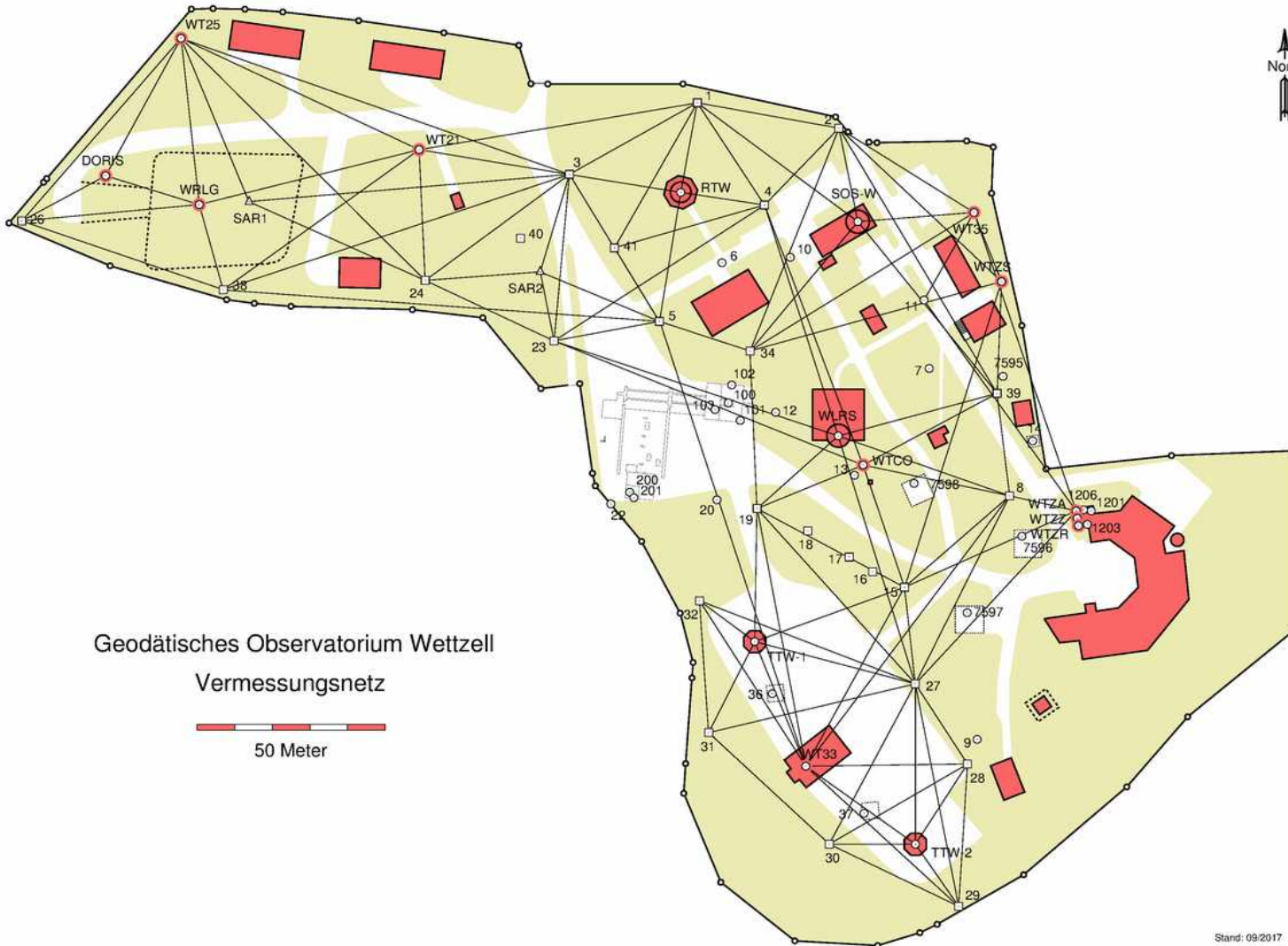
- | | | | |
|--|------------------------|---|--|
| 1 Zeitkeller | 4 Gravimeter 1 | 7 Wettzell Laser Ranging System (WLRs) | 10 Betriebsgebäude Radioteleskop |
| 2 Turm mit Globales Navigationssatellitensystem (GNSS) | 5 TWIN-Teleskop 1 | 8 TWIN-Teleskop 2 | 11 Das 20 m-Radioteleskop Wettzell (RTW) |
| 3 Hauptgebäude | 6 TWIN-Betriebsgebäude | 9 Satellite Observing System-Wettzell (SOS-W) | 12 Großringlaser G |

Weiterführende Informationen

Bundesamt für Kartographie und Geodäsie - Geodätisches Observatorium Wettzell - Sackenrieder Straße 25 • D-93444 Bad Kötzing • www.bkg.bund.de • www.fs.wettzell.de



Introduction - Local Tie Network -





Introduction - measurement equipment -

- Total Station, Laser-Tracker, Retro-Reflectors
- Angle & Range measurement



GNSS-monuments: simple

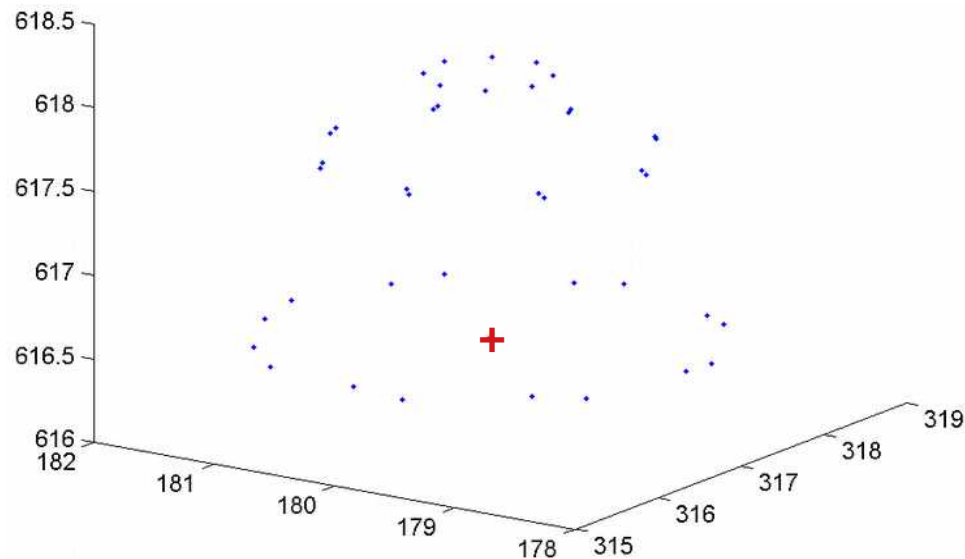


VLBI- (or SLR-) telescopes: difficult

- Reference point: IVP (invariant point)
 - Intersection of azimuth and elevation axis
 - Not directly accessible
- observation of targets at the moving telescope
- construction of the invariant point
- Several hundred measurements per IVP determination



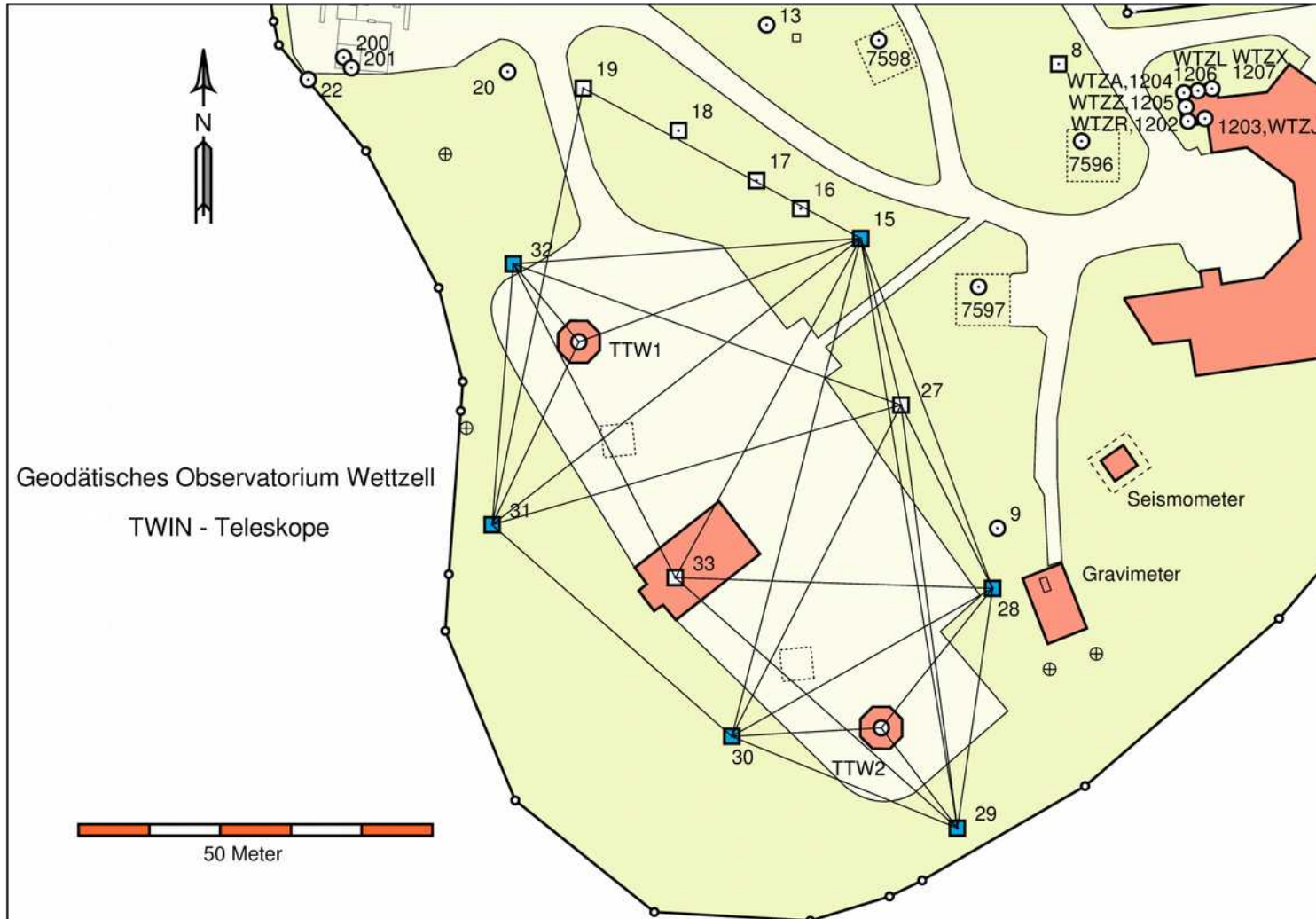
- Mount a Retro-Reflector on the telescope
 - Rotate in Azimuth & Elevation
 - Measure from several different directions
- Result: Sphere with System Reference Point as center
Example: Satellite Observing System Wettzell



Requirement: Both axis do intersect!

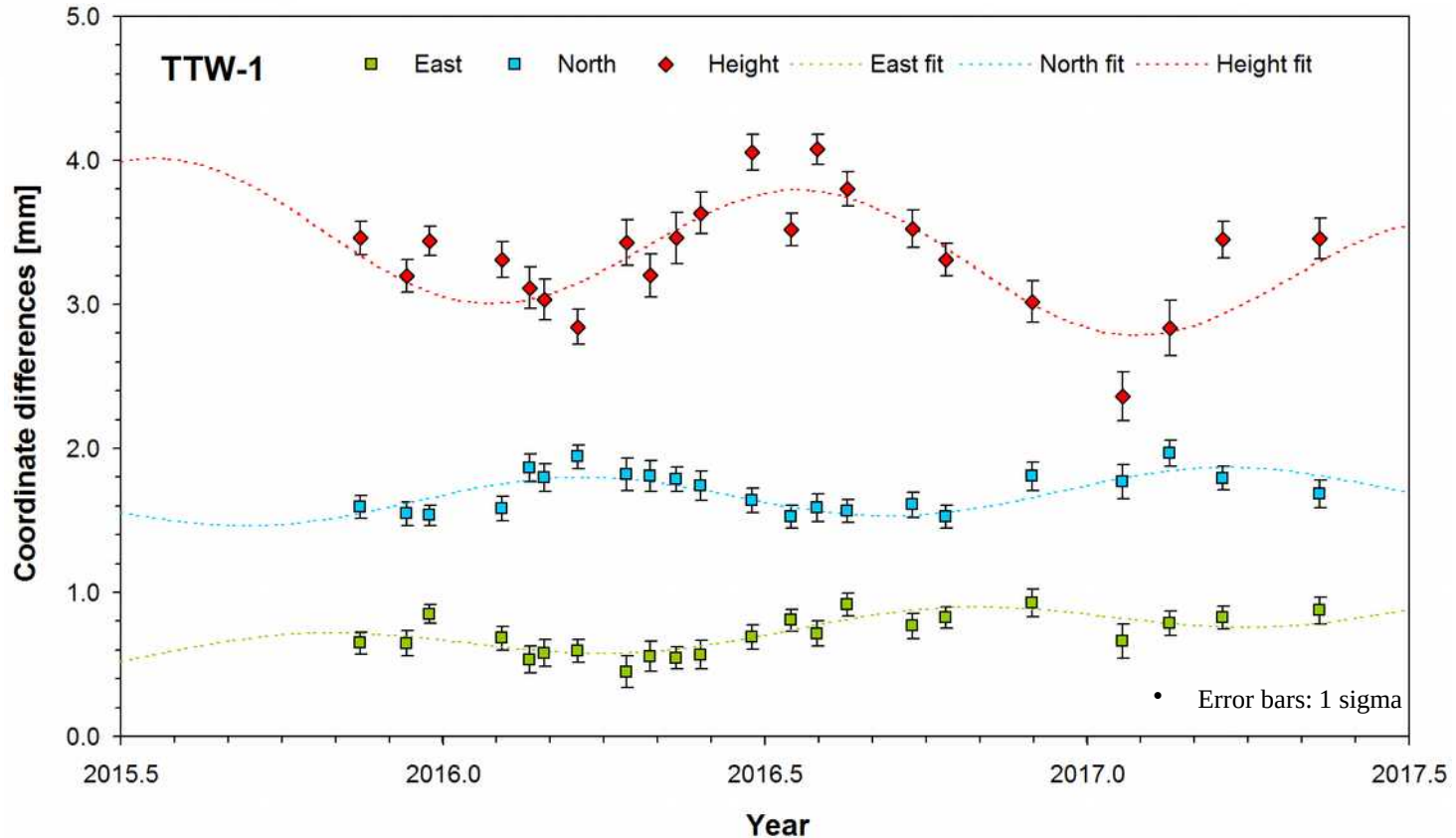


Monitoring Network - example TWIN Radiotelescopes -





VLBI Permanent Monitoring - reference point TTW-1 -



- Least-square-fit: $y = a + bt + c \cos(\omega t) + d \sin(\omega t)$ • mit $\omega = 2\pi / \text{Jahr}$

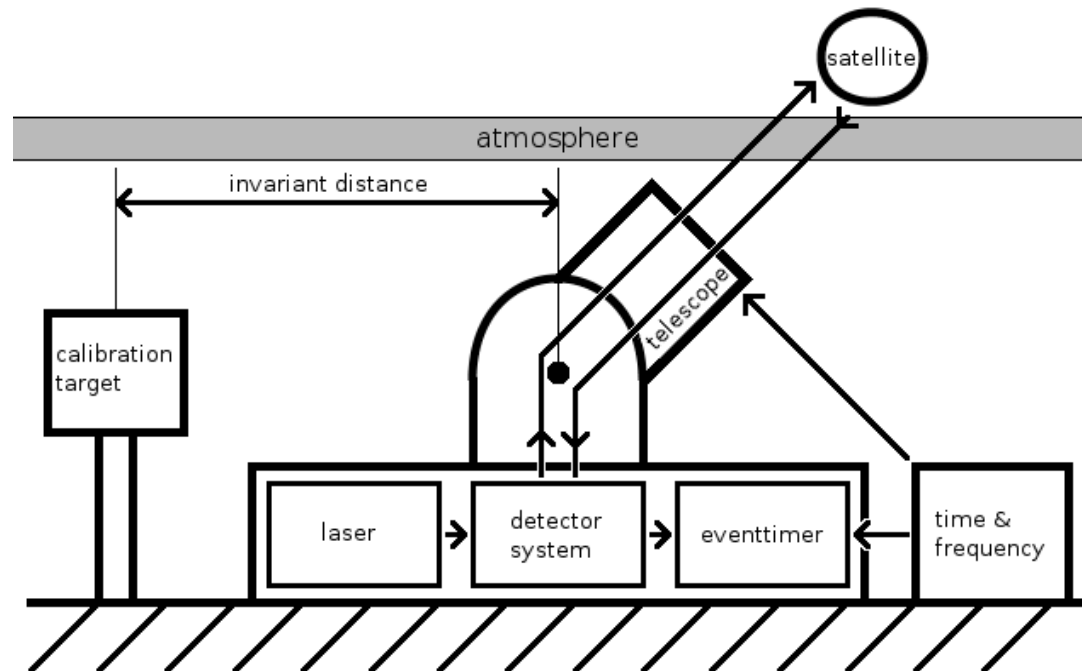
[LOSSIN, 2013]

Component	b [mm/y]	c [mm]	d [mm]	Amplitude [mm]	Phase [°]	rms error [mm]
TTW-1 East	0,18	0,031	-0,108	0,11	285,9	0,086
TTW-1 North	0,07	0,037	0,147	0,15	76,0	0,091
TTW-1 Height	-0,22	-0,405	-0,193	0,45	205,4	0,246

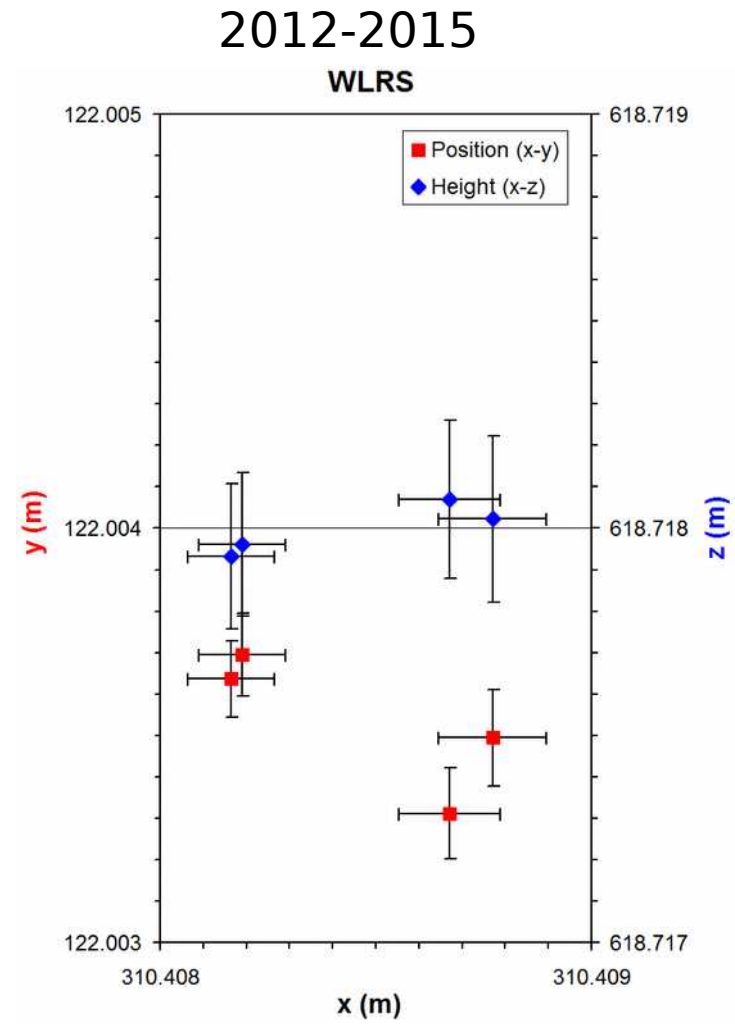
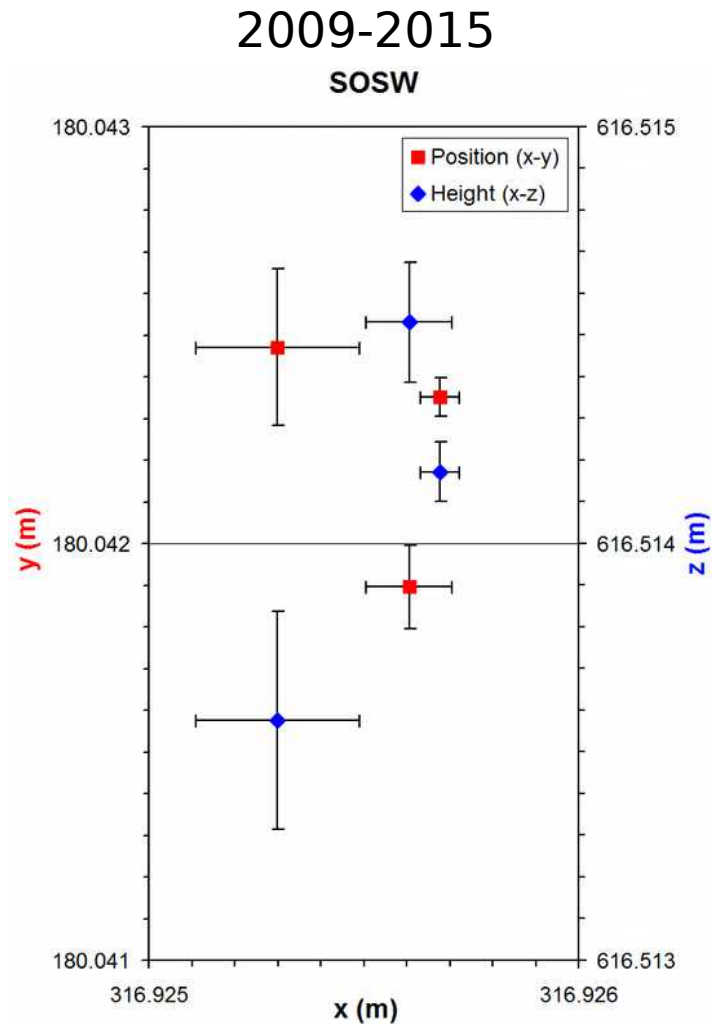


Satellite Laser Ranging - principle -

- Time of flight measurement to determine the distance to objects in space.
- Reference is time of flight measurement to target of well known distance

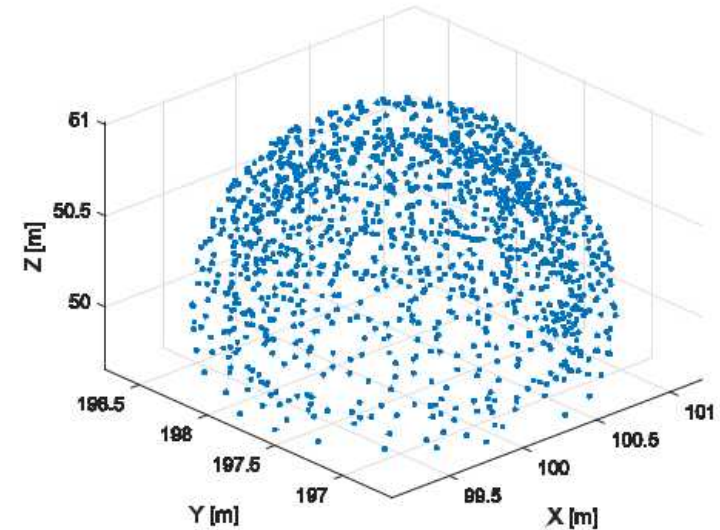


Satellite Laser Ranging - reference point stability -





Satellite Laser Ranging - SOSW axis intersection -

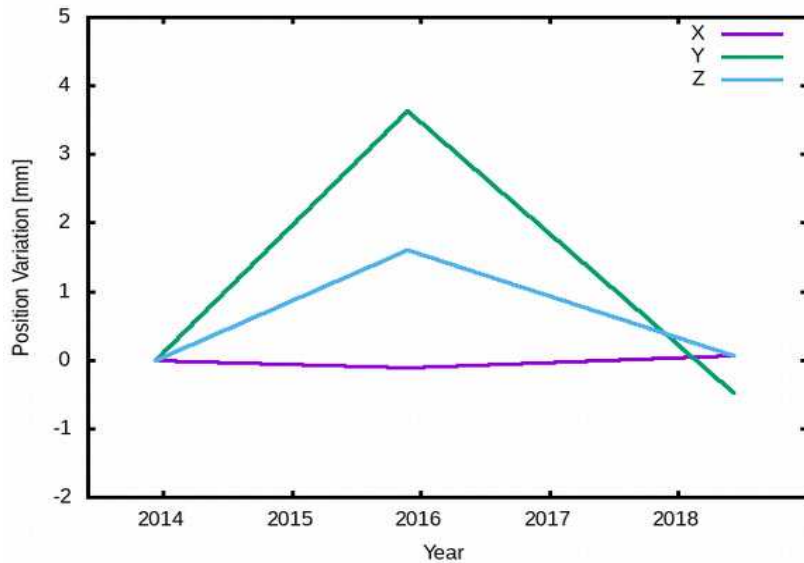
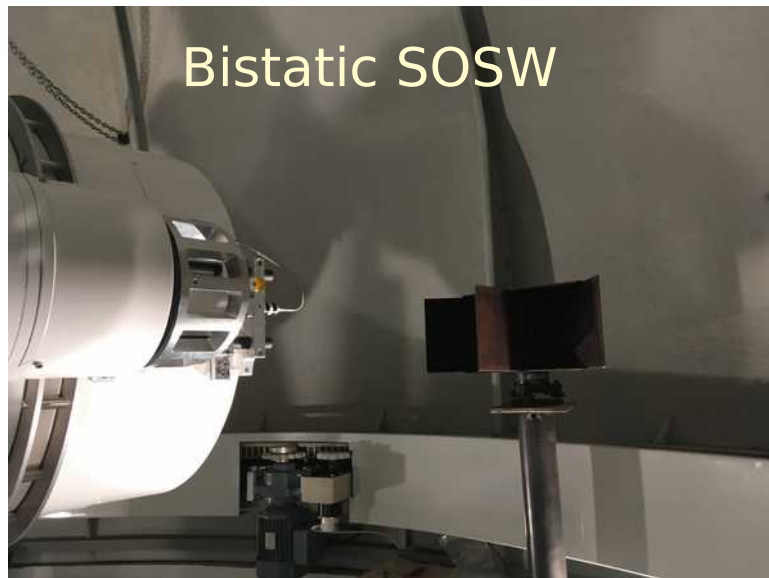


	X in m	Y in m	Z in m	e_{AO} in mm
IRP-I	100.16246	197.69374	50.01237	-0.03
IRP-II	100.16246	197.69376	50.01234	-0.02
Sphere	100.16247	197.69375	50.01234	—

[LÖSLER, “A Modified Approach for Process-integrated Reference Point Determination”]



Satellite Laser Ranging - in-dome calibration targets -





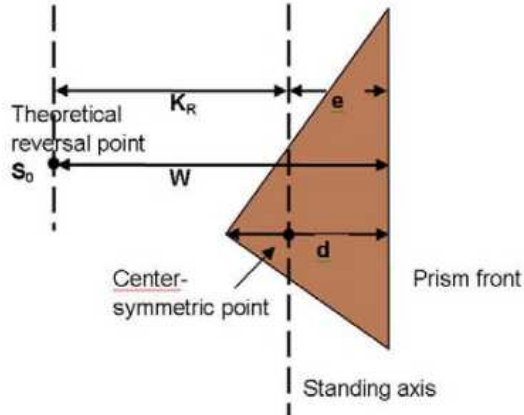
Satellite Laser Ranging - common calibration target -

Custom target on motorized rotation stage
→ reflector constant TBD

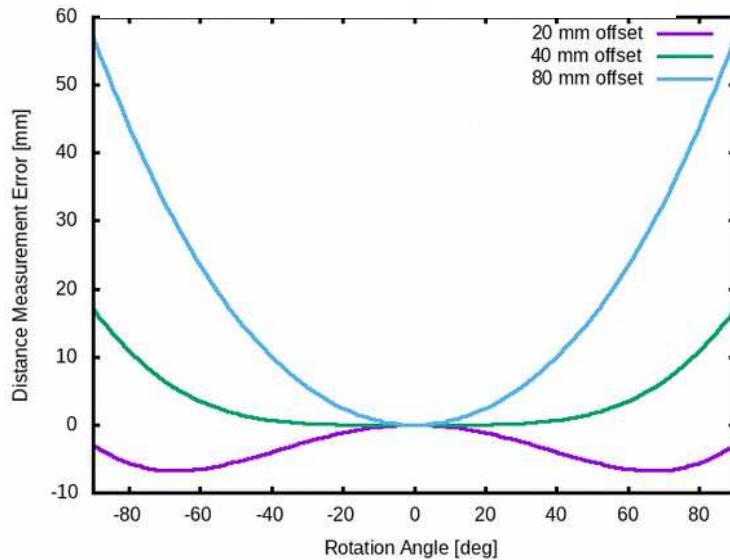




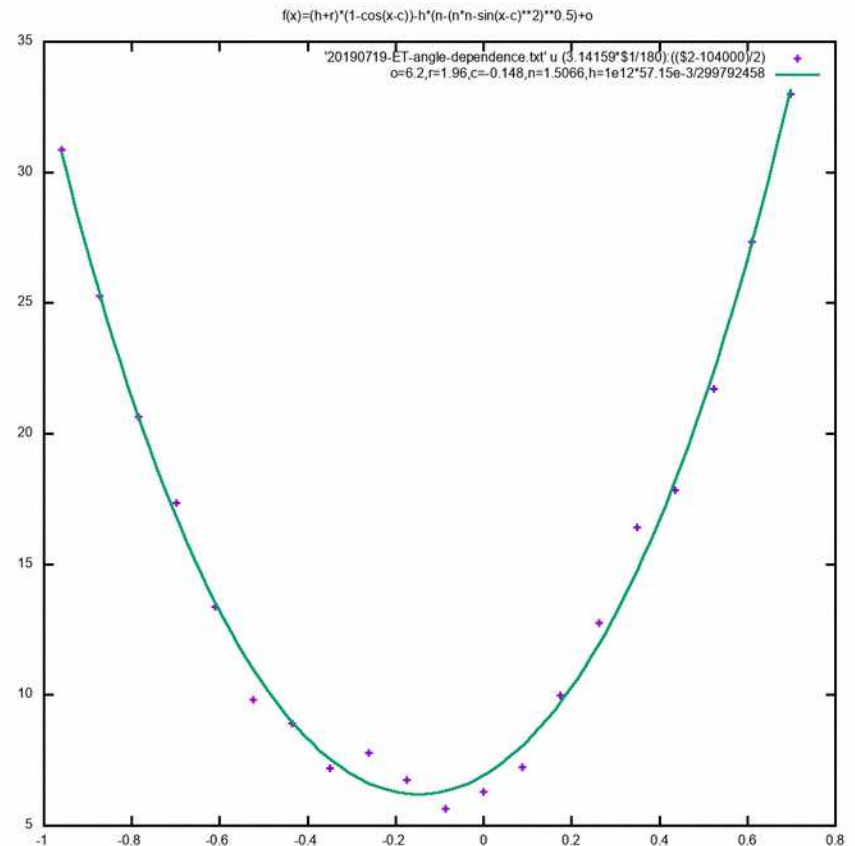
Satellite Laser Ranging - reflector tilt measurement -



$$\Delta d = e \cdot (1 - \cos \alpha) - d \cdot \left(n - \sqrt{n^2 - \sin^2 \alpha} \right)$$



[LEICA, "Surveying Reflectors"]





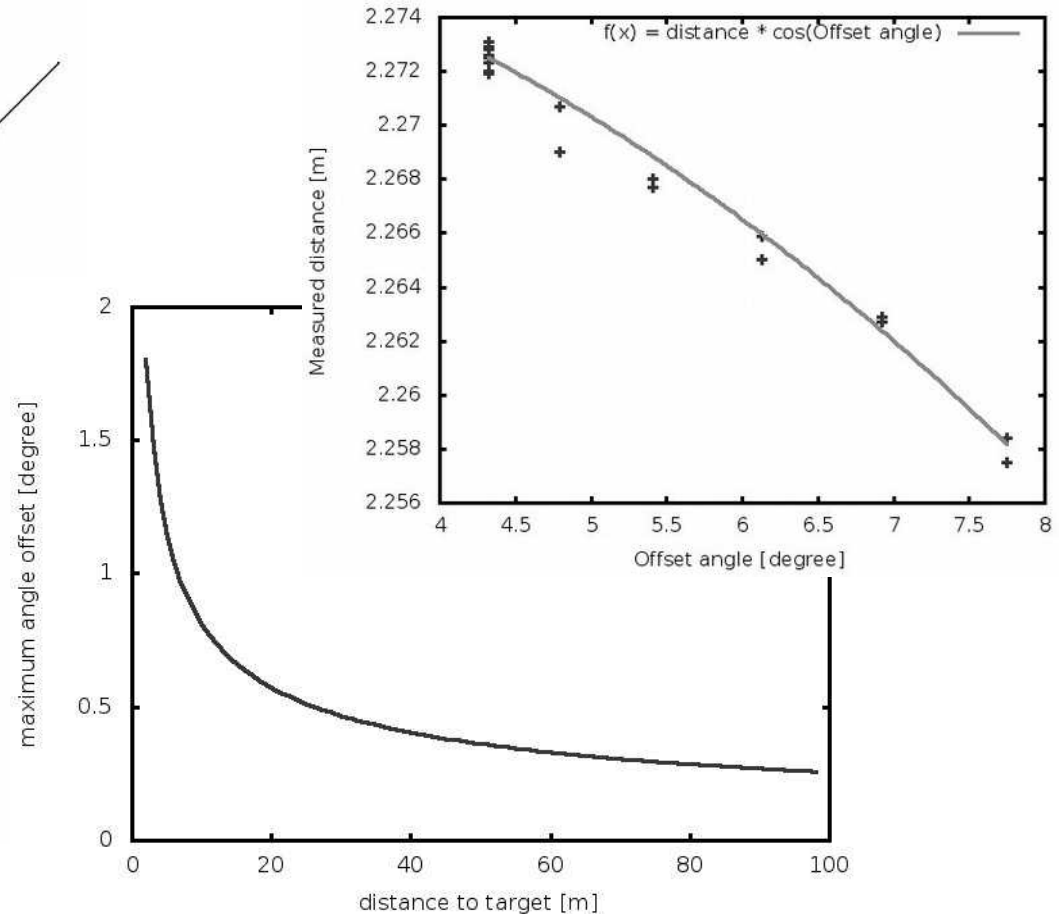
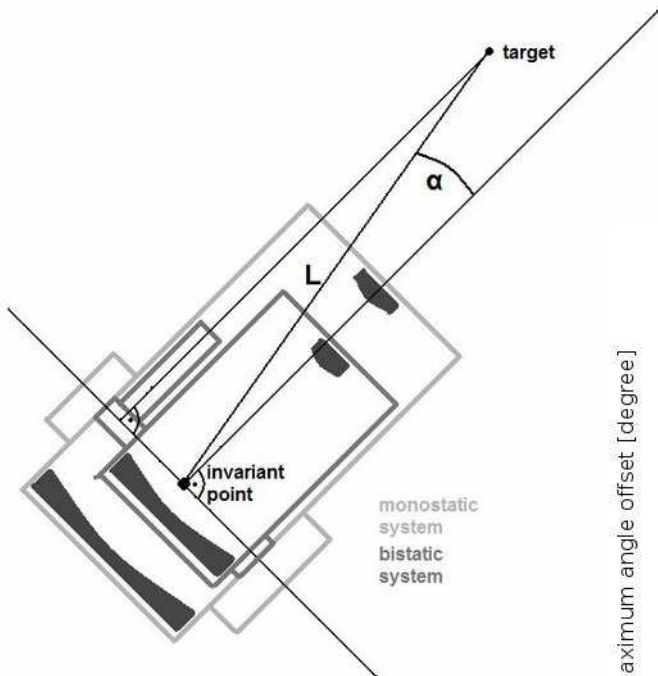
Satellite Laser Ranging - bistatic calibration target -

Attention:

- telescope azimuth pointing towards reflector position
 - close to 0 degree elevation
- Else: geometry bias



Plane wave front in the near-field cause geometry bias in case of offset pointing





- System Reference Points seem to be stable at the 1 mm level (massive objects)
- Further verification of the stability of the Calibration Targets needed
→ especially sub-daily, seasonal variation
- Permanent monitoring of selected points planned
→ Redesign of Common Target (Station Fiducial) in progress
- Long-Term Goal: definition of a space-time reference point



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