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Requirements for CubeSats: the Astrocast CubeSat Mission

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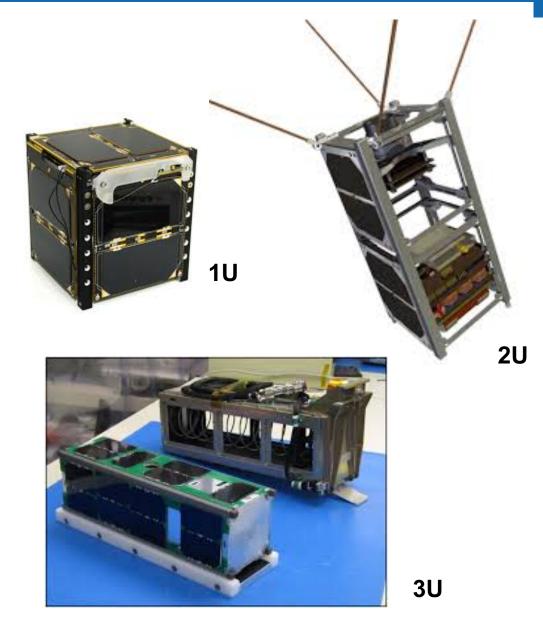
Overview

- Introduction: cube satellites
- Requirements for SLR observations and corner cubes
- Example: Astrocast Mission
- Mission Goal: Orbit Determination with low-cost GNSS
- SLR Orbit Validation
- Conclusions and Outlook

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Introduction: Cube Satellites

- Standard for nano-satellites
- Defined in 1999 by California Polytechnic State University (Cal Poly) and Stanford University
- 1 unit (1U) Cube Satellite: Size: cube of 11.35 cm × 10 cm × 10 cm Weight: max. 1.33 kg
- 2 units (2U) Cube Satellite: Size: 22.7 cm × 10 cm × 10 cm Weight: max. 2.66 kg
- Today cubesats may have 6, 12, 27 units
- Usually COTS components are used
- Mainly used for **in-orbit demonstrations**

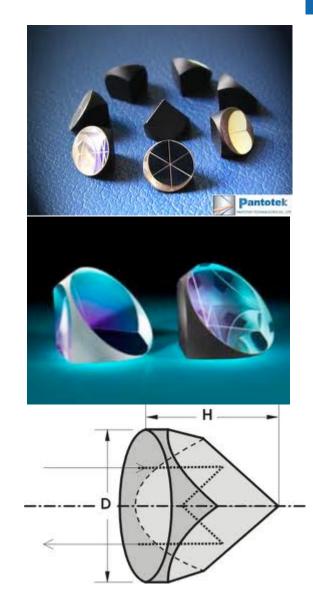


SLR Requirements for CubeSats

- Very **limited space** for retroreflectors, most surfaces for solar cells
- Aberration angle to be compensated ~25-50 µrad (5"-10")
- Effective cross section should be about 50'000 m² at aberration angle
- Use of **small 10 mm diameter prisms**, coated on the back
- Available from:

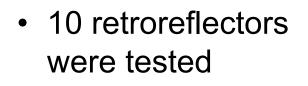
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- Hengrun Optoelectronics Tech. Co., accuracy ±3", price € 60.-
- Stock Optics Ltd, UK, accuracy ±3", price €135.-
- For non-stabilized cubesats, at least one retroreflector on each surface

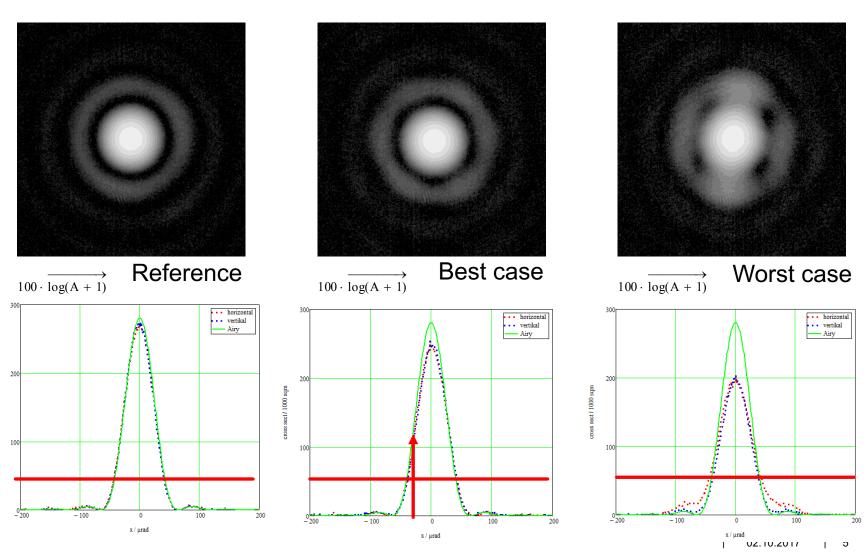


Retroreflector Quality Test (Ludwig Grunwaldt, GFZ)

- Laboratory setup at GFZ Potsdam
- Far Field Diffraction Pattern (FFDP) images obtained



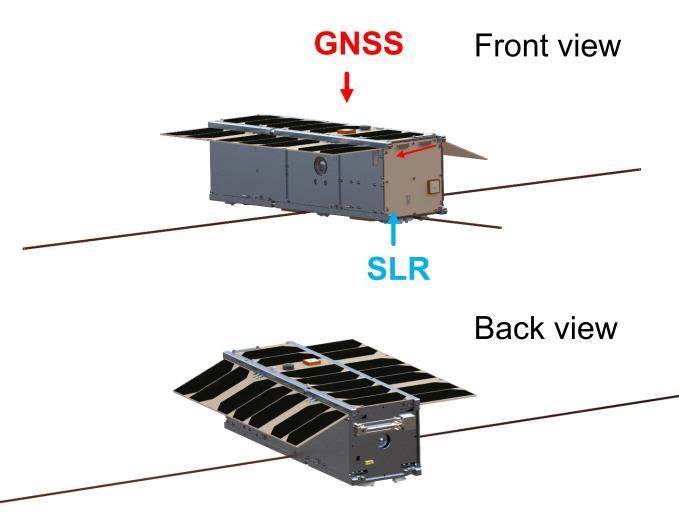
 Only 1 bad piece detected



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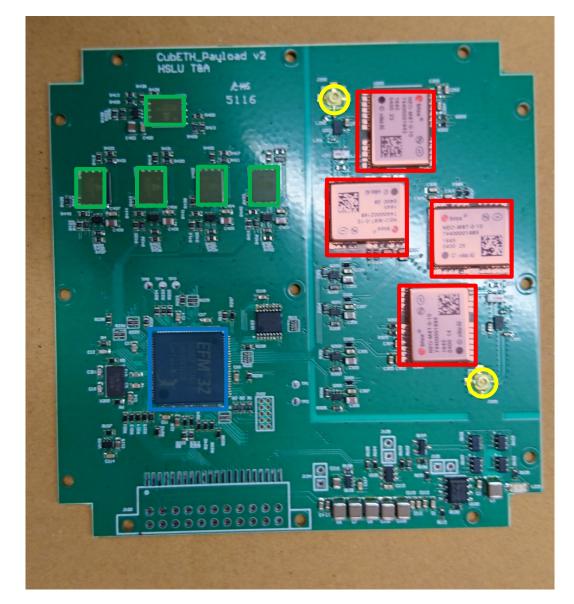
Astrocast Satellite

- 3-Unit CubeSat
- Sun-synchronous orbit at 575 km height
- Full attitude control
- Propulsion system
- S- and L-band downlink
- 2 GNSS antennas (top and front)
- Mounting with 3 SLR retroreflectors
- Launch: June 2018



GNSS Payload Board

- 4 u-blox single-frequency multi-GNSS receivers (low-power, low-weight, inexpensive; redundancy)
- 2 antenna HF inputs (top, front antenna), two receivers per antenna
- 2.5 MB MRAM onboard memory
- ARM Cortex-M3 CPU
- Latchup protection
- Major task: space environmental tests (radiation, vacuum, temperature, ...)



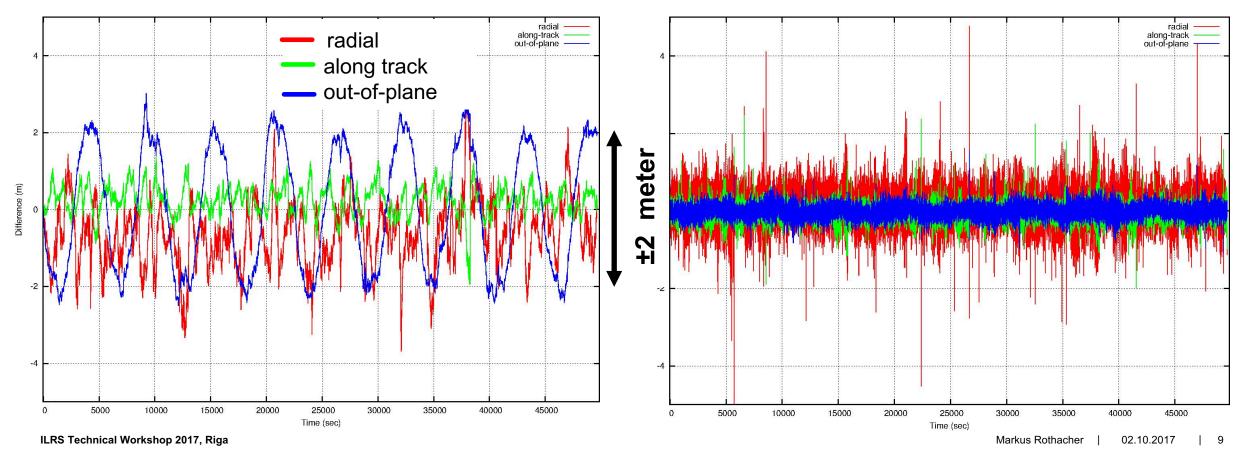
Mission Goals with GNSS Payload

- First multi-GNSS receiver in space: GPS, GLONASS, Galileo, Beidou, QZSS
- Precise orbit determination with COTS-based single-frequency receiver
- Compare the orbits derived from different GNSS
- Validation of the orbit accuracies with SLR
- Validation of propulsion system
- Sidewise-looking antenna: S/N analysis at low elevations (occultation scenario)
- Short baseline in space: antenna phase center calibrations, multipath
- Keep in mind: main error sources are ionospheric refraction and broadcast satellite orbits and clocks (2-3 m)

Orbit Determination: GPS Signal Simulator Tests

u-blox navigation solution. The out-of-plane component is affected by a 1/revolution error.

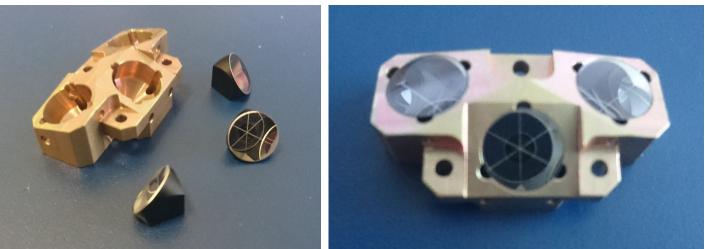
Code solution computed with Bernese out of signal simulator raw data. The RMS is 0.44 m (radial), 0.21 m (along-track) and 0.15 m (out-of-plane).

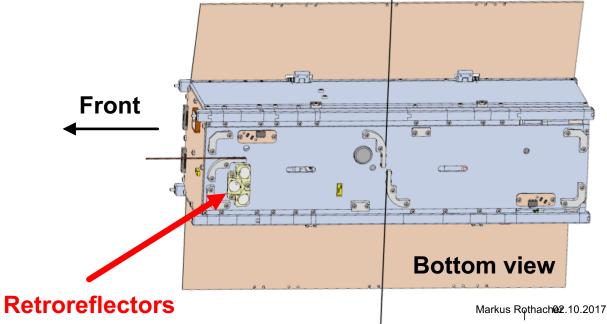


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Laser Retroreflectors

- Mounting for three corner cubes
- One front-looking reflector
- Two side-looking reflectors
- Inclination 20° w.r.t. to surface normal
- 1 cm diameter
- JGS1 optical glass

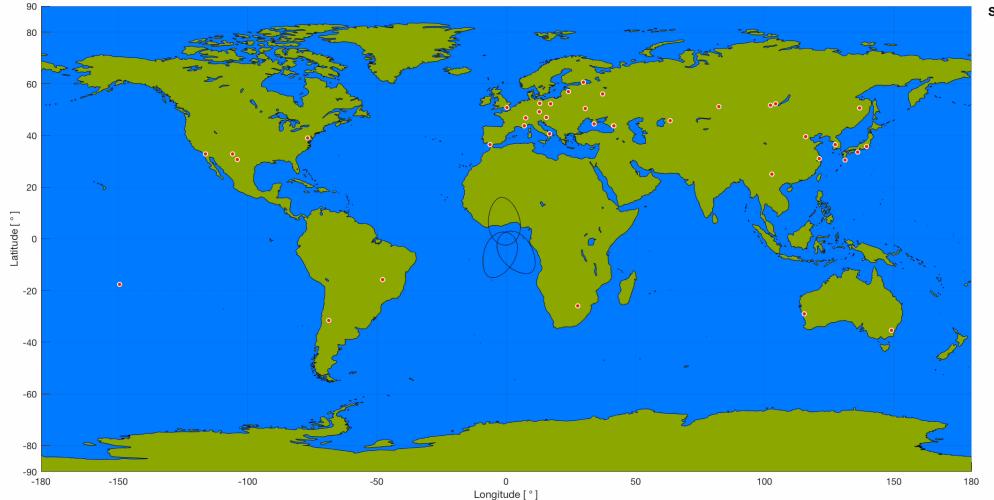




ILR:

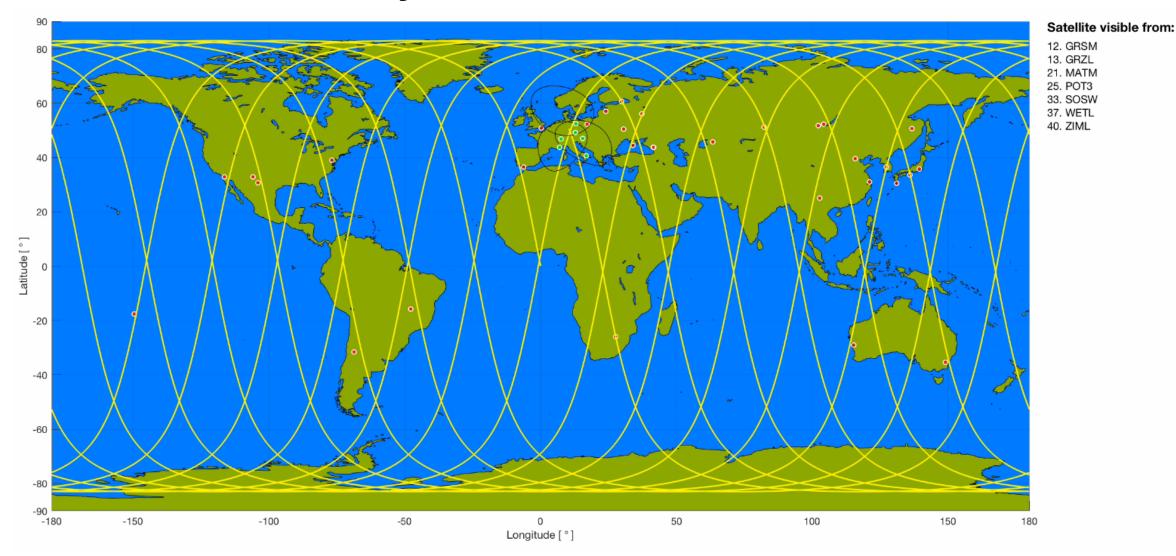
SLR Satellite Visibility Simulation

Time: 00d 00h 00min 00s

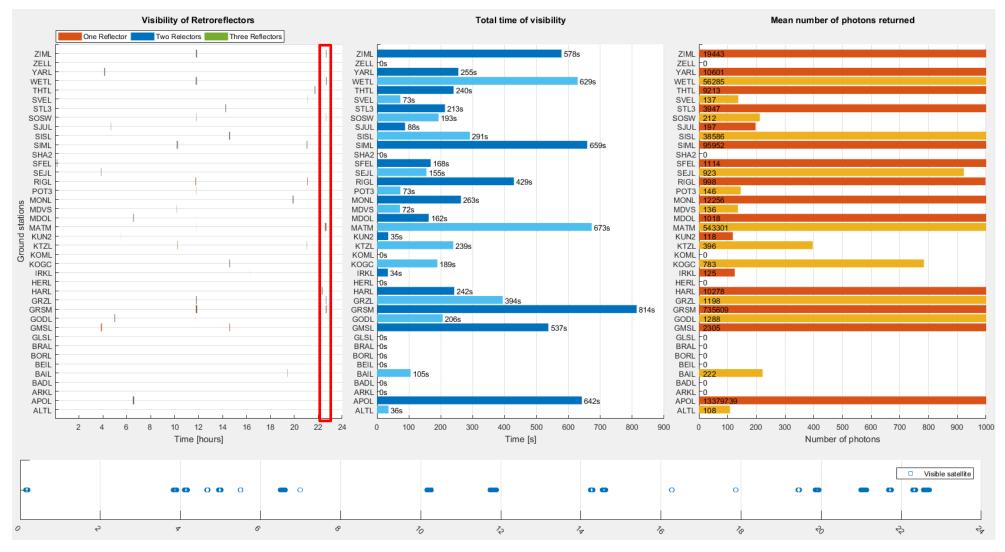


Satellite visible from:

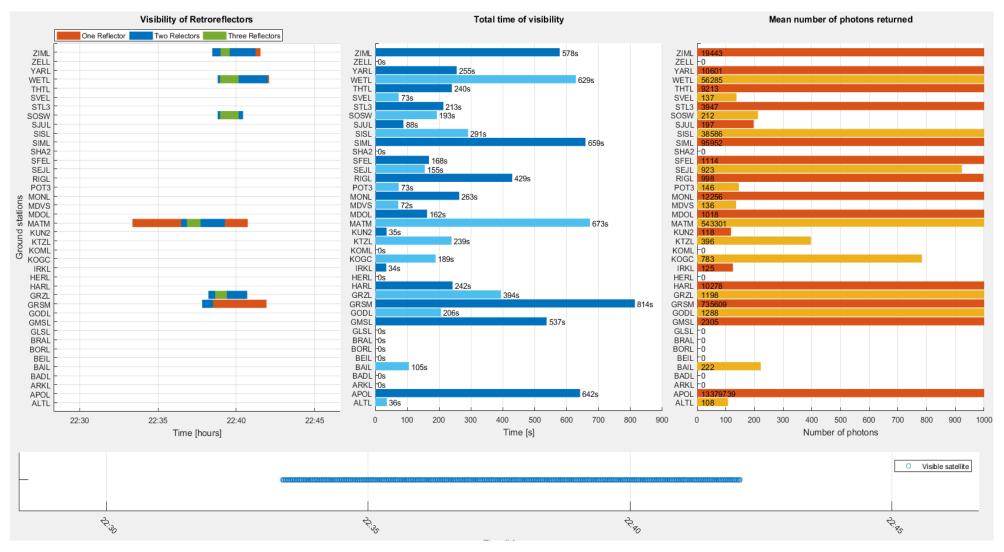
SLR Satellite Visibility Simulation: 22:40



SLR Satellite Visibility Simulation: 1 Day



SLR Satellite Visibility Simulation: 22:30 – 22:45



Conclusions and Outlook

Conclusions:

- CubeSats become more and more important
- Constellations with up to 4000 satellites planned; Astrocast: constellation of 40 satellites
- CubeSats can be tracked with SLR using 10 mm prisms
- We hope that the ILRS will help to validate the Astrocast multi-GNSS satellite orbit

Outlook:

- Present mission is only the first step
- Soon dual-frequency COTS GNSS receivers will become available
- **cm-level orbit determination** (post-processing) for any satellite
- Already COTS GNSS Real-Time Kinematic (RTK) receivers are available (e.g. from u-blox)
- mm-level relative positioning between satellites (formation flying, constellations)