Automated Tracking at NGSLR (SLR2000): Nearing the Final Goal

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System Status

• At night able to open-loop (hands-off) track LEO and LAGEOS:

- Point telescope ahead no independent pointing of laser.
- Open receiver field of view to 25 arcsec.
- Signal processing appears to work well.

• Need to close receiver field of view for daylight ranging:

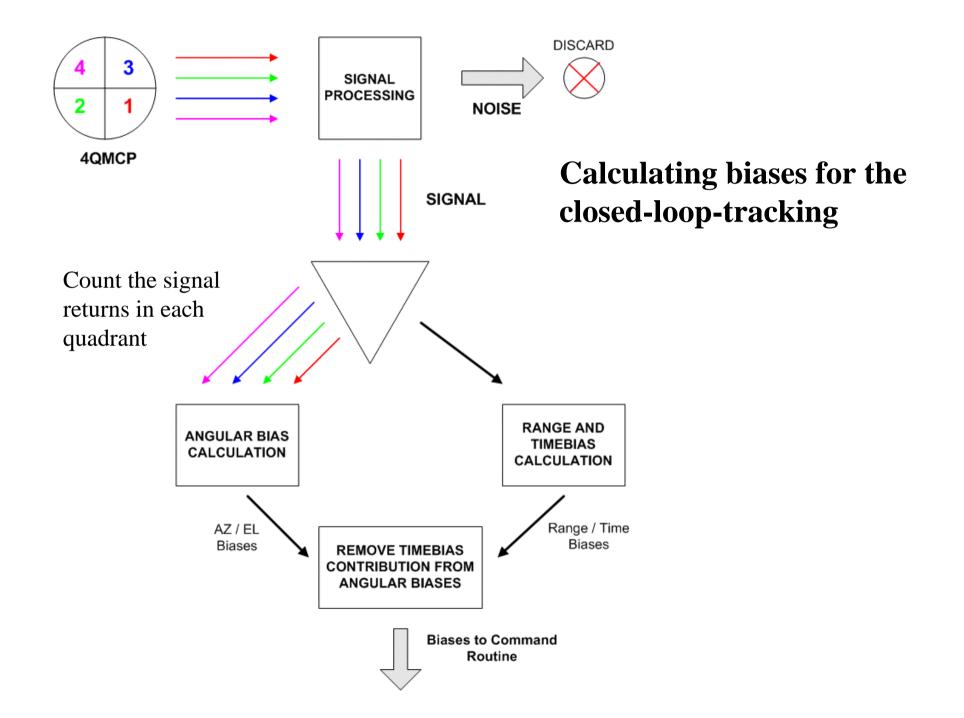
- Point telescope behind and independently pointing laser ahead.
- Risley prisms used to steer laser.
- Have taken multiple passes in this mode with mixed success.
- Re-analysis of system optics reveals alignment and offset issues which are being addressed.

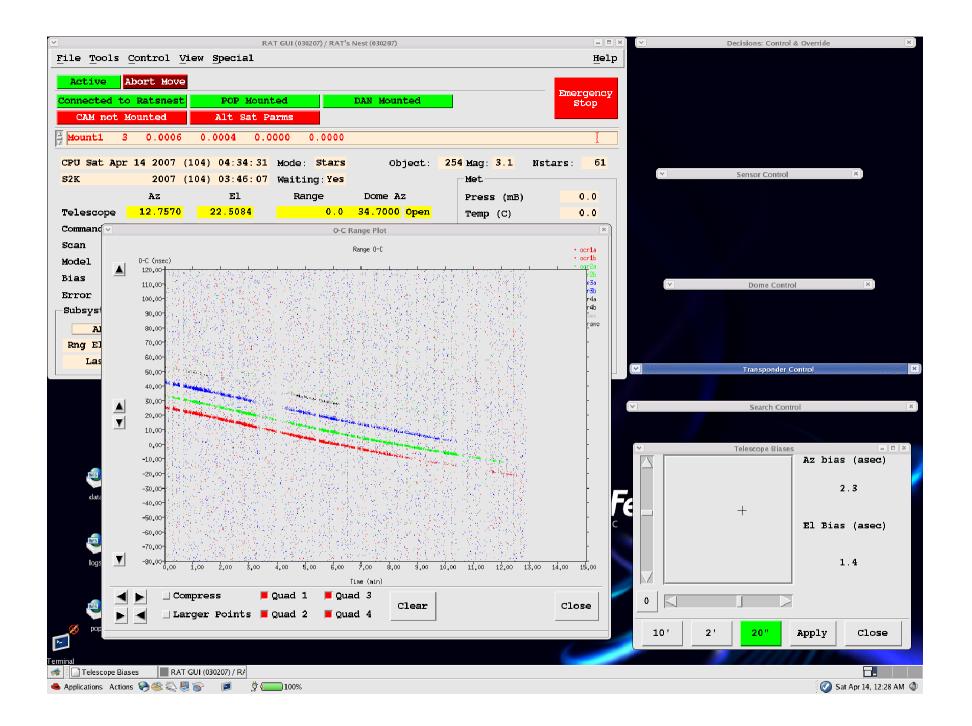
• Final goals for SLR2000 (2008):

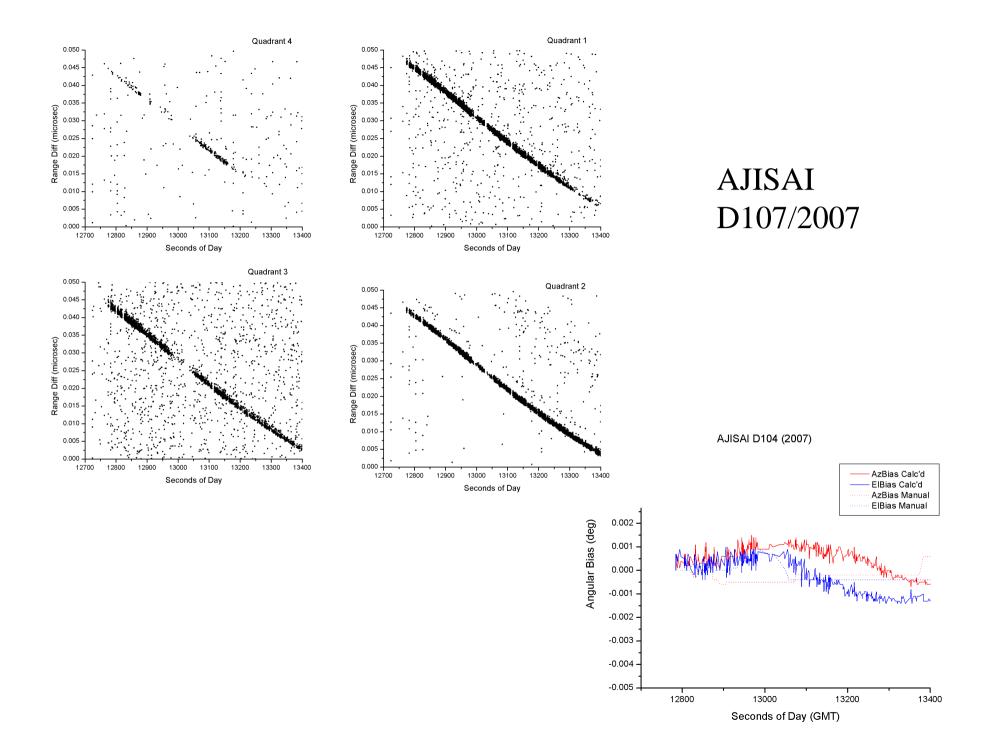
- Get Risley Prisms working correctly.
- Complete automated closed-loop tracking using quadrant detector.

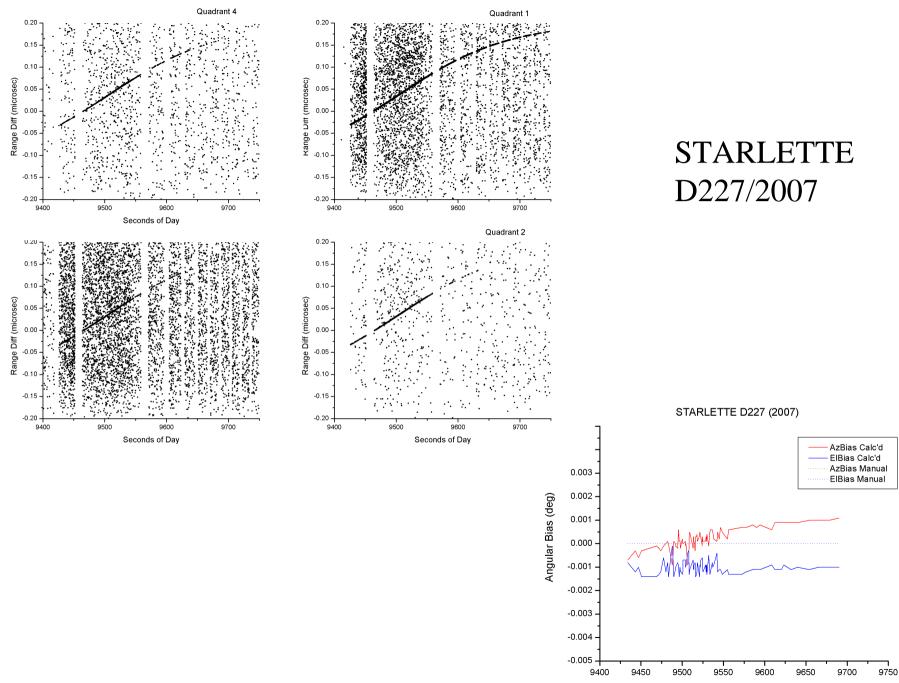
Automation at NGSLR

- Star calibrations are automated:
 - Takes ~ 30-40 minutes to complete. RMS normally ~ 2 arcseconds.
- Satellite scheduling and selection are completely automated.
- Search (for both satellites and stars) is automated.
- Weather information, including visibility (and soon cloud cover) is regularly taken and archived by a background process.
- Decision to stop tracking and move to secondary target based upon cloud cover is newly automated.
- Sun avoidance routine automatically prevents telescope from driving through sun.
- Signal processing provides starting point for automated Normal Point postprocessing.

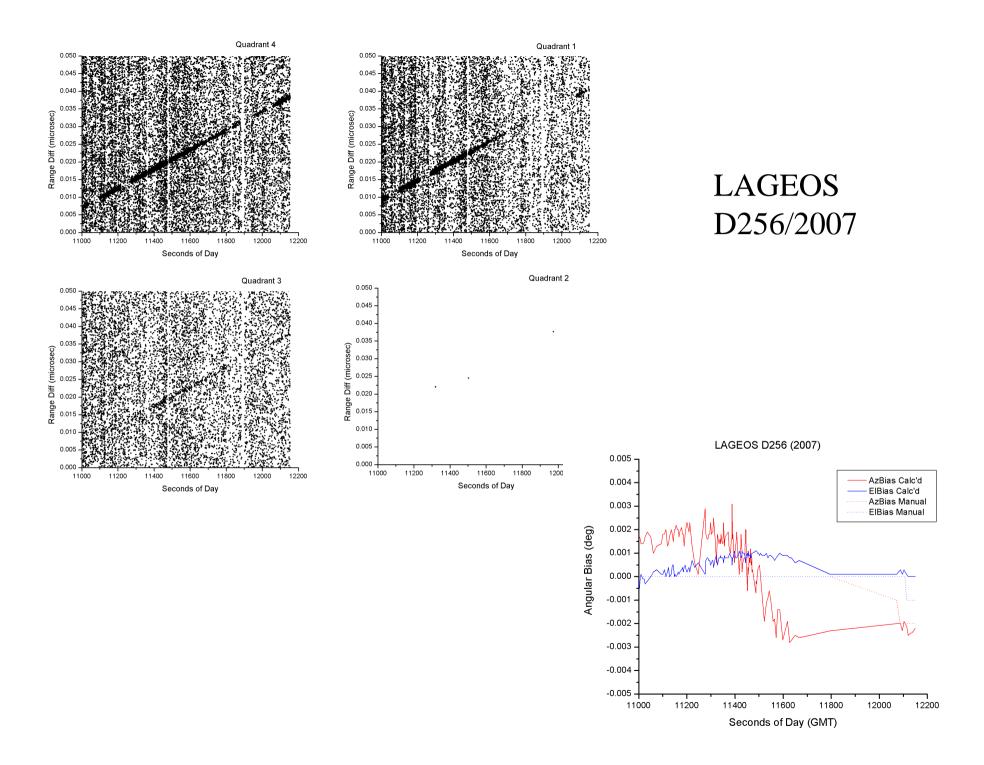








Seconds of Day (GMT)



Last major step to full tracking automation at NGSLR is Closed Loop Tracking.

➤ Must be completed before LRO-LR launch (Oct 2008)